

3. Optimization problem based on an undefined Petri net

Outline

Statement of the problem

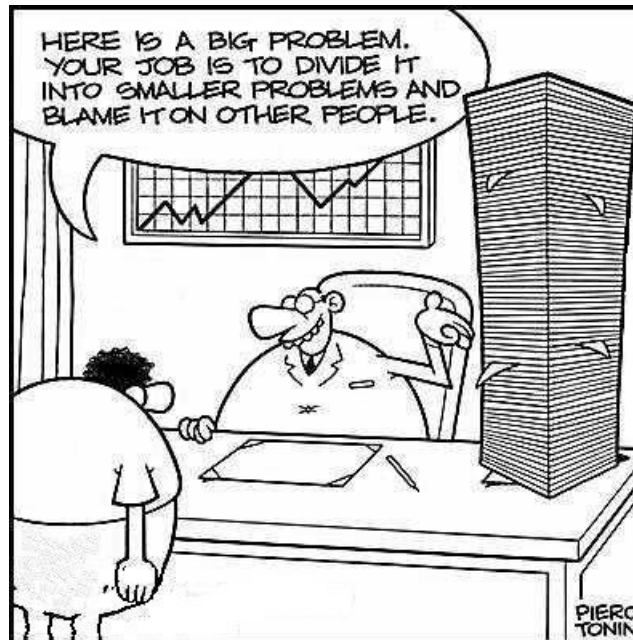
- Max/min objective/multiobjective function } Quality measurement of a solution
- Definition of the structure of the feasible solutions.
- Constraints → configuration of the solution space.
- Undefined Petri net:
 1. Disjunctive constraint: only one simple alternative PN must be verified.
 2. It is a complement to the objective function.

3. Optimization problem based on an undefined Petri net

Classical solution

Decomposition of the problem in n different cases based on a simple alternative Petri net.

The proposed methodology allows to transform a compound PN into a set of simple alternative PN



3. Optimization problem based on an undefined Petri net

Classical solution

Decomposition of the problem in n different cases based on a simple alternative Petri net

The disjunctive constraint is avoided.

It requires the solution of n optimization problems.

It requires a further stage of comparing the results.

If n is large...



...selection.

3. Optimization problem based on an undefined Petri net

Proposed methodology

Alternatives aggregation Petri nets

Transformation of an undefined PN into an AAPN.

Efficient exploration of a single solution space.

Solution of the problem by means of classical methodologies (state explosion).

Heuristics / metaheuristics

3. Optimization problem based on an undefined Petri net

Alternatives aggregation Petri nets

Construction of an AAPN

Decomposition of a set of alternative Petri nets in:

Subnets

Link transitions

Aggregation and link of the subnets.

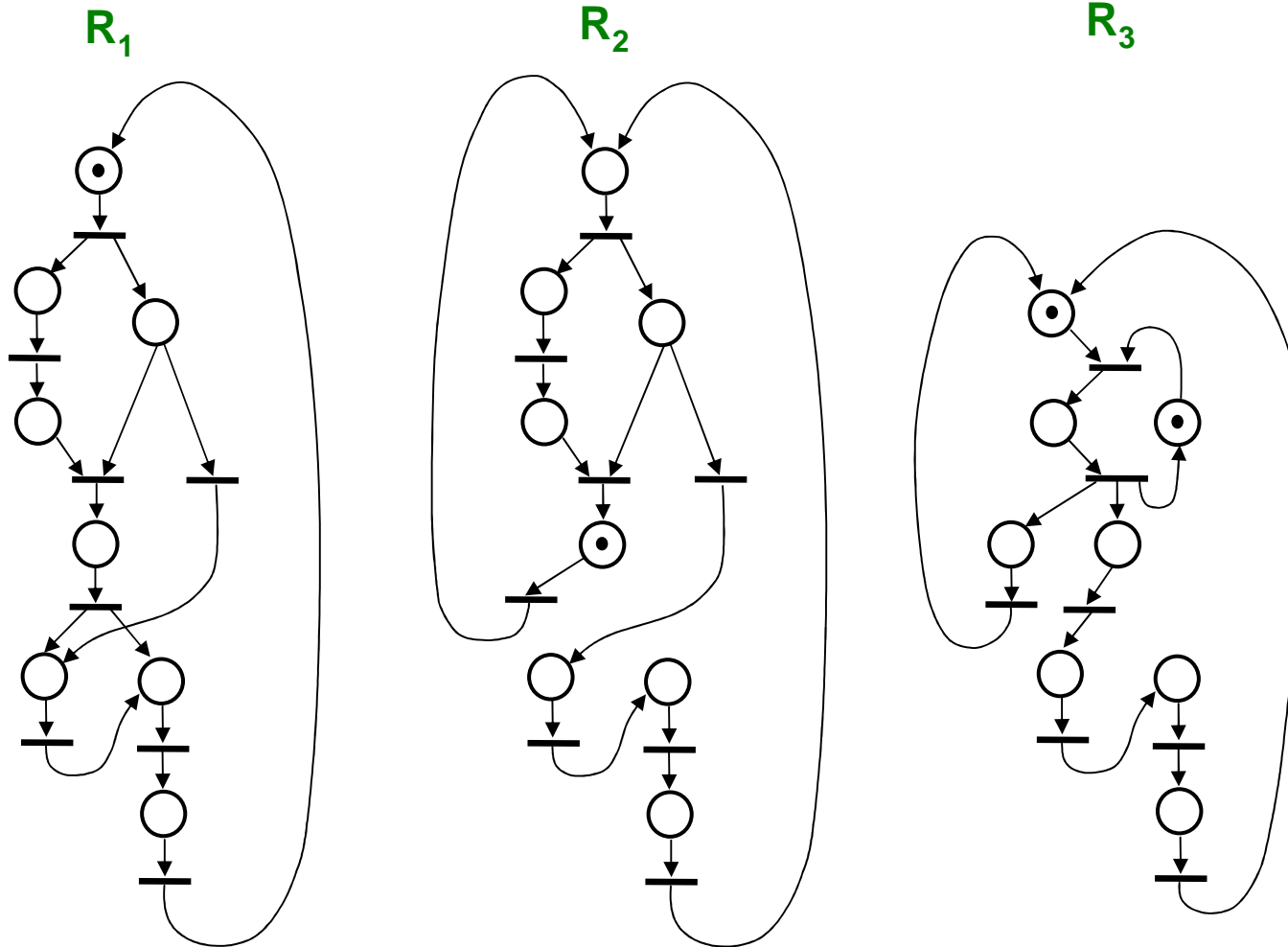
Application of the reduction rules.

Application of the simplification rules.

3. Optimization problem based on an undefined Petri net

Example 4

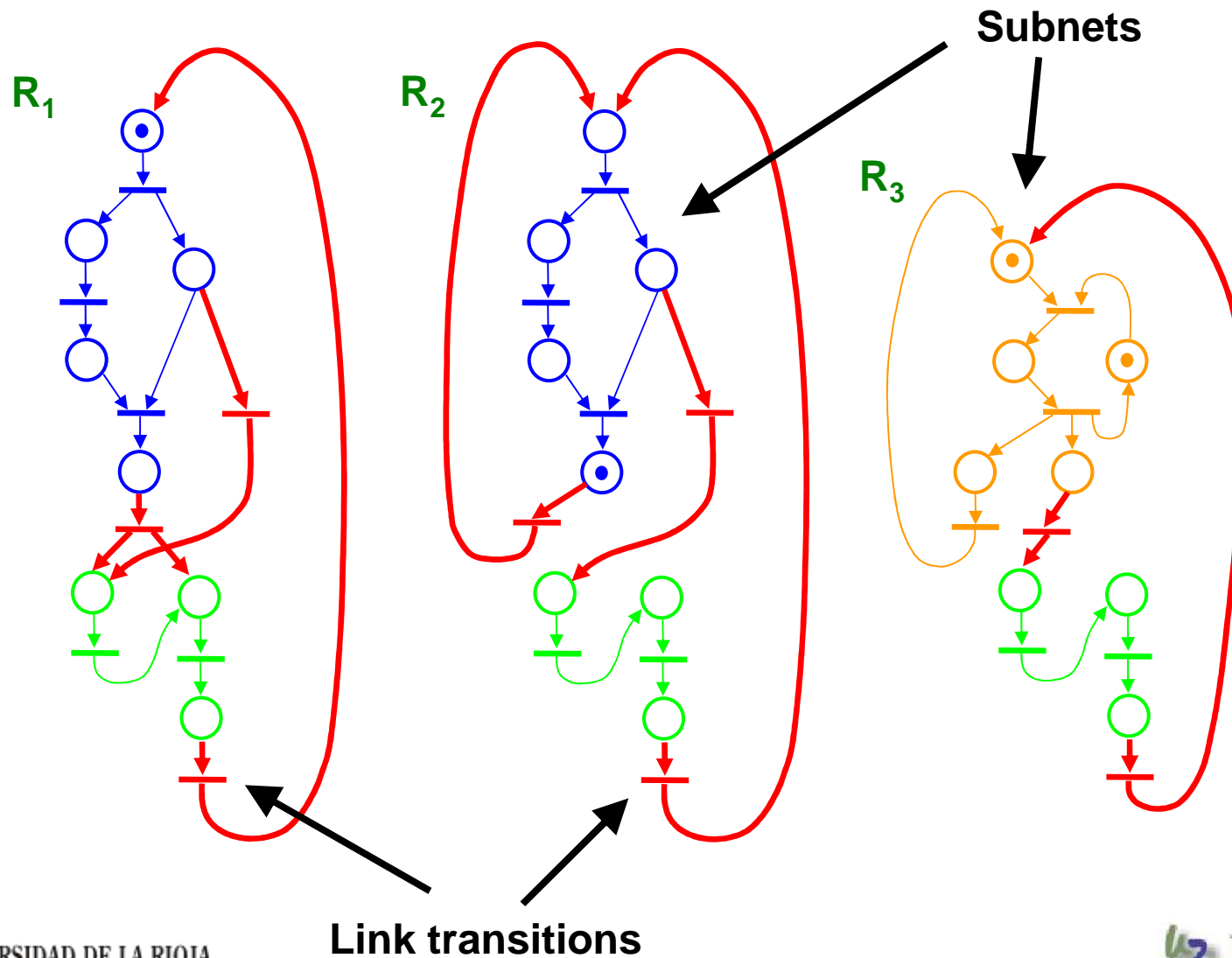
Alternatives aggregation Petri nets



3. Optimization problem based on an undefined Petri net

Example 4

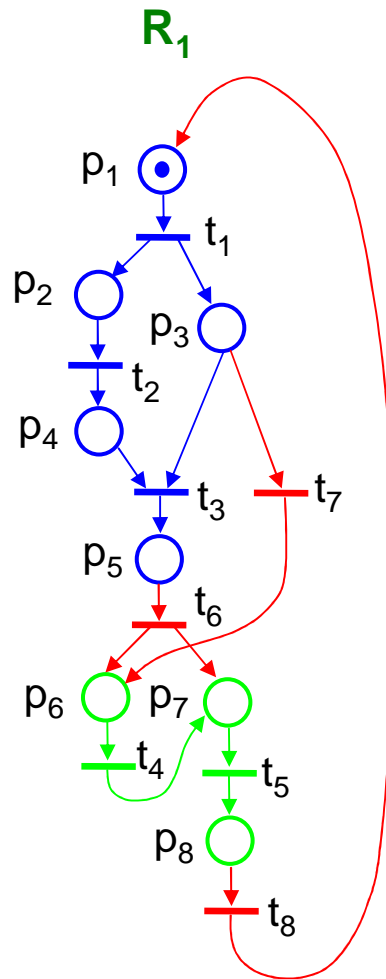
1. Decomposition into subnets



3. Optimization problem based on an undefined Petri net

Example 4

1. Decomposition into subnets



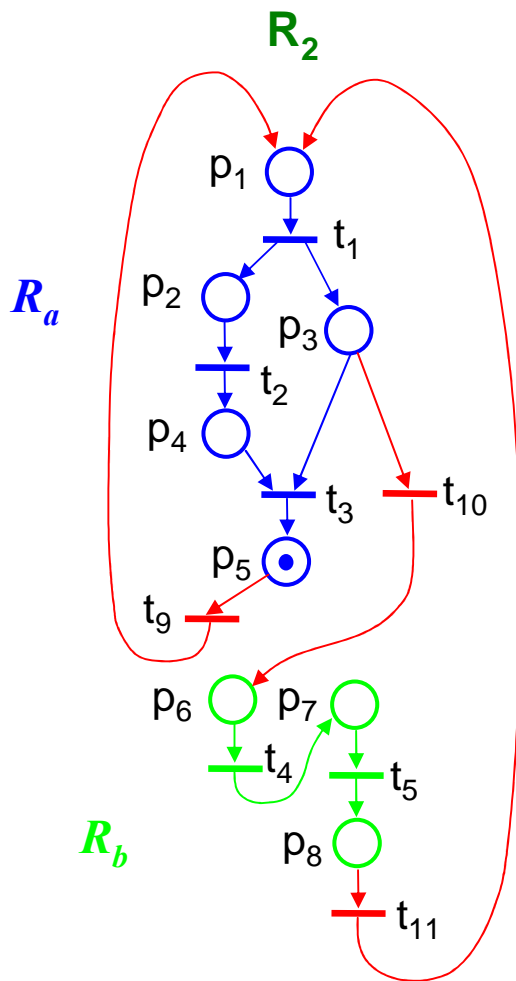
Incidence matrix

$$W_1 = \begin{matrix} & \begin{matrix} t_1 & t_2 & t_3 & t_4 & t_5 & t_6 & t_7 & t_8 \end{matrix} \\ \begin{matrix} Q_a \\ \hline \\ \\ \\ \\ \\ \\ \\ \\ Q_b \end{matrix} & \begin{pmatrix} -1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & -1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \end{pmatrix} & \begin{matrix} p_1 \\ p_2 \\ p_3 \\ p_4 \\ p_5 \\ p_6 \\ p_7 \\ p_8 \end{matrix} \end{matrix}$$

3. Optimization problem based on an undefined Petri net

Example 4

1. Decomposition into subnets



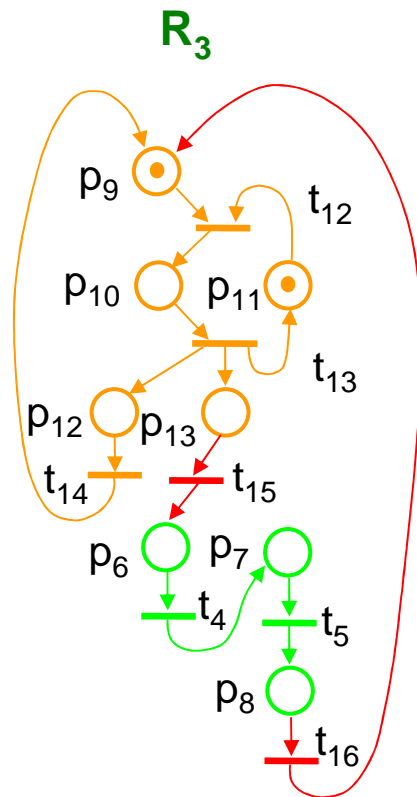
Incidence matrix

$$W_2 = \begin{matrix} & \begin{matrix} t1 & t2 & t3 & t4 & t5 & t9 & t10 & t11 \end{matrix} \\ \begin{matrix} Q_a \\ Q_b \end{matrix} & \begin{pmatrix} -1 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & -1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \end{pmatrix} \\ & \begin{matrix} p1 \\ p2 \\ p3 \\ p4 \\ p5 \\ p6 \\ p7 \\ p8 \end{matrix} \end{matrix}$$

3. Optimization problem based on an undefined Petri net

Example 4

1. Decomposition into subnets



Incidence matrix

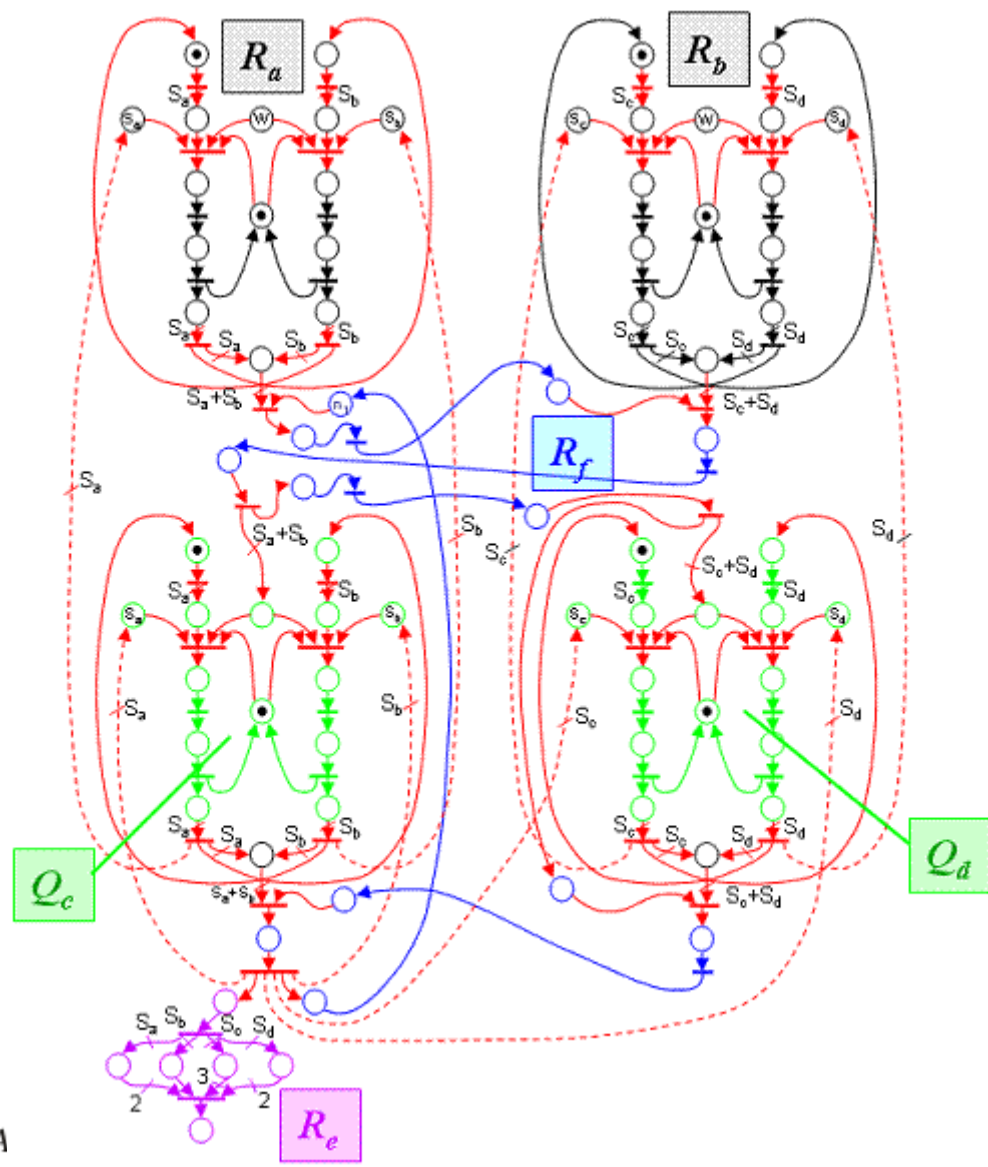
$$W_3 =$$

	t4	t5	t12	t13	t14	t15	t16	
	-1	0	0	0	0	1	0	p1
	1	-1	0	0	0	0	0	p2
	0	1	0	0	0	0	1	p3
	0	0	-1	0	1	0	-1	p4
	0	0	1	-1	0	0	0	p5
	0	0	-1	1	0	0	0	p6
	0	0	0	1	-1	0	0	p7
	0	0	0	1	0	-1	0	p8
	Subnet R_a		Subnet R_1^3			Link transitions t_{15}, t_{16}		

3. Optimization problem based on an undefined Petri net

Example 2

1. Decomposition into subnets



R^c_1

Manufacturing strategy pull.

1 route of AGV.

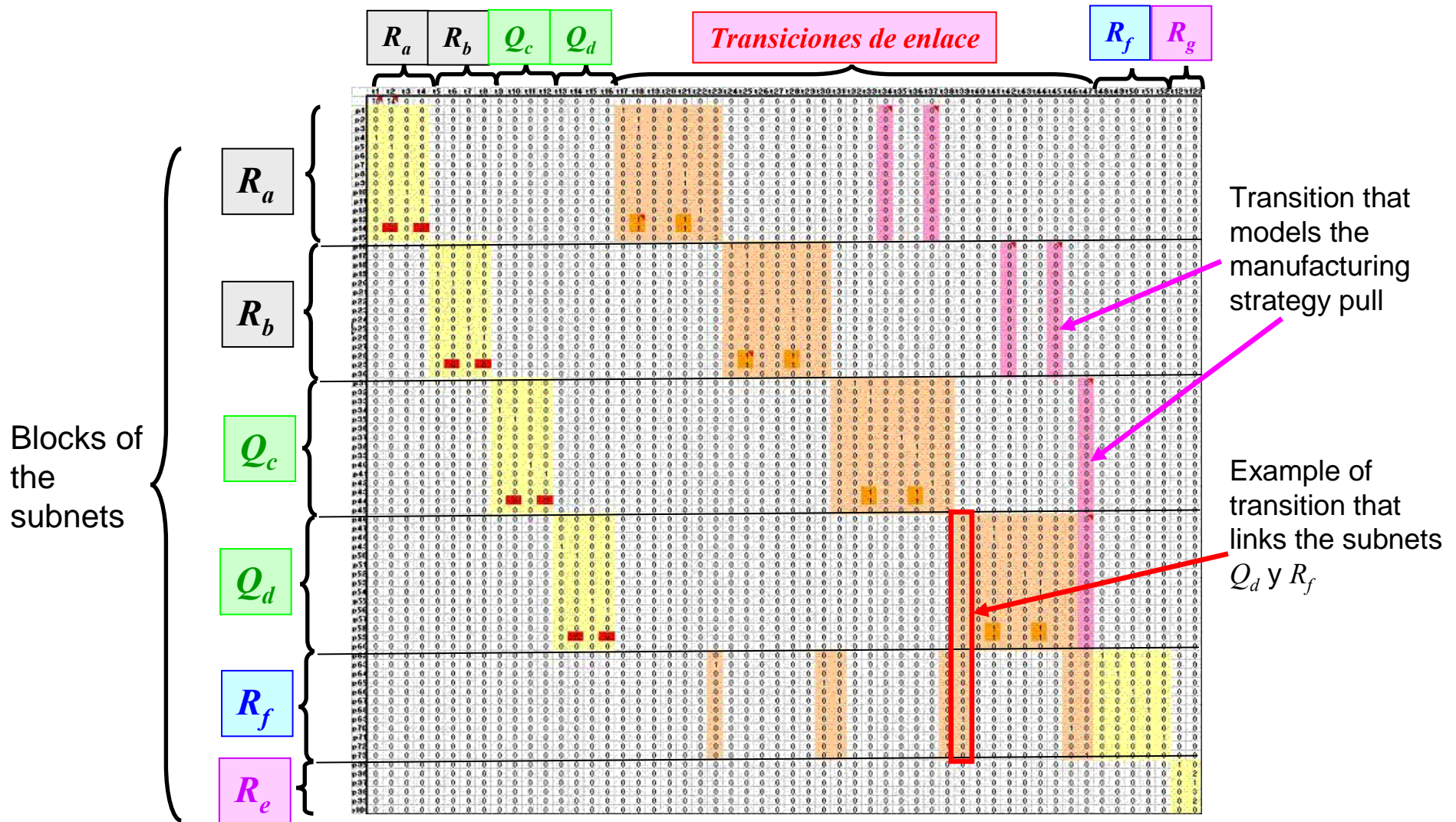
Undefined structural parameters

Lot sizes.

3. Optimization problem based on an undefined Petri net

Example 2

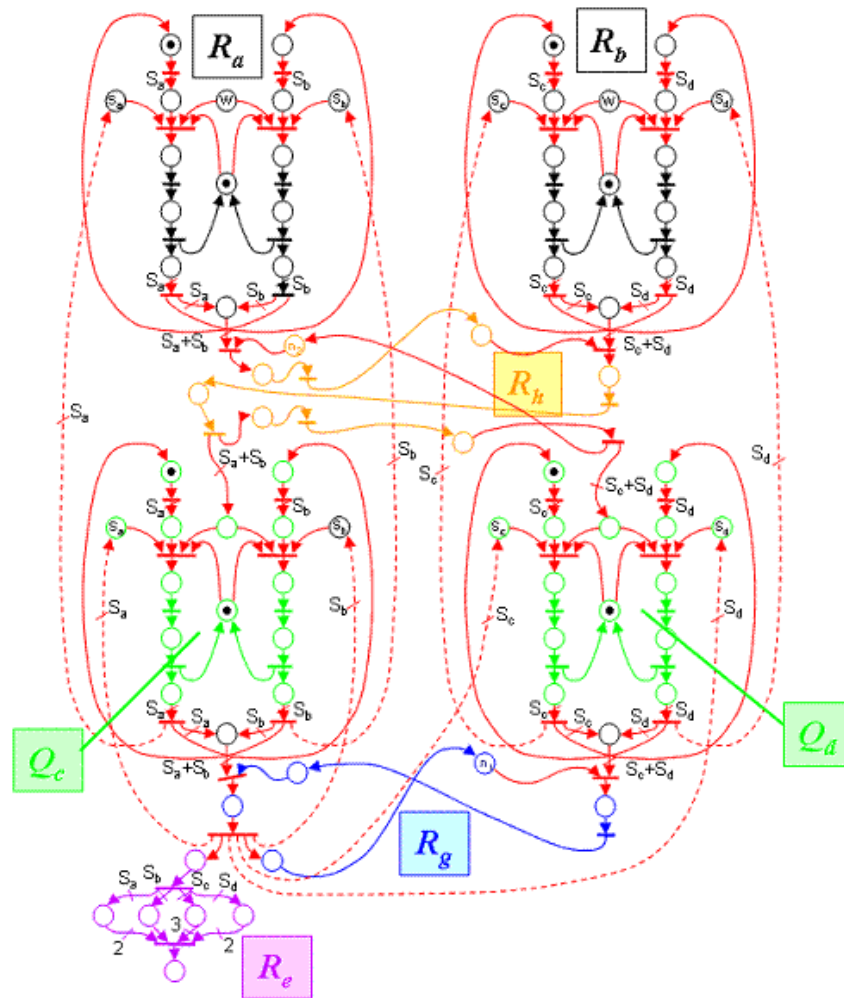
1. Decomposition into subnets



3. Optimization problem based on an undefined Petri net

Example 2

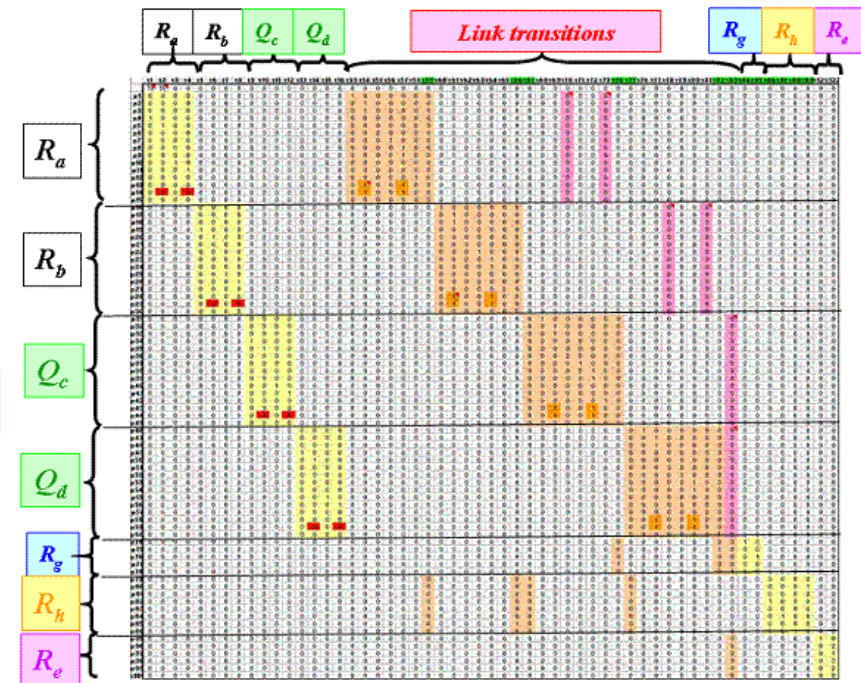
1. Decomposition into subnets



R^c_2

Manufacturing strategy pull.

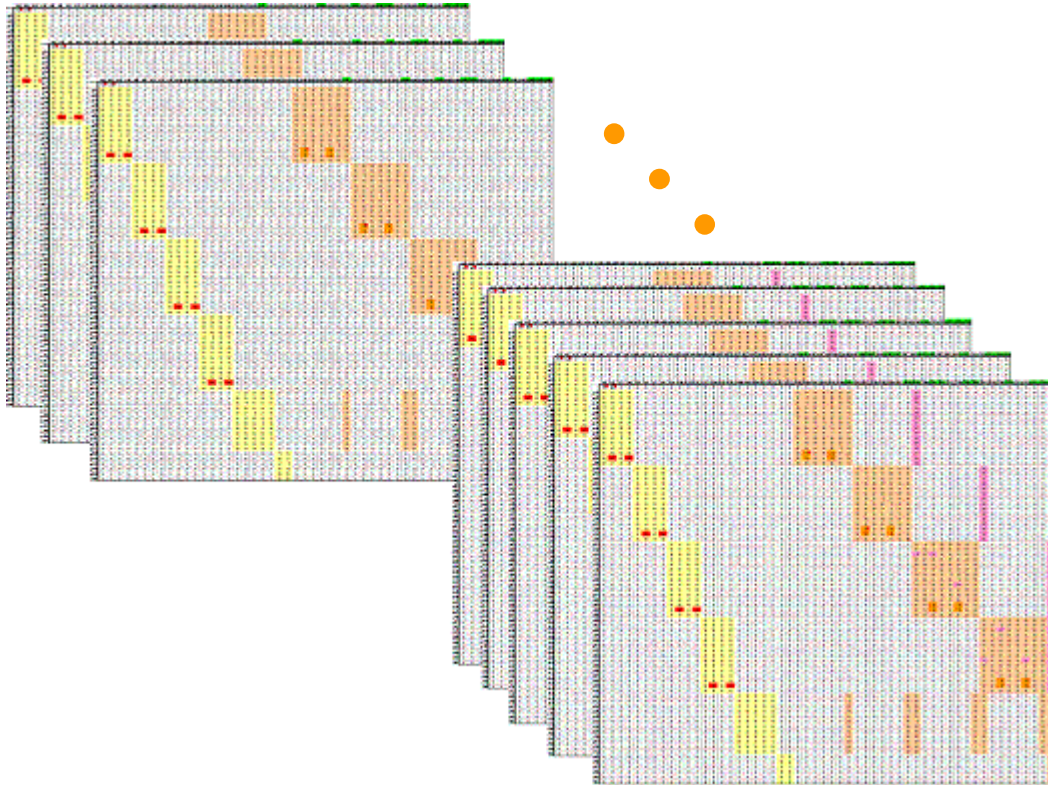
2 routes of AGV.



3. Optimization problem based on an undefined Petri net

Example 2

1. Decomposition into subnets



Incidence matrices

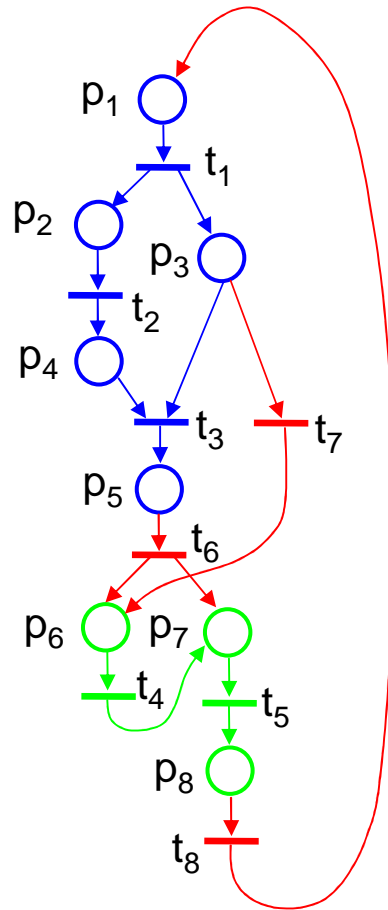
24 compound alternative PN.

Size of each matrix $\approx 78 \times 54$.

3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets



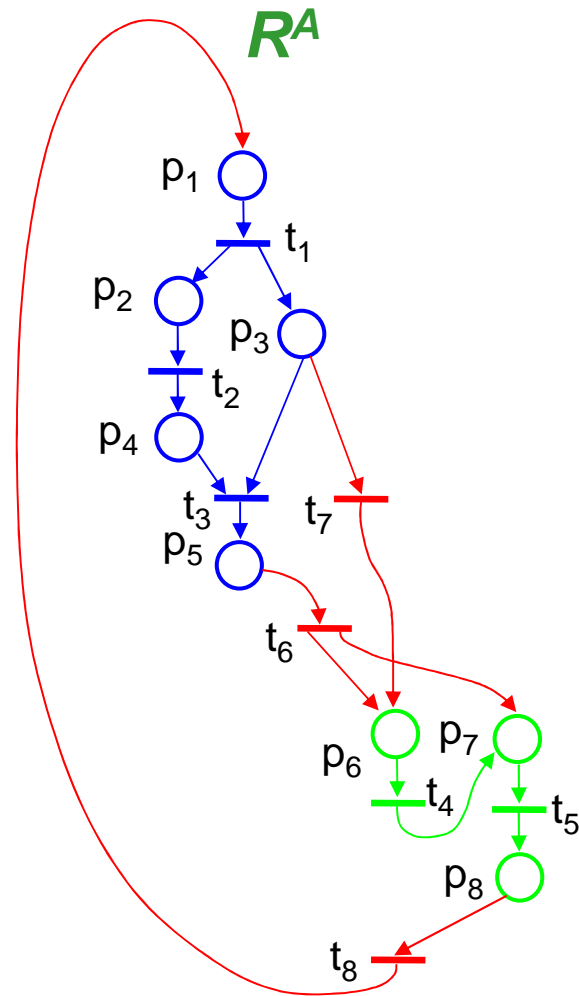
R_1

$$W_1 = \begin{matrix} & \begin{matrix} t1 & t2 & t3 & t4 & t5 & t6 & t7 & t8 \end{matrix} \\ \begin{pmatrix} -1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & -1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \end{pmatrix} & \begin{matrix} p1 \\ p2 \\ p3 \\ p4 \\ p5 \\ p6 \\ p7 \\ p8 \end{matrix} \end{matrix}$$

3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets



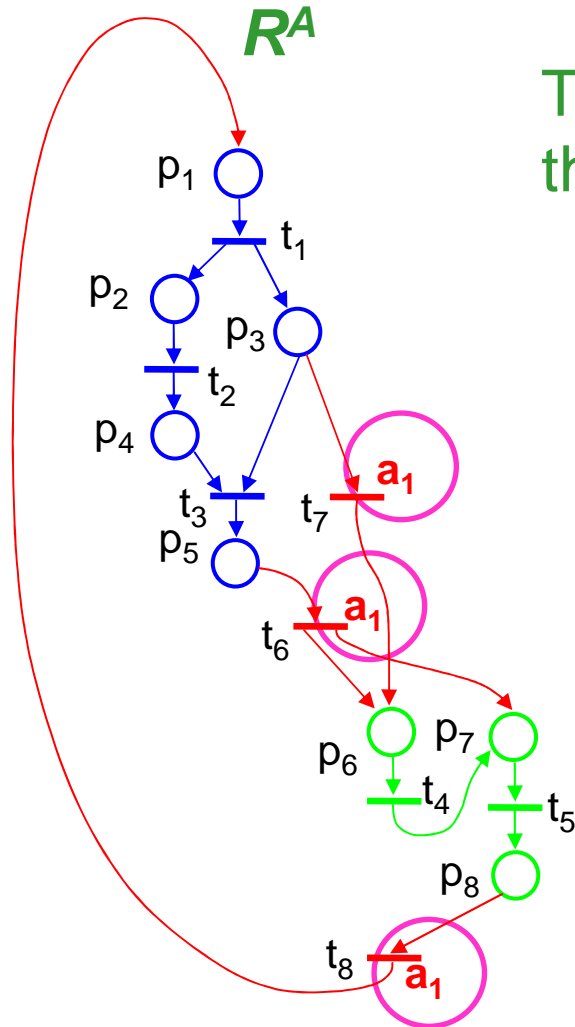
Step 1. Aggregation of R_1

$$W^A = \begin{matrix} & \begin{matrix} t1 & t2 & t3 & t4 & t5 & t6 & t7 & t8 \end{matrix} \\ \begin{pmatrix} -1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & -1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \end{pmatrix} & \begin{matrix} p1 \\ p2 \\ p3 \\ p4 \\ p5 \\ p6 \\ p7 \\ p8 \end{matrix} \end{matrix}$$

3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets



The choice variable a_1 is associated to the link transitions of R_1 .

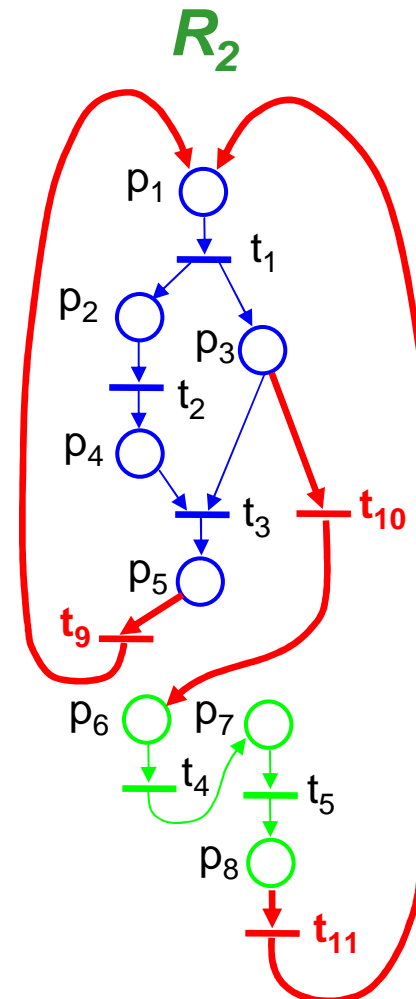
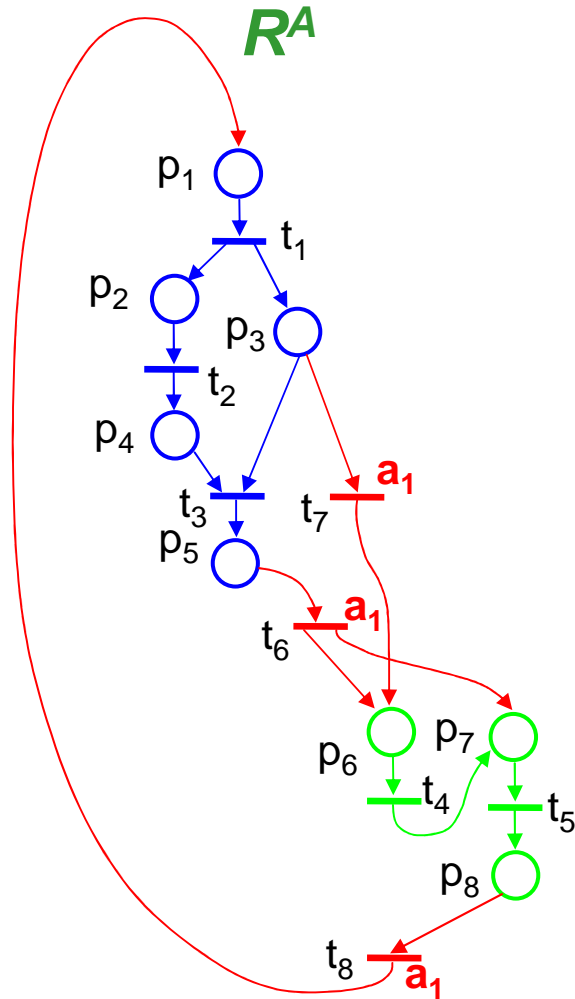
$$W^A = \begin{matrix} & \begin{matrix} t1 & t2 & t3 & t4 & t5 & t6 & t7 & t8 \end{matrix} \\ \begin{pmatrix} -1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & -1 & 0 & 0 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \end{pmatrix} & \begin{matrix} p1 \\ p2 \\ p3 \\ p4 \\ p5 \\ p6 \\ p7 \\ p8 \end{matrix} \end{matrix}$$

$\underbrace{\hspace{10em}}_{a_1}$

3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets



It does not provide with new subnets.

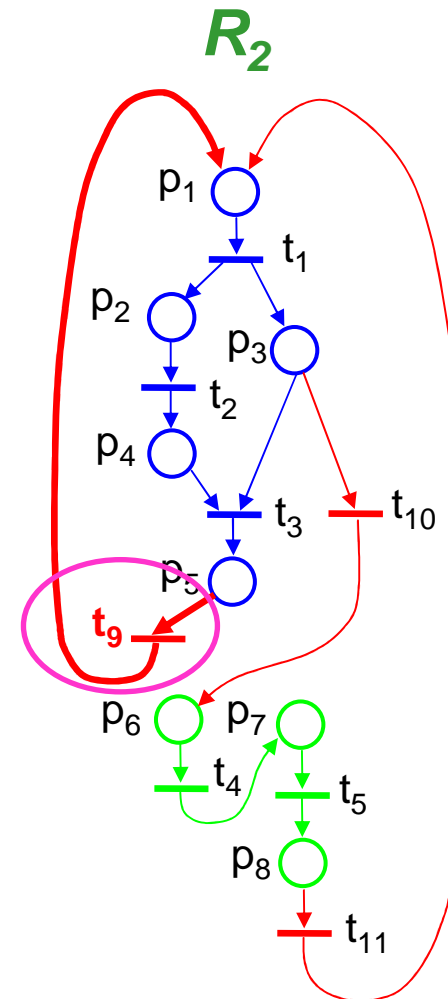
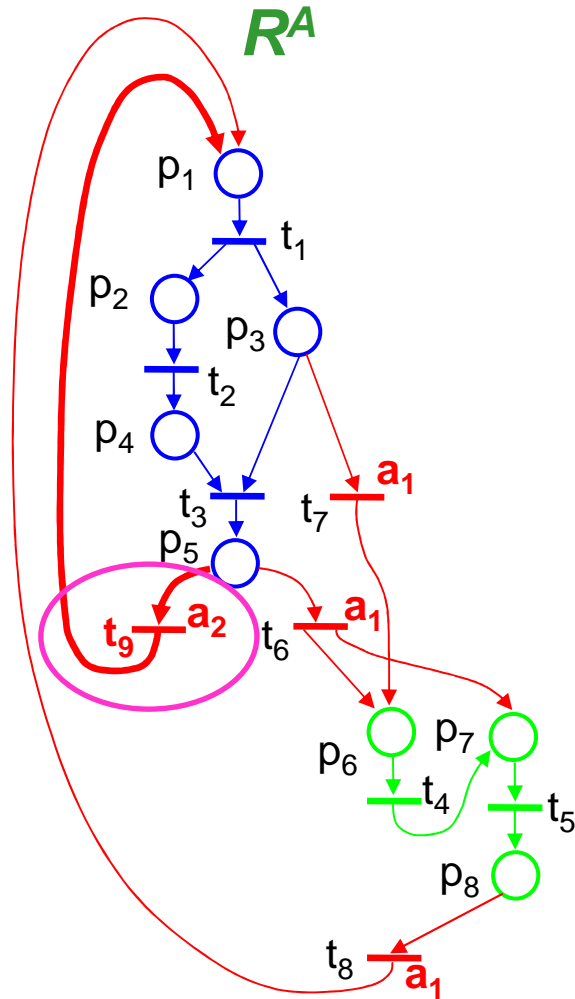
It has three link transitions.

t_9, t_{10}, t_{11} .

3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets



R_2

It does not provide with new subnets.

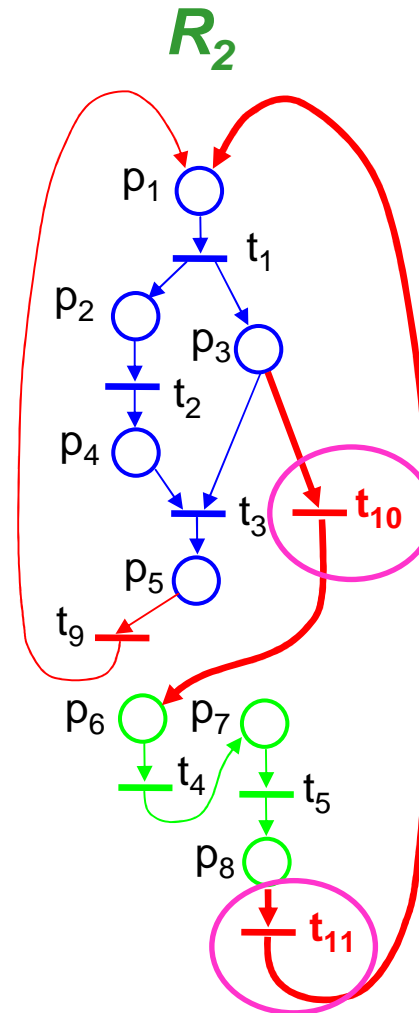
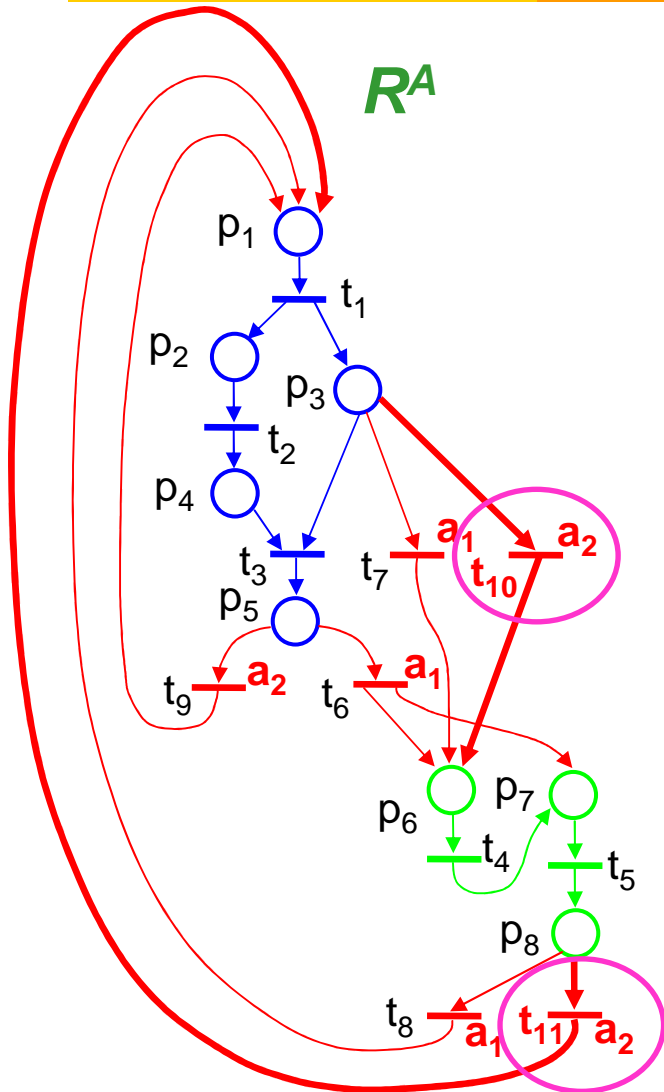
It has three link transitions.

t_9, t_{10}, t_{11} .

3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets



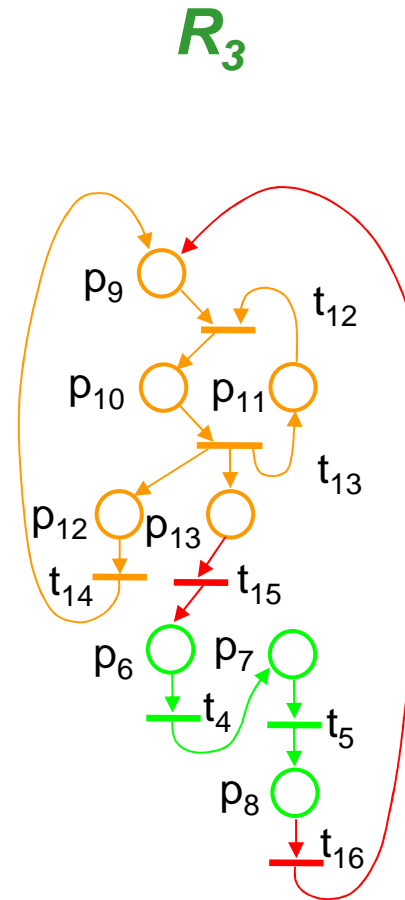
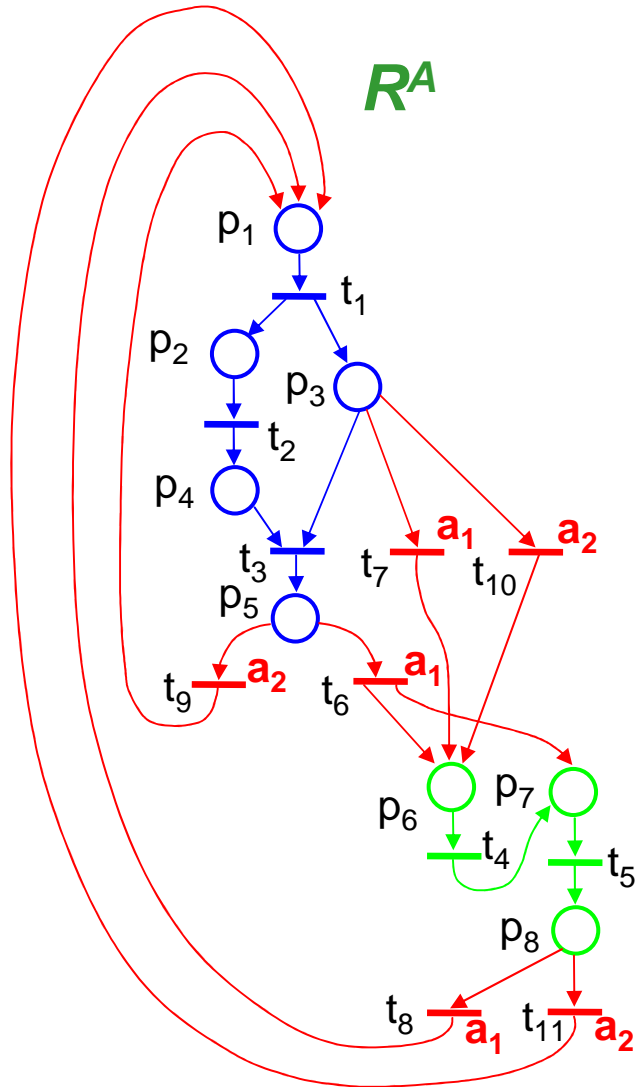
It does not provide with new subnets.
It has three link transitions.

t_9, t_{10}, t_{11} .

3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets



R_3

It provides with a new subnet.

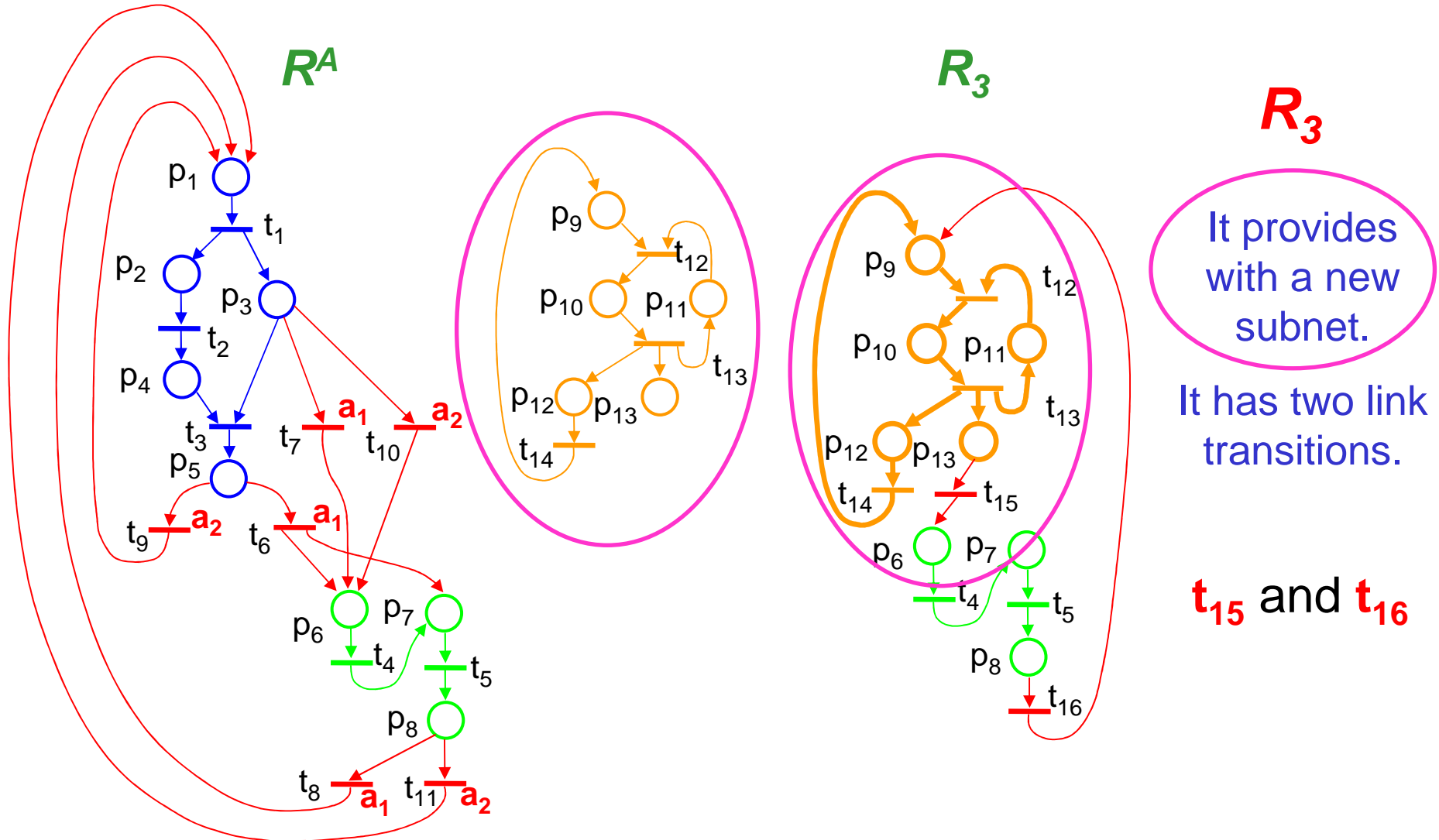
It has two link transitions.

t_{15} and t_{16}

3. Optimization problem based on an undefined Petri net

Example 4

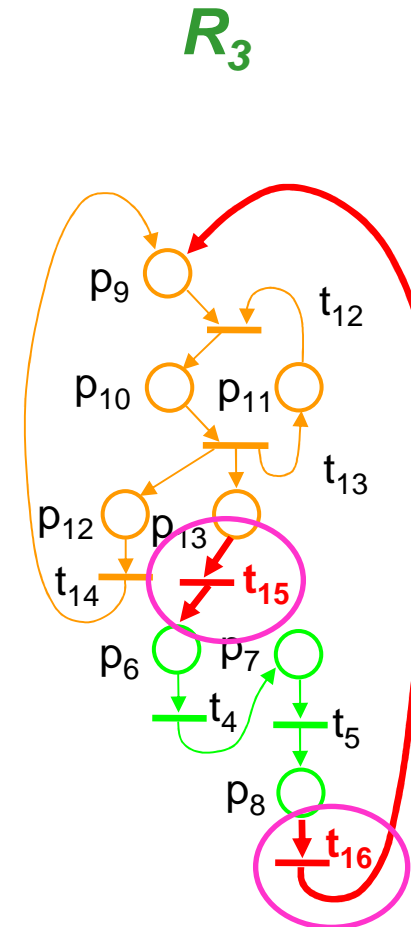
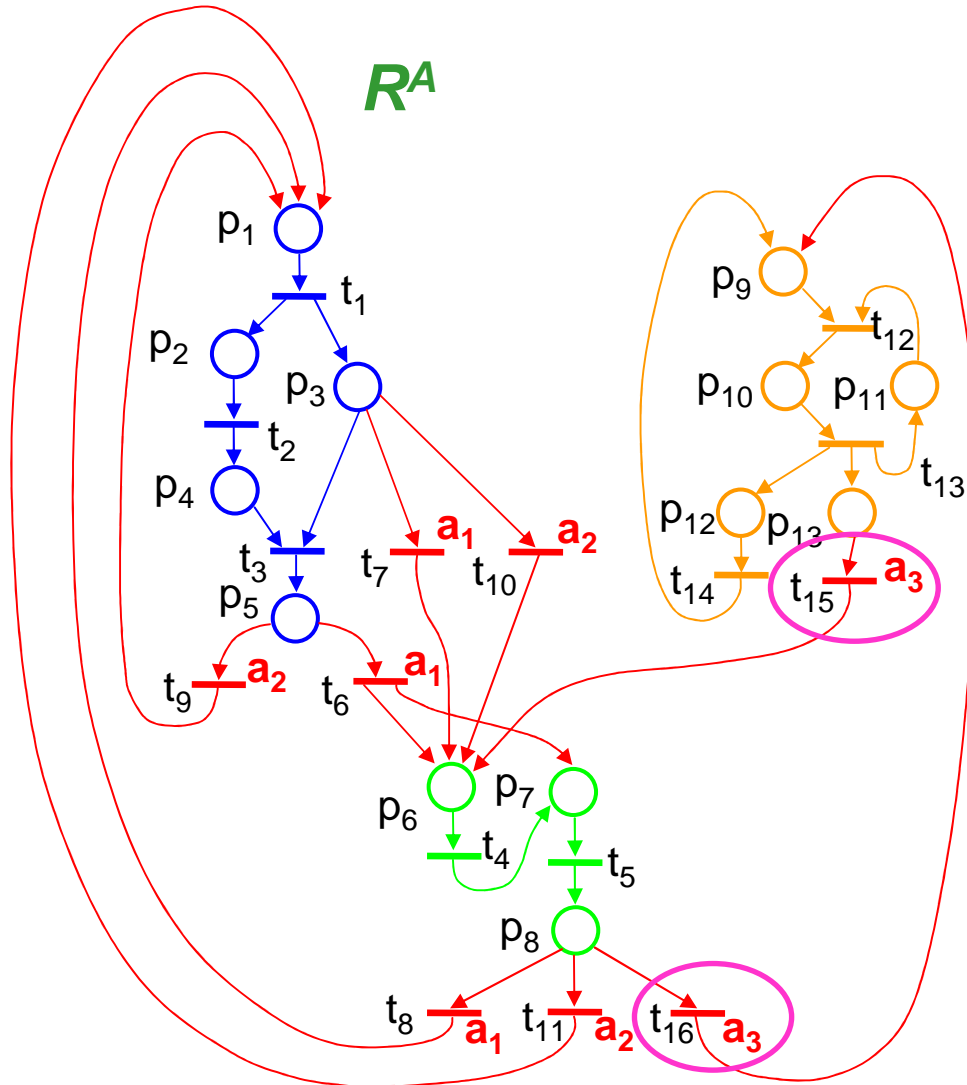
2. Aggregation of subnets



3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets



R_3

It provides with a new subnet.

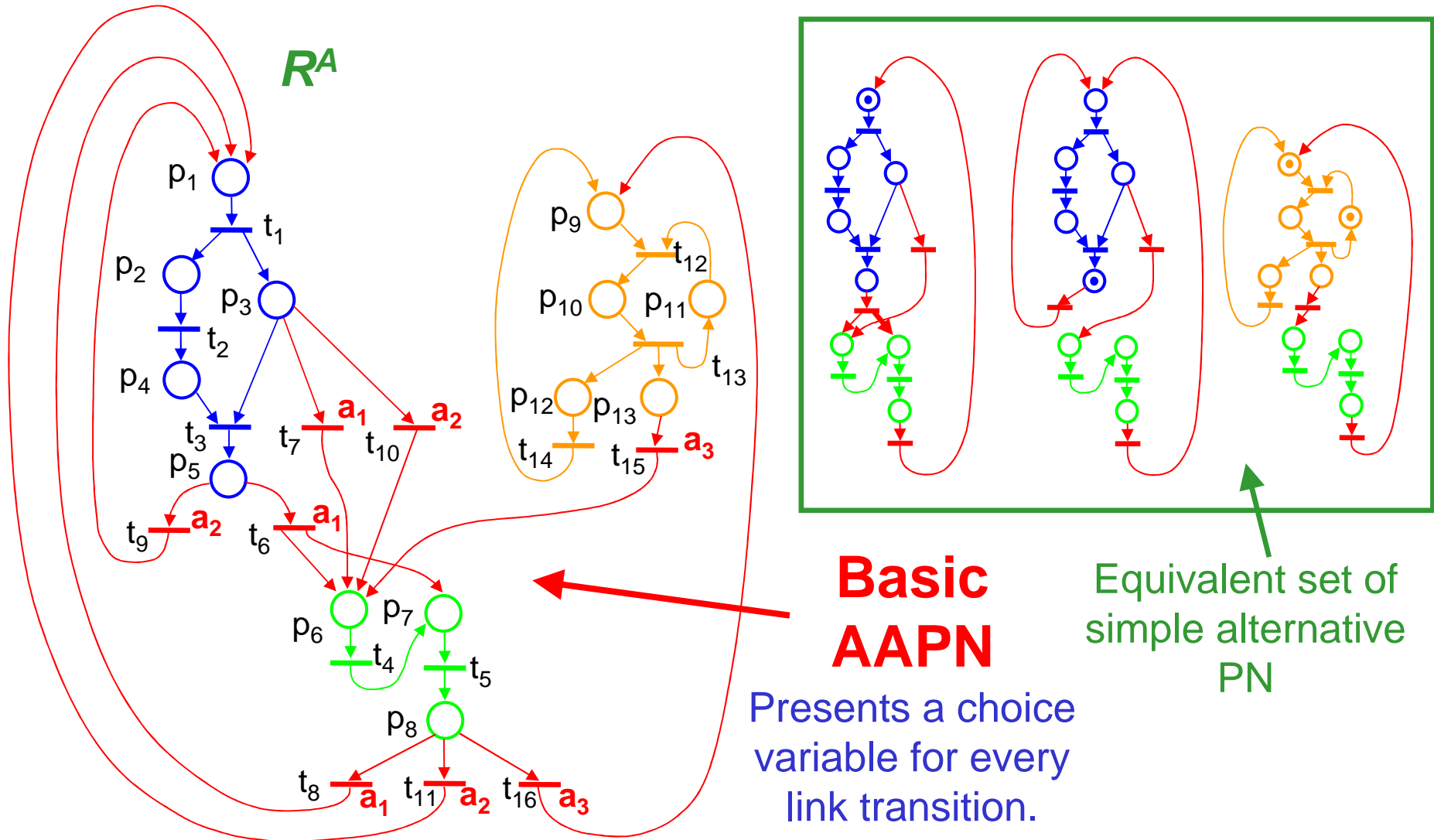
It has two link transitions.

t_{15} and t_{16}

3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets

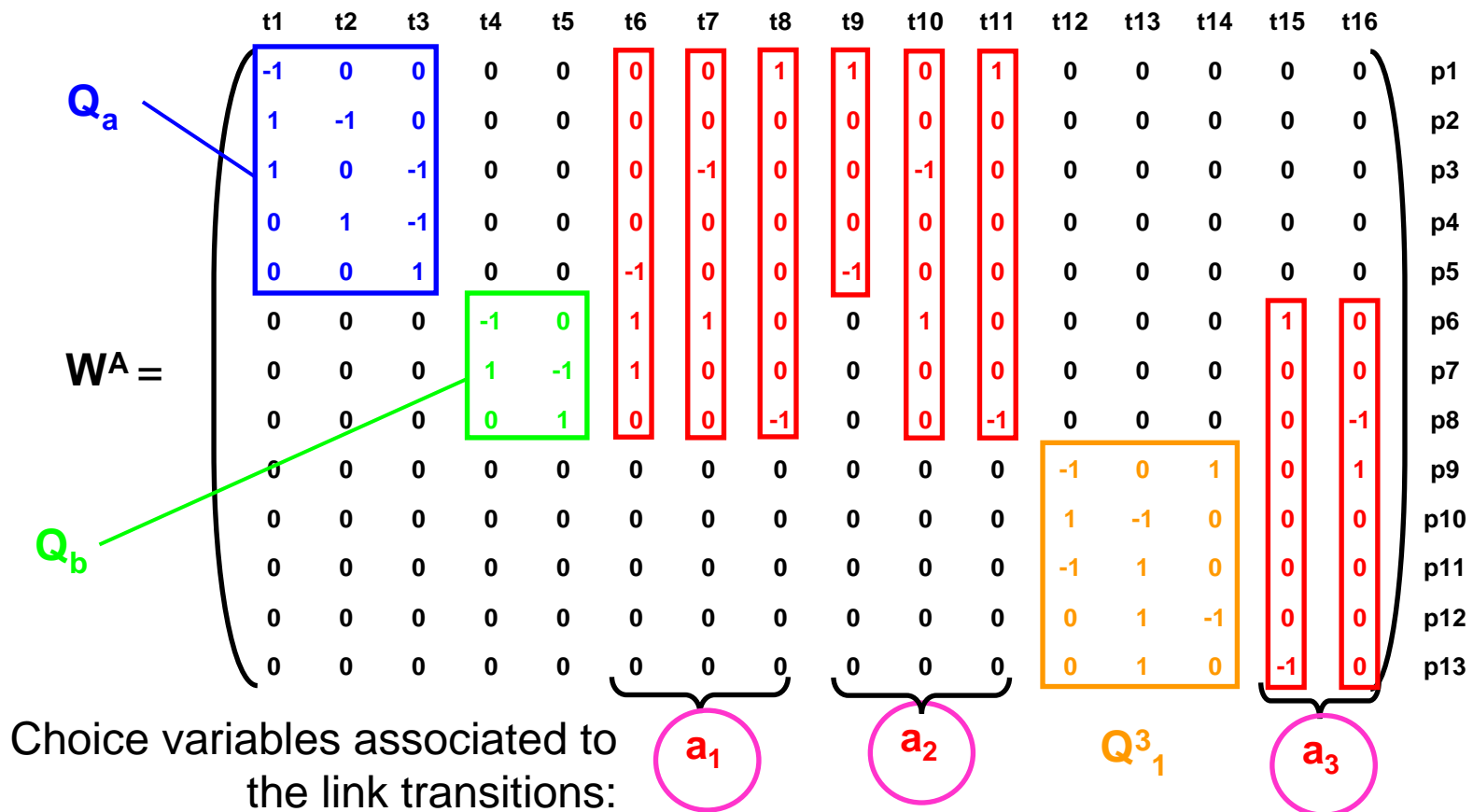


3. Optimization problem based on an undefined Petri net

Example 4

2. Aggregation of subnets

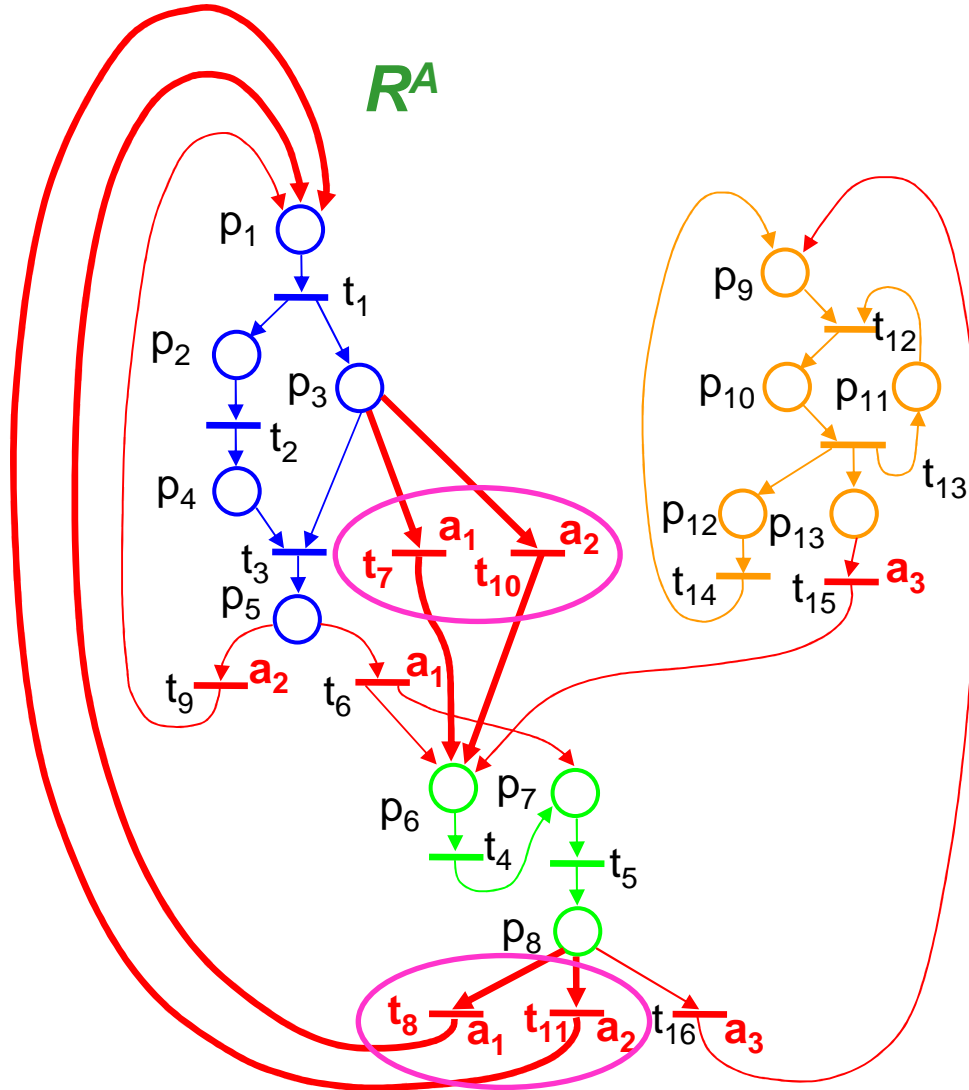
Incidence matrix of the AAPN



3. Optimization problem based on an undefined Petri net

Example 4

3. Reduction of the link transitions



Application of the reduction rule

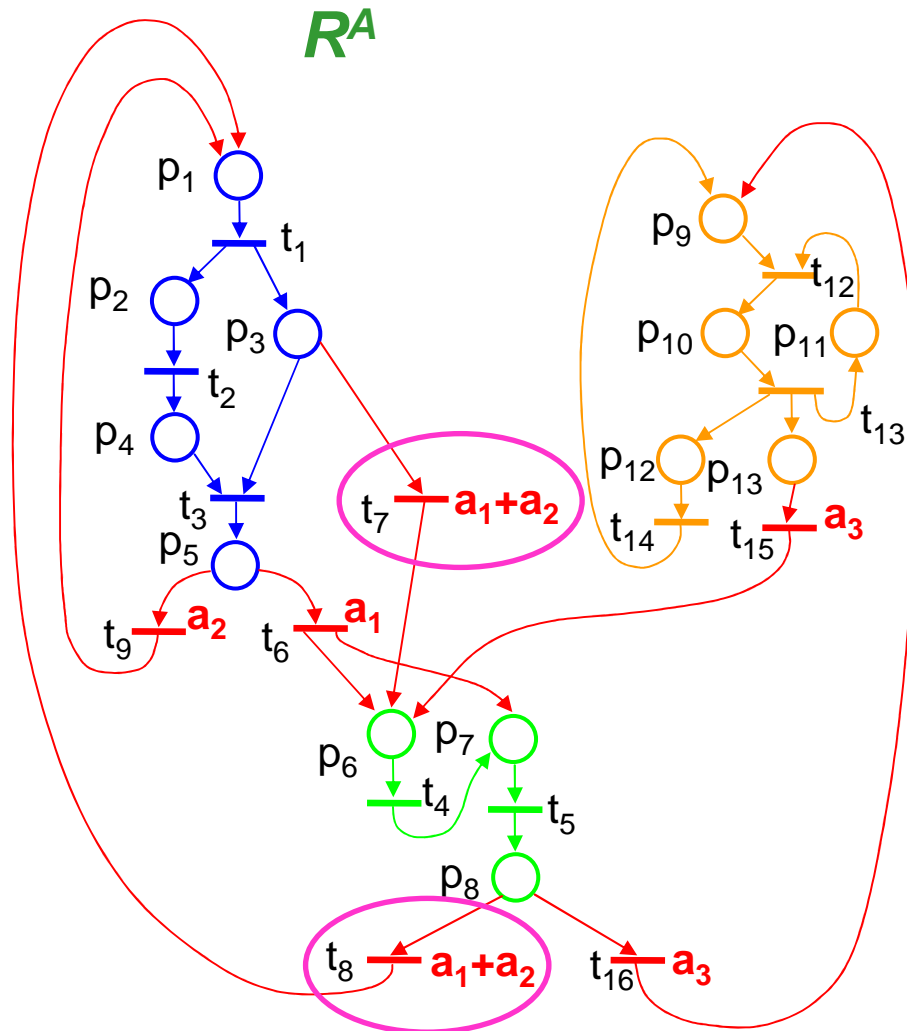
$\{t_7, t_{10}\}$ reduced to t_7 by associating the next function of choice variables $f_7 = a_1 + a_2$

$\{t_8, t_{11}\}$ reduced to t_8 by associating the next function of choice variables $f_8 = a_1 + a_2$

3. Optimization problem based on an undefined Petri net

Example 4

3. Reduction of the link transitions



Application of the reduction rule

$\{t_7, t_{10}\}$ reduced to t_7 by associating the next function of choice variables $f_7 = a_1 + a_2$

$\{t_8, t_{11}\}$ reduced to t_8 by associating the next function of choice variables $f_8 = a_1 + a_2$

The incidence matrices are reduced proportionally.

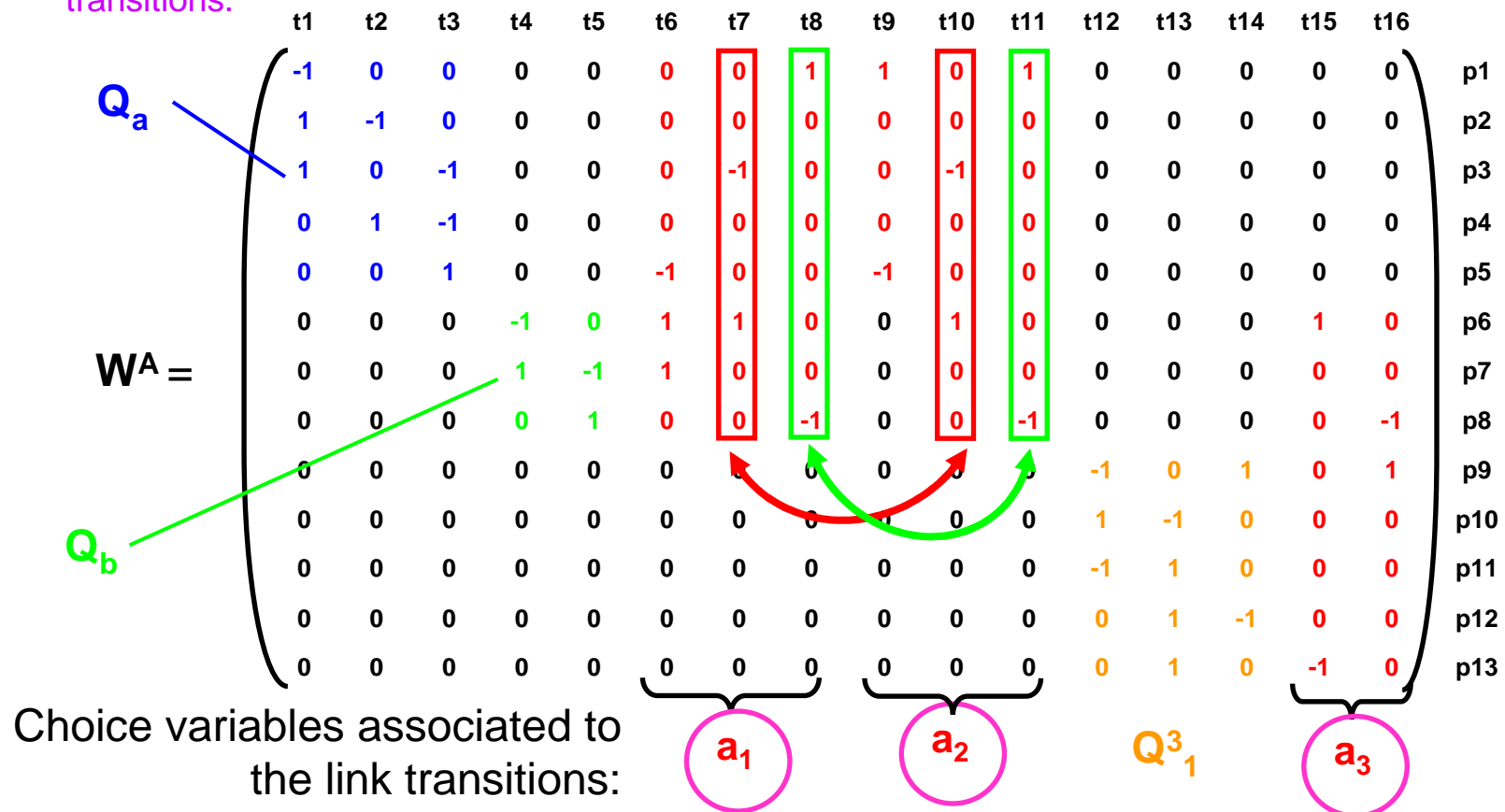
3. Optimization problem based on an undefined Petri net

Example 4

3. Reduction of the link transitions

In the incidence matrix of the AAPN there exist several identical columns:

- 1) Every identical columns can be reduced to a single one.
- 2) A function of choice variables is associated to the column which is equivalent to the reduced transitions.



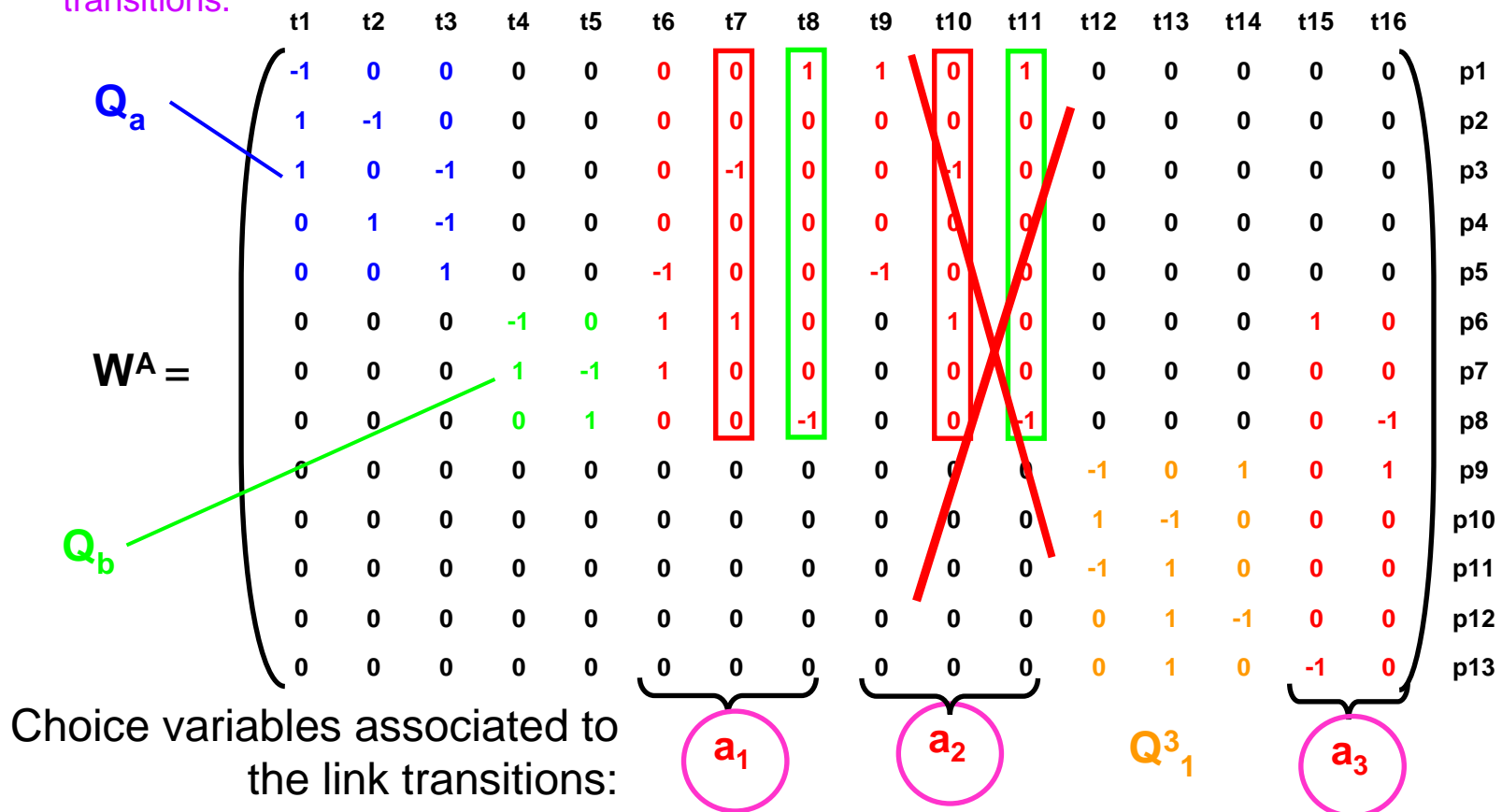
3. Problema de 3. Optimization problem based on an undefined Petri net basado en una RdP indefinida

Example 4

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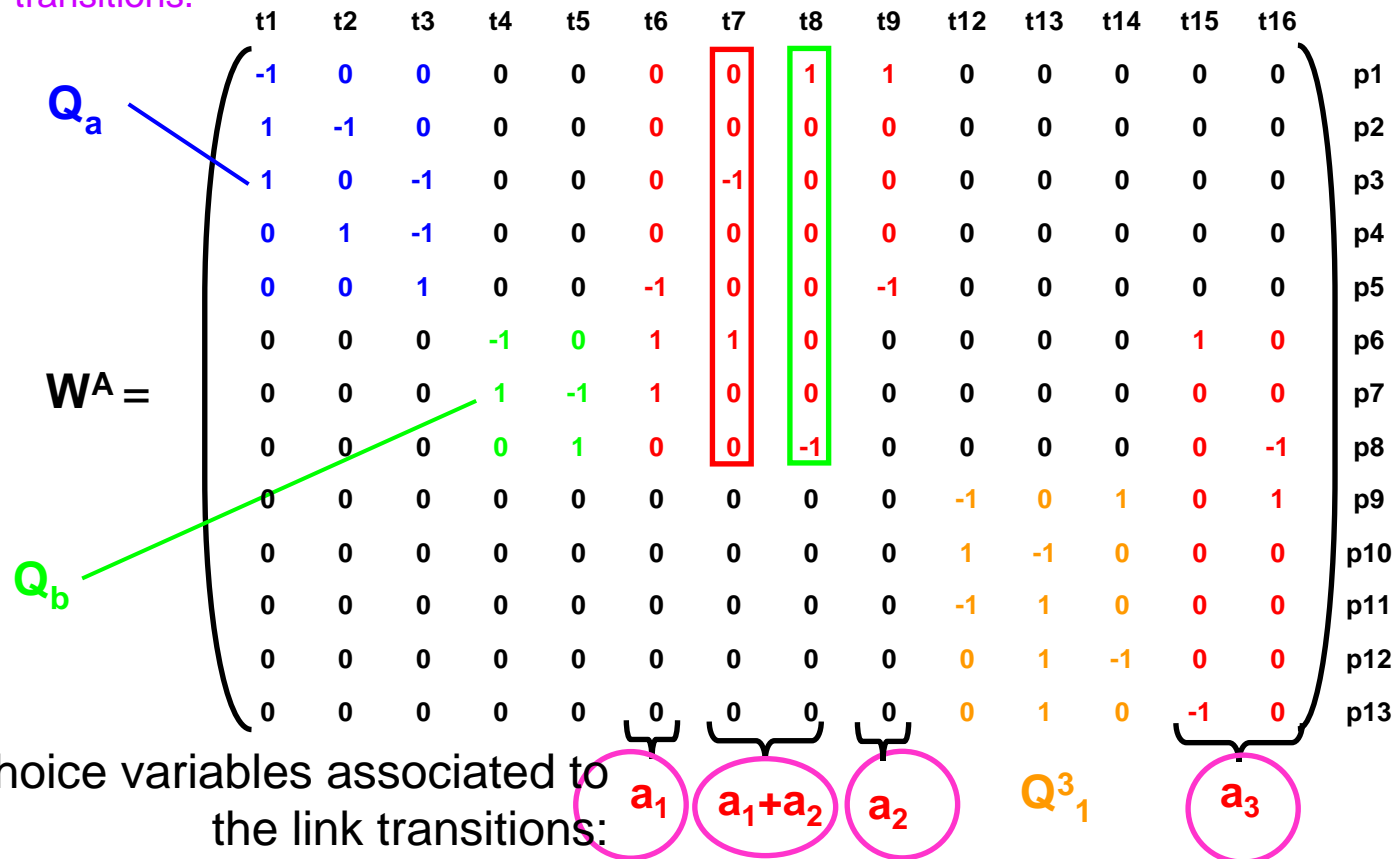
3. Optimization problem based on an undefined Petri net

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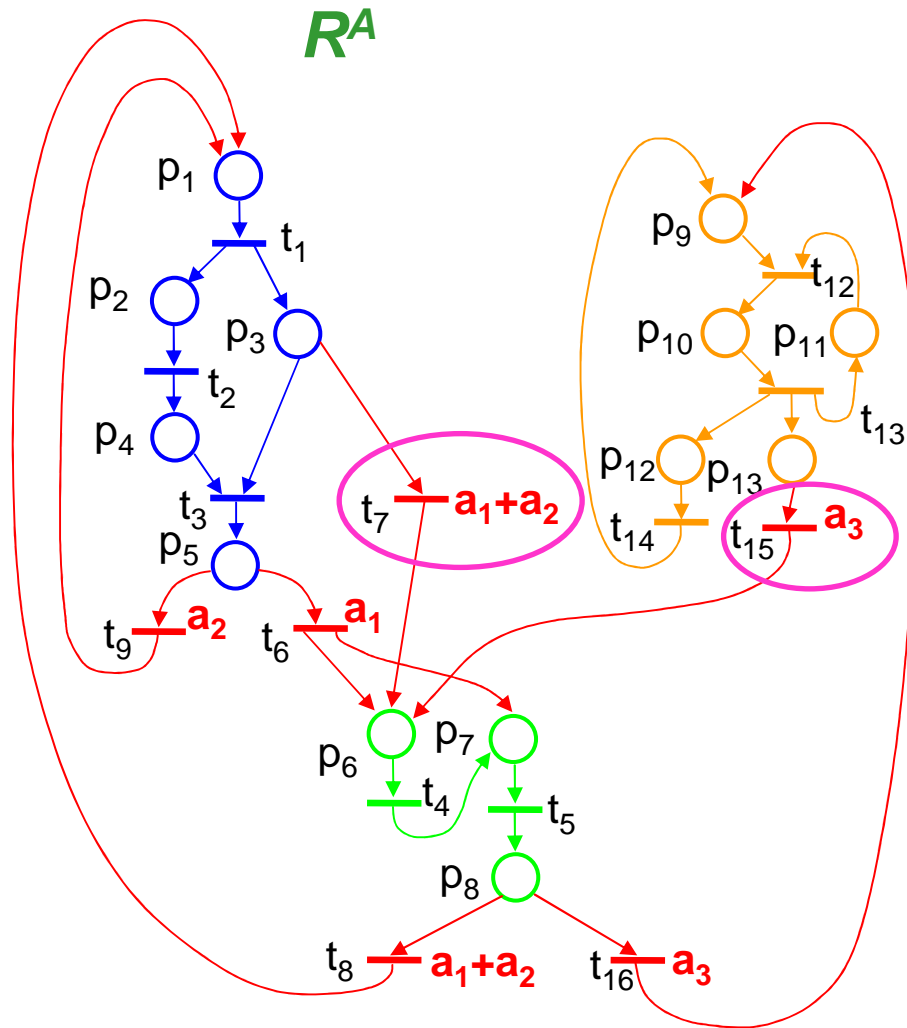
- 1) Every identical columns can be reduced to a single one.
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3. Optimization problem based on an undefined Petri net

Example 4

4. Simplification of functions



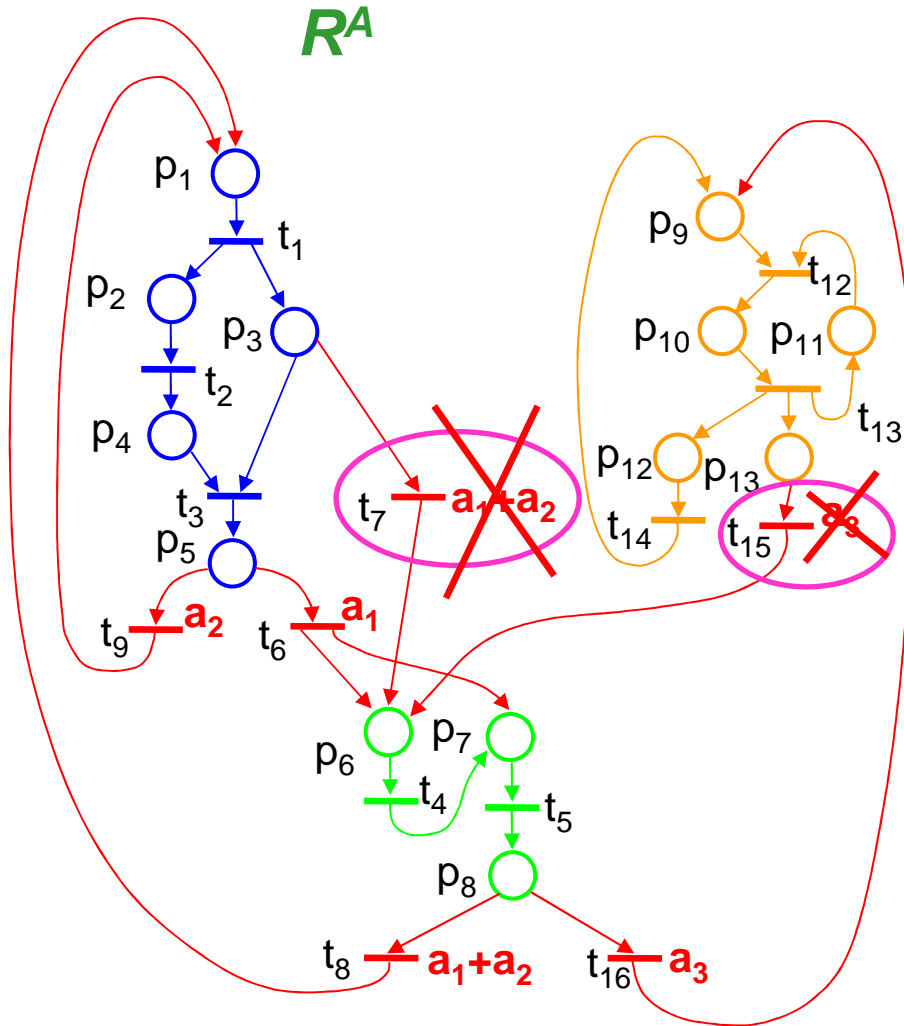
Application of the rule of simplification

t_7 and t_{10} are only enabled when one of the choice variables of the associated function is active.

3. Optimization problem based on an undefined Petri net

Example 4

4. Simplification of functions



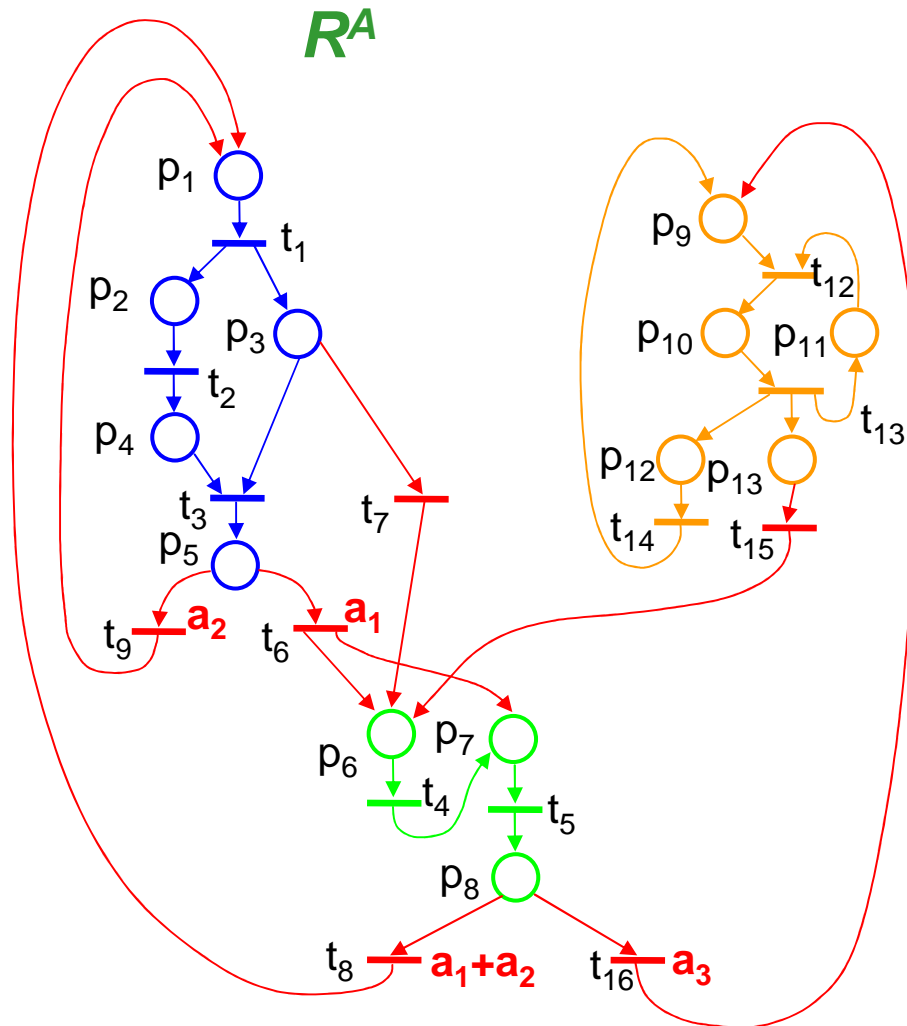
Application of the rule of simplification

t_7 and t_{10} are only enabled when one of the choice variables of the associated function is active.

3. Optimization problem based on an undefined Petri net

Example 4

5. Simplified AAPN



**Alternatives
aggregation PN**

PN equivalent to the
original set of simple
alternative PN

3. Optimization problem based on an undefined Petri net

Example 4

5. Simplified AAPN

Incidence matrix of the AAPN

	t1	t2	t3	t4	t5	t6	t7	t8	t9	t12	t13	t14	t15	t16	
Q_a	-1	0	0	0	0	0	0	1	1	0	0	0	0	0	p1
	1	-1	0	0	0	0	0	0	0	0	0	0	0	0	p2
	1	0	-1	0	0	0	-1	0	0	0	0	0	0	0	p3
	0	1	-1	0	0	0	0	0	0	0	0	0	0	0	p4
	0	0	1	0	0	-1	0	0	-1	0	0	0	0	0	p5
	0	0	0	-1	0	1	1	0	0	0	0	0	1	0	p6
	0	0	0	1	-1	1	0	0	0	0	0	0	0	0	p7
	0	0	0	0	1	0	-1	0	0	0	0	0	0	-1	p8
	0	0	0	0	0	0	0	0	0	-1	0	1	0	1	p9
	0	0	0	0	0	0	0	0	0	1	-1	0	0	0	p10
	0	0	0	0	0	0	0	0	0	-1	1	0	0	0	p11
	0	0	0	0	0	0	0	0	0	0	1	-1	0	0	p12
	0	0	0	0	0	0	0	0	0	0	1	0	-1	0	p13

Choice variables associated to the link transitions:

a_1 (pointing to t6), a_2 (pointing to t8), a_3 (pointing to t16), and $a_1 + a_2$ (pointing to t7).

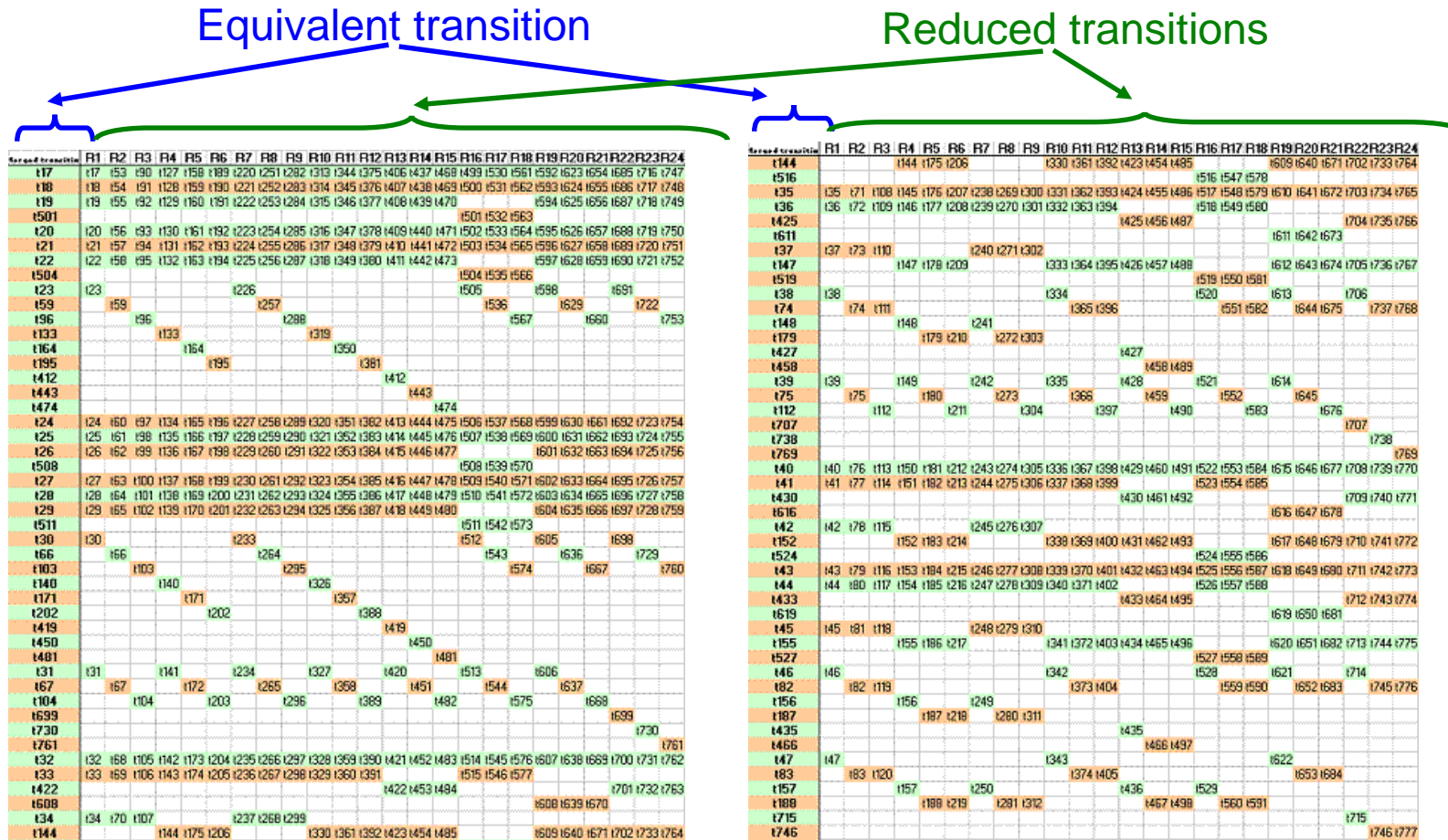
Q_a (blue box around t1-t3), Q_b (green box around t4-t5), Q^3_1 (orange box around t12-t14), and red boxes around columns t6, t7, t8, t9, t15, t16.

3. Optimization problem based on an undefined Petri net

Example 2

3 y 4. Reduction and simplification

The number of link transitions is reduced from 741 to 92.



3. Optimization problem based on an undefined Petri net

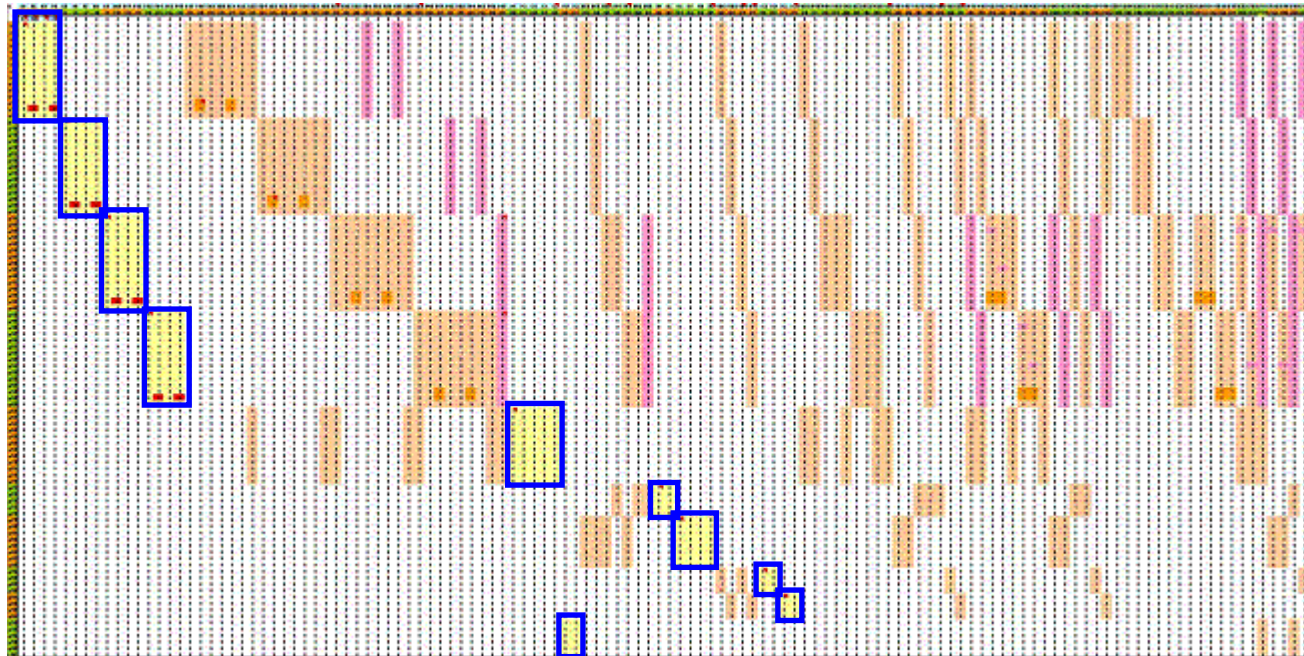
Example 2

3 y 4. Reduction and simplification

Incidence matrix of the AAPN (Same information than in the original alternative PN).

Size = 99x125 versus 78x54 in the ones from everyone of the 24 alternative PN.

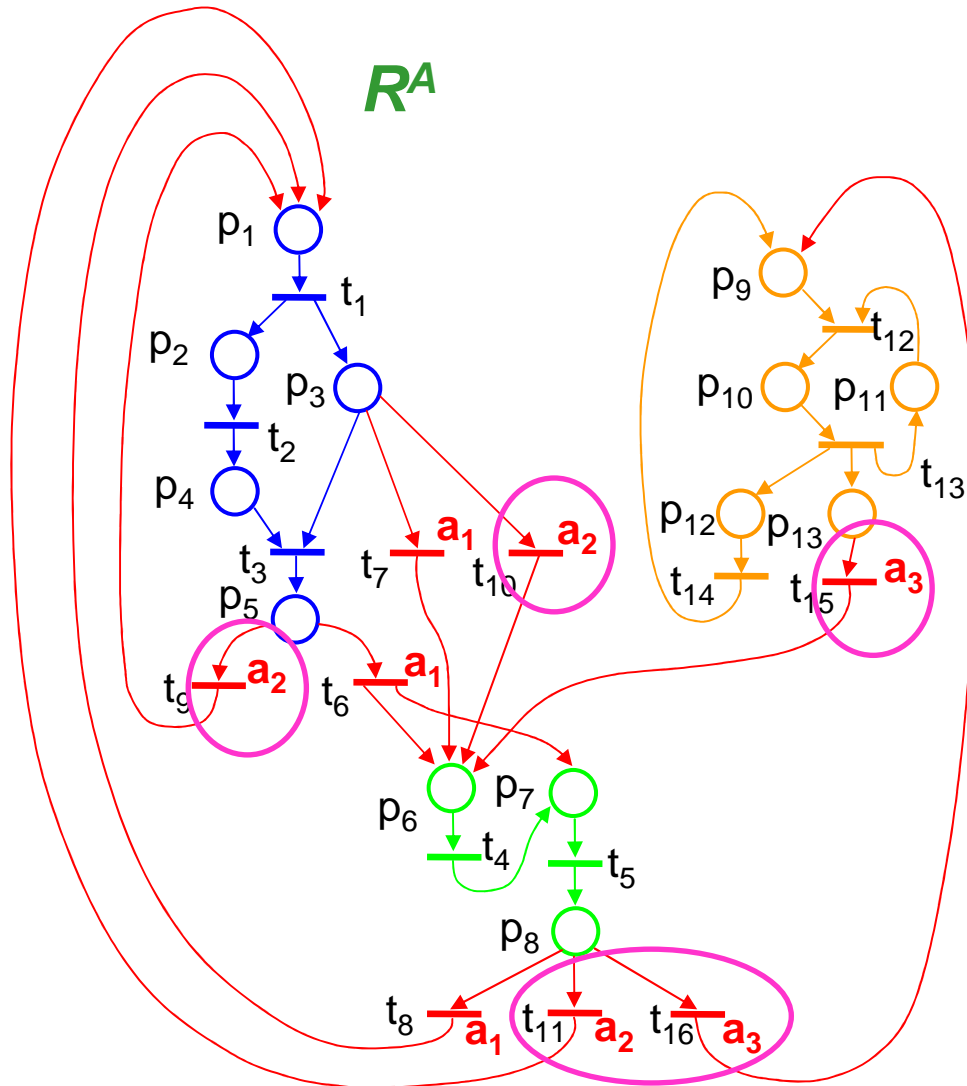
- Blocks associated to the subnets.
- Columns associated to the link transitions.
- Columns associated to the link transitions that represent work orders (push/pull).



3. Optimization problem based on an undefined Petri net

Ejemplo 4

Behaviour of the AAPN



Let us suppose that $a_1=1$

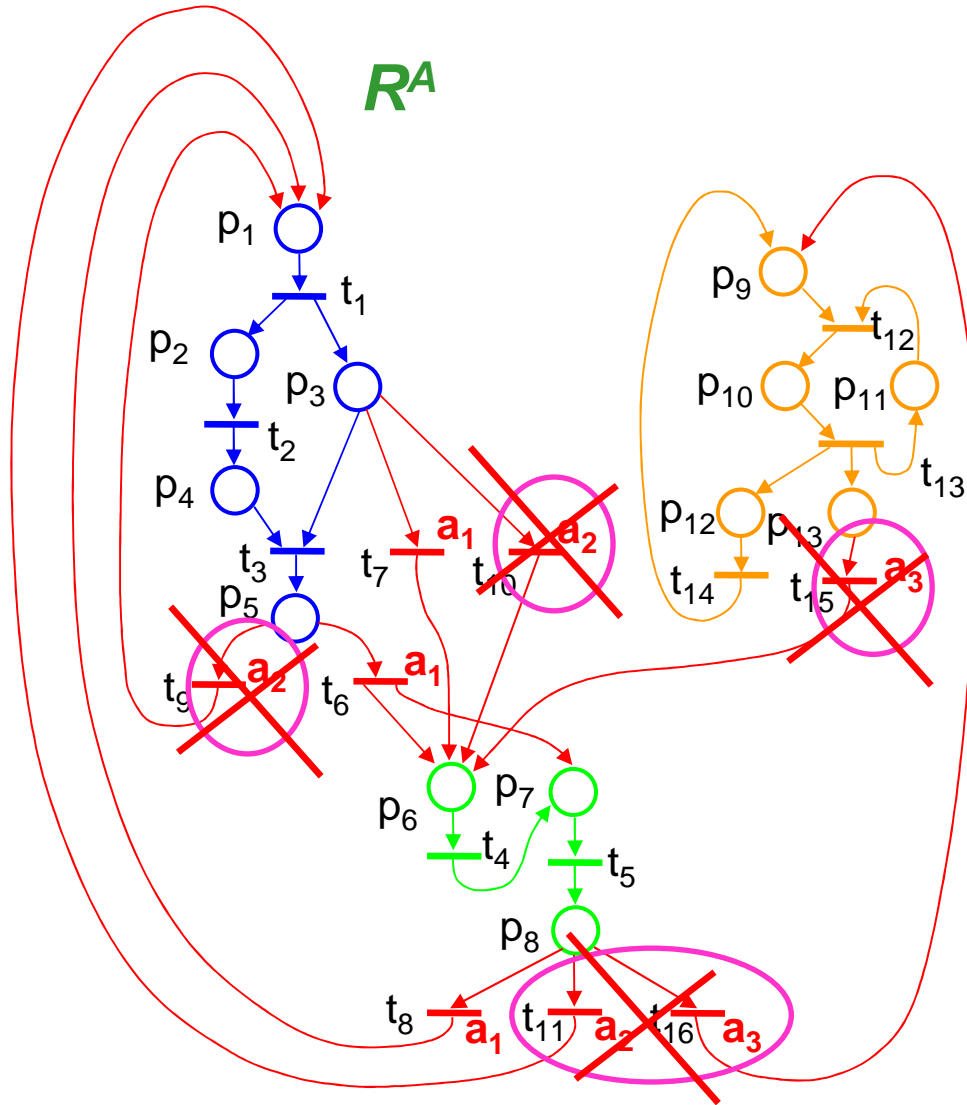
By definition $a_j=0$, $i \neq j$, $1 \leq j \leq n$,
(n = number of alternative PN).

a) Removing the transitions that are not allowed to fire, a PN with the same reachability graph than the original alternative PN R_1 is obtained. This behaviour is shared for a basic and a simplified AAPN.

3. Optimization problem based on an undefined Petri net

Ejemplo 4

Behaviour of the AAPN



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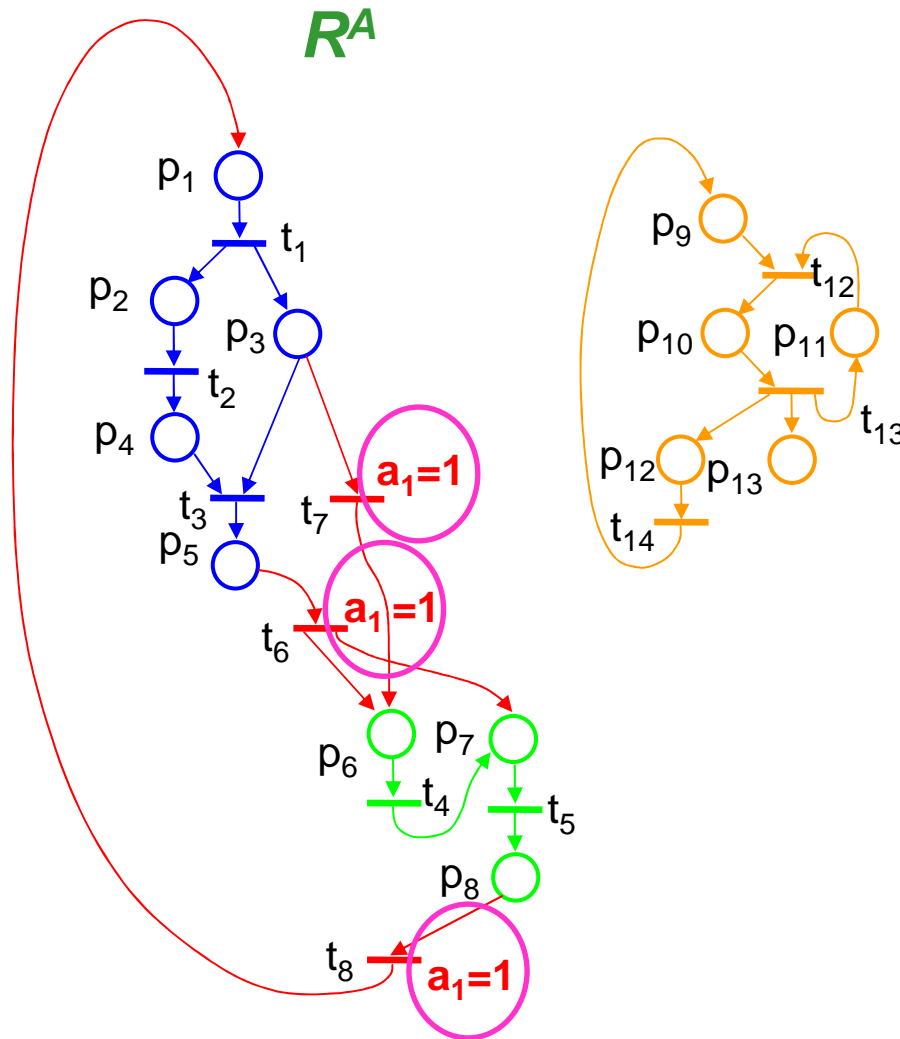
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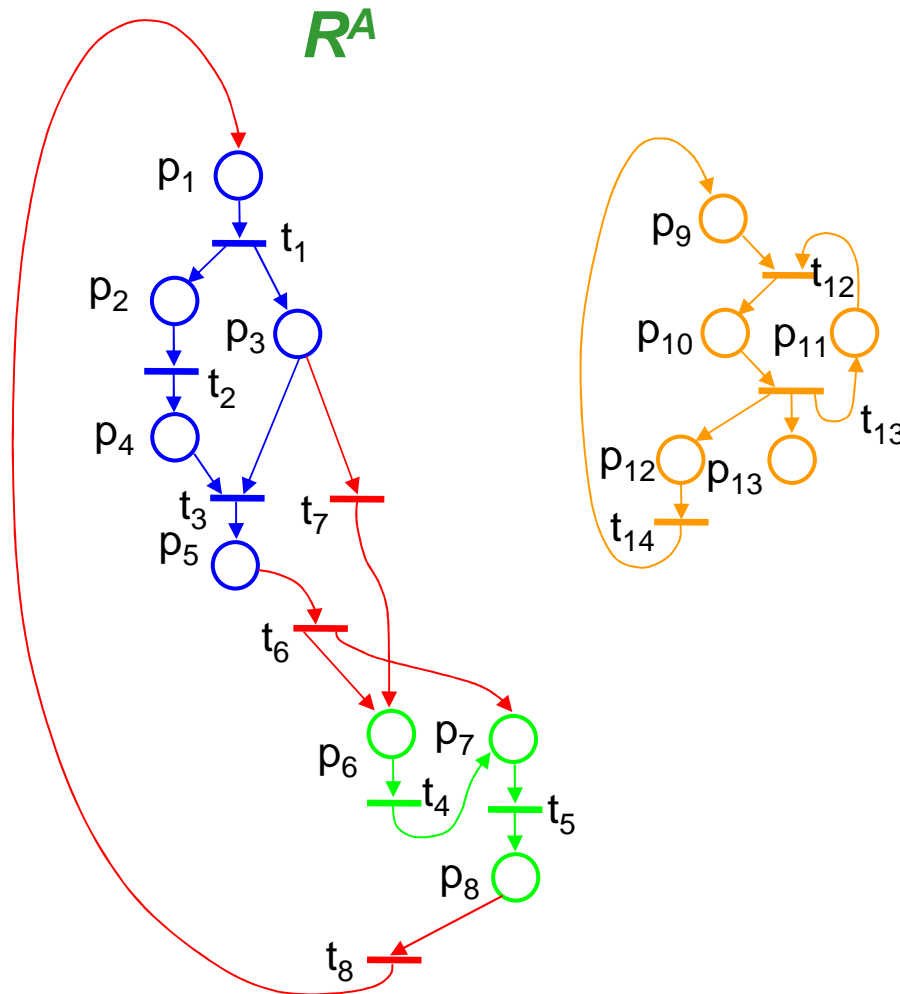
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Ejemplo 4

Behaviour of the AAPN



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By definition $a_j=0, i \neq j, 1 \leq j \leq n$,
(n = number of alternative PN).

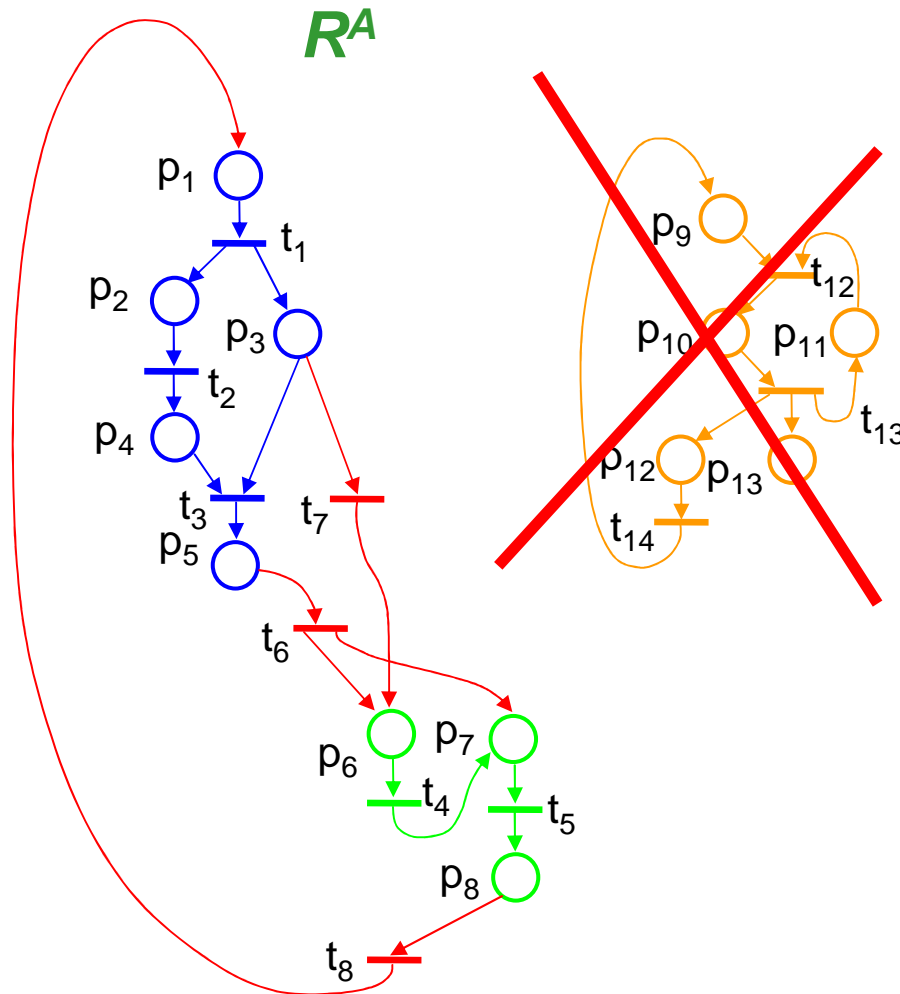
a) Removing the transitions that are not allowed to fire, a PN with the same reachability graph than the original alternative PN R_1 is obtained. This behaviour is shared for a basic and a simplified AAPN.

b) According to the definition of extended marking $m_0^{E1}(p_k) = 0$ with $9 \leq k \leq 13 \Rightarrow$ the subnet R_1^3 does not participate in the evolution of the PN.

3. Optimization problem based on an undefined Petri net

Ejemplo 4

Behaviour of the AAPN



Let us suppose that $a_i=1$

By definition $a_j=0, i \neq j, 1 \leq j \leq n$,
(n = number of alternative PN).

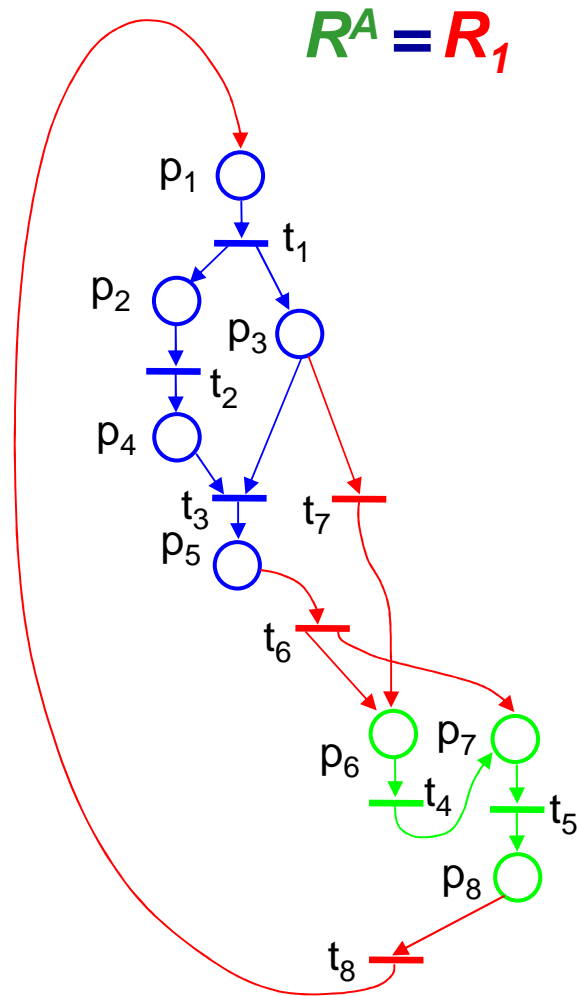
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3. Optimization problem based on an undefined Petri net

Ejemplo 4

Behaviour of the AAPN



Let us suppose that $a_1=1$

By definition $a_j=0, i \neq j, 1 \leq j \leq n$,
(n = number of alternative PN).

a) Removing the transitions that are not allowed to fire, a PN with the same reachability graph than the original alternative PN R_1 is obtained. This behaviour is shared for a basic and a simplified AAPN.

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3. Optimization problem based on an undefined Petri net

Outline

New statement of the problem

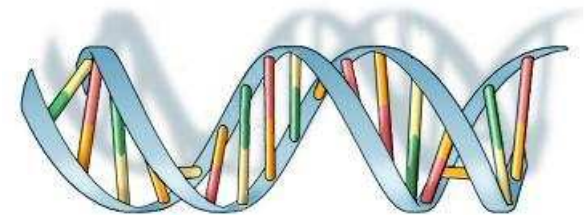
- Max/min objective/multiobjective function } Quality measurement of a solution
- Definition of the structure of the feasible solutions.
- Constraints → configuration of the solution space.
- Alternatives aggregation Petri net:
 1. Obtained from a disjunctive constraint but it is handled as a non-disjunctive constraint.
 2. It is a complement to the objective function.

3. Optimization problem based on an undefined Petri net

Solution by means of a genetic algorithm

Steps of the classical methodology

- 1) Random selection of the initial set of feasible solutions.
- 2) Evaluation of the objective function for every feasible solution
- 3) Evaluation of the stop criterion.
- 4) Calculation of the quality of every solution.
- 5) Removal of the less apt solutions.
- 6) Obtention of the new generation of solutions from the crossover of the surviving solutions.
- 7) Return to step 2.



3. Optimization problem based on an undefined Petri net

Comparison

Optimization based on n alternative PN.

- ☹️ n optimizations based on a single Petri net.
- ☹️ Worst alternative PNs → waste of time.
- ☹️ Additional stage for the comparison of the results.

Optimization based on an AAPN

- 😊 1 single optimization process, based on an AAPN.
- 😊 Computational effort focussed on the most promising regions of the solution space.
- ☹️ Larger size of the incidence matrices.
- 😊 It profits from the shared subnets.

3. Optimization problem based on an undefined Petri net

Example 2

Comparison

General characteristics

15 generations.

Population composed by 50 feasible solutions.

Adjustable parameters (mortality rate, mutation rate, type of crossover, etc).

Option 1: 24 optimizations based on a compound alternative PN.

Option 2: 1 optimization based on a single AAPN.

3. Optimization problem based on an undefined Petri net

Example 2

Comparison

Solution obtained from the AAPN

Quality of the solution

The value of the objective function is the **98.85%** of the value obtained from the process of 24 optimizations

Computational working time

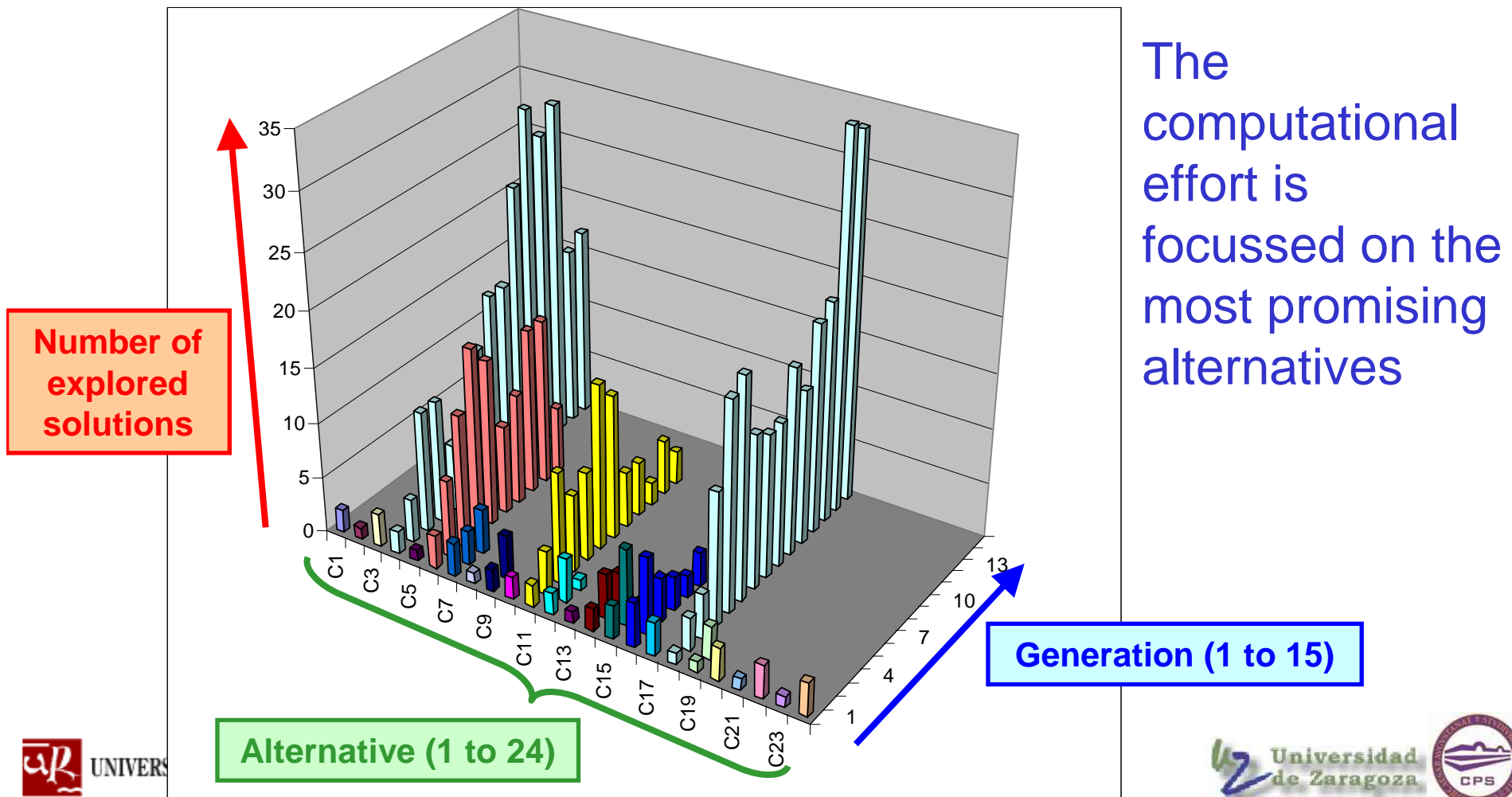
The time needed to develop is the **10.07%** of the time needed to perform the 24 optimization (note: the stage of comparing the results has not been included).

3. Optimization problem based on an undefined Petri net

Example 2

Comparison

Explanation of the results



4. Conclusions

Methodology for decision taking based on alternatives aggregation Petri nets

1. Decision problem based on a DES

2. Decision problem based on an undefined Petri net

Representation by means of {
Simple or compound alternative PN.
AAPN or CPN.

3. Optimization problem based on an undefined PN.

4. Optimization problem based on an alternatives aggregation Petri net.

Transforms a disjunctive constraint.

The AAPN is not unique. It depends on → {
Set of alternative PN
Decomposition in subnets and link transitions

Efficient application of a classical methodology

Equivalent to a coloured PN which allows the use of its software

4. Conclusions

Methodology for decision taking based on alternatives aggregation Petri nets

Open research fields

Increase the efficiency in the application of the genetic algorithm:

Data storage / Adjustable characteristics of the algorithm

Extend the analysis of the performance of the optimization based on different representations of an undefined PN (compound PN, etc).

Extend the analysis of the performance of an AAPN obtained from different sets of alternative PN (simple, compound, mixed).

Extend the application of this methodology to other metaheuristics.

Analysis the applicability to other problems and solve them:

Problem of the design of a PN (large number of undefined structural parameters)

Problem of the preventive maintenance (timed sequence of decisions that modify the structure of the Petri net)