Title: Hierarchical SLAM: Real-time accurate mapping of large environments

Author(s): Estrada, C

Source: IEEE TRANSACTIONS ON ROBOTICS Volume: 21 Issue: 4 Pages: 588-596 Published: AUG 2005

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2. Title: A practical approach for EKF-SLAM in an indoor environment: fusing ultrasonic sensors and stereo camera

Author(s): Ahn SH, Choi JW, DoH NL, et al.

Source: AUTONOMOUS ROBOTS Volume: 24 Issue: 3 Pages: 315-335 Published: APR 2008

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Author(s): Villaverde I, Grana M, d'Anjou A


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Author(s): Rodriguez-Losada D, Matia F, Jimenez A, et al.

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Author(s): Ellekilde LP, Huang S, Miro JV, et al.


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9. Title: SLAM with panoramic vision

Author(s): Lemaire T, Lacroix S


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10. Title: Building a robust implementation of bearing-only inertial SLAM for a UAV

Author(s): Bryson M, Sukkarieh S


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