Citing Articles

Title: Multisensor fusion for simultaneous localization and map building
Author(s): Castellanos, JA
Source: IEEE TRANSACTIONS ON ROBOTICS AND AUTOMATION Volume: 17 Issue: 6 Pages: 908-914 Published: DEC 2001

The above article has been cited by the articles listed below.

Results: 15

1. Title: Mobile robot localization using the Haudsoff distance
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2. Title: The M-space feature representation for SLAM
   Author(s): Folkesson J, Jensfelt P, Christensen HI
   Source: IEEE TRANSACTIONS ON ROBOTICS Volume: 23 Issue: 5 Pages: 1024-1035 Published: OCT 2007
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3. Title: Heterogeneous multisensor fusion for mapping dynamic environments
   Author(s): Huang GQ, Rad AB, Wong YK, et al.
   Source: ADVANCED ROBOTICS Volume: 21 Issue: 5-6 Pages: 661-688 Published: 2007
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4. Title: Recent advances in simultaneous localization and map-building using computer vision
   Author(s): Chen ZH, Samarabandu J, Rodrigo R
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5. Title: On multisensor image fusion performance limits from an estimation theory perspective
   Author(s): Blum RS
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6. Title: Local difference probability (LDP)-based environment adaptive algorithm for unmanned ground vehicle
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10. Title: A solution for integrating map building and self localization strategies in mobile robotics
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    Source: INTERNATIONAL JOURNAL OF INTELLIGENT SYSTEMS Volume: 20 Issue: 5 Pages: 499-521 Published: MAY 2005
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