

Virtual light transport matrices for non-line-of-sight imaging

Julio Marco¹ Adrian Jarabo¹ Ji Hyun Nam² Xiaochun Liu²
Miguel Ángel Cosculluela¹ Andreas Velten² Diego Gutierrez¹

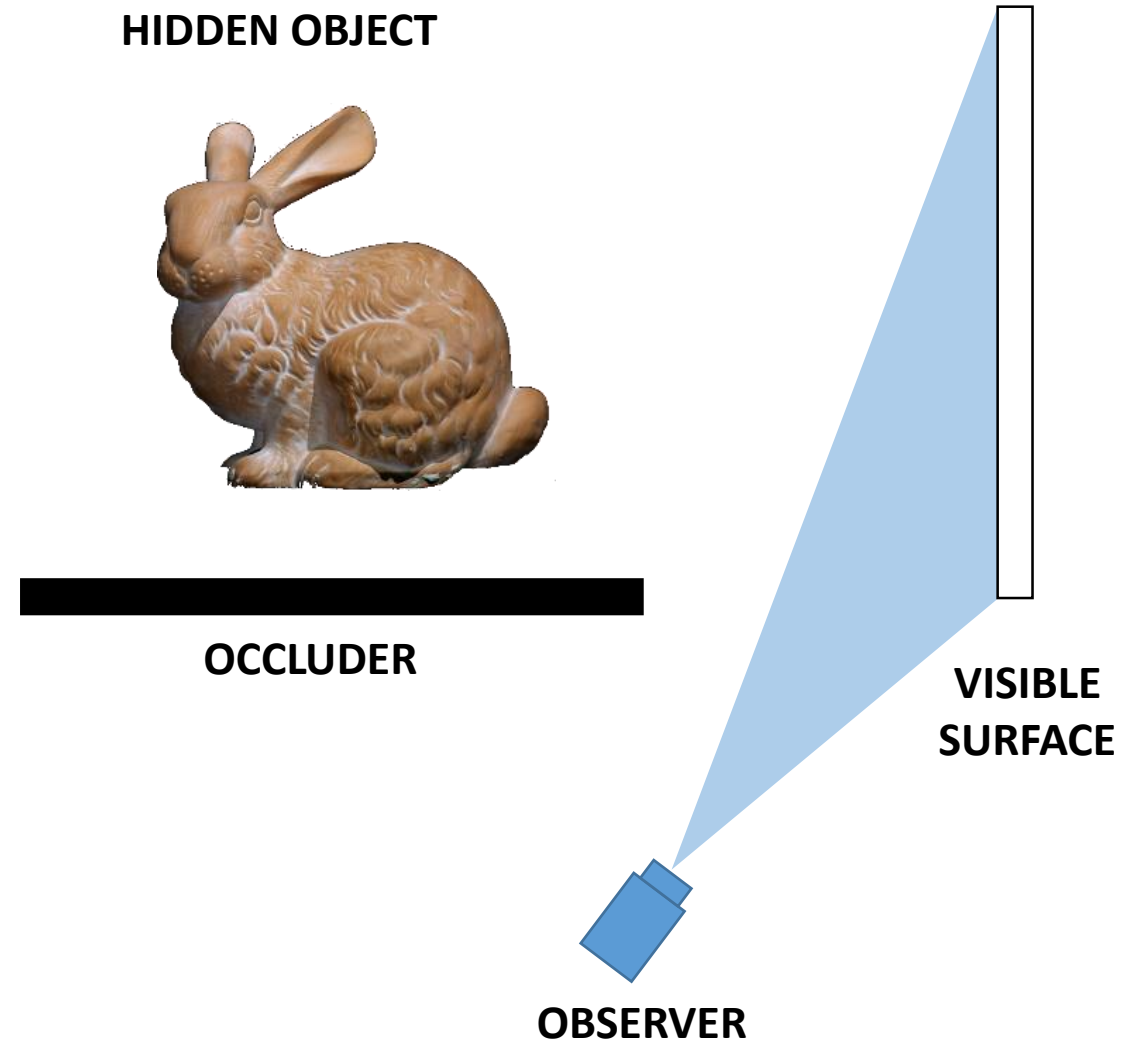
¹Universidad de Zaragoza ²University of Wisconsin-Madison

What is NLOS imaging?

Seeing scenes behind a corner

What is NLOS imaging?

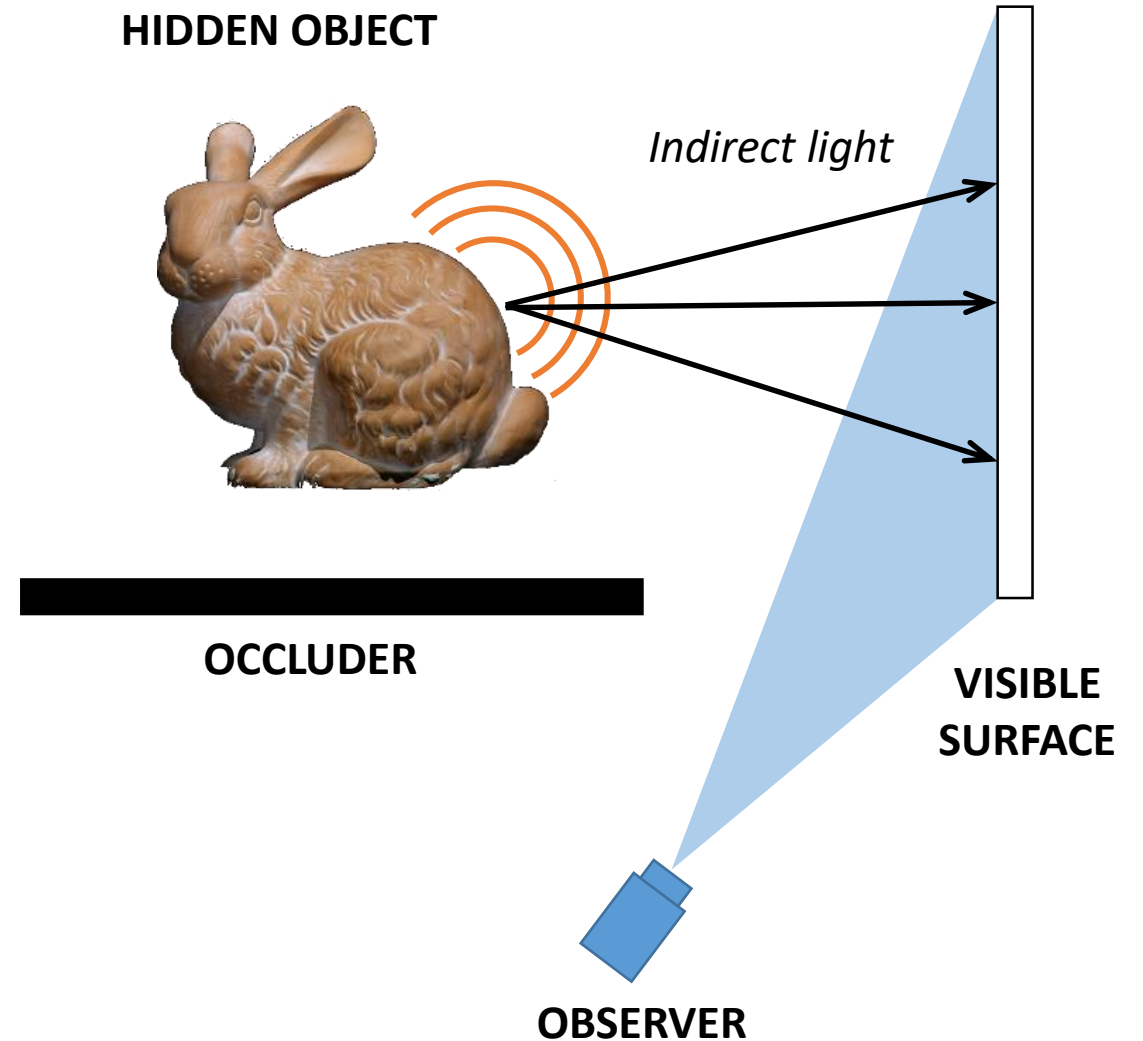
Seeing scenes behind a corner



What is NLOS imaging?

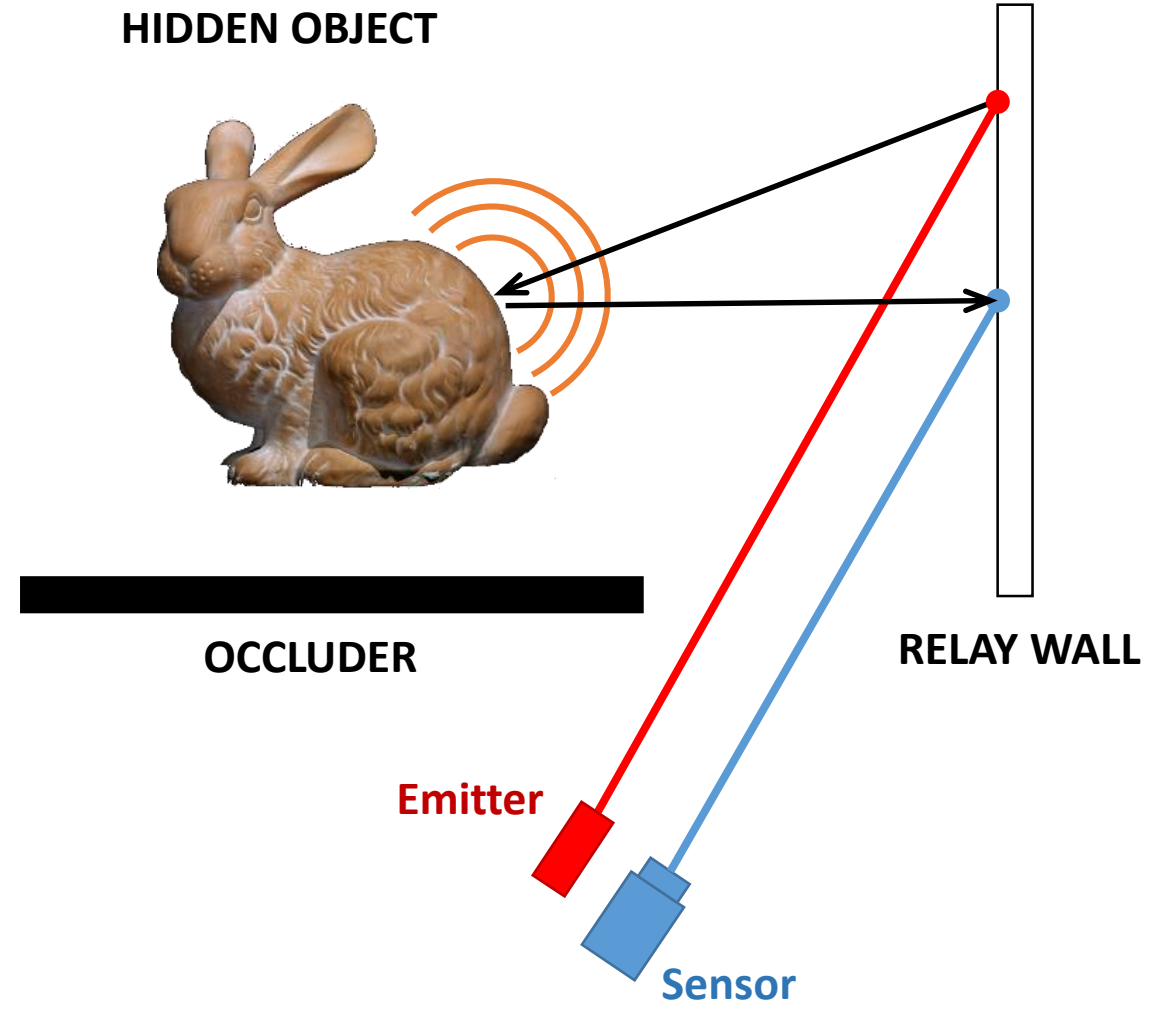
Seeing scenes behind a corner

*Analyze indirect illumination
in visible surfaces*



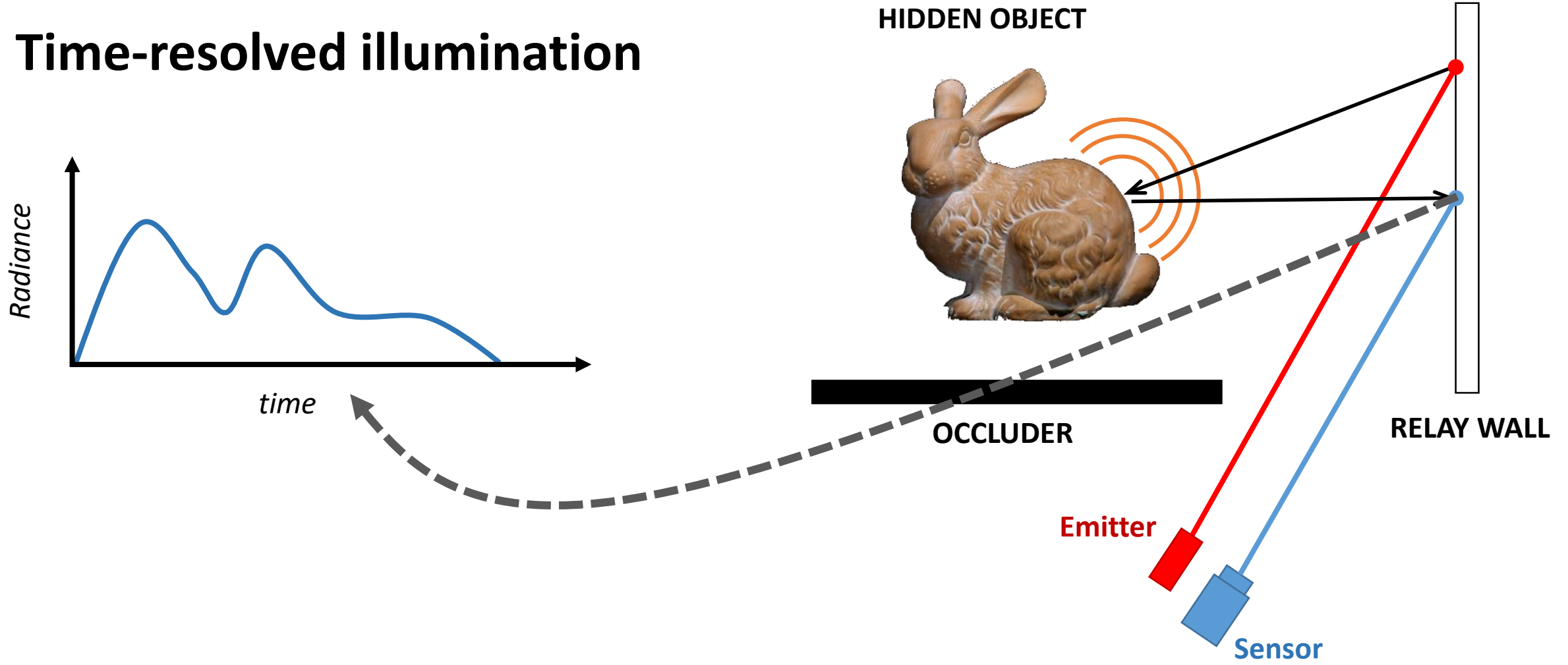
Active-light NLOS imaging

Time-resolved illumination



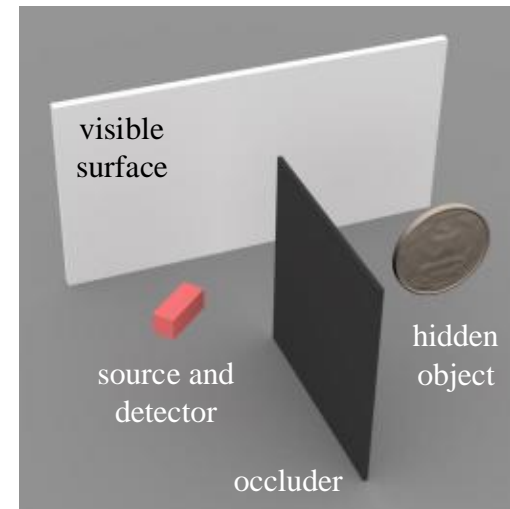
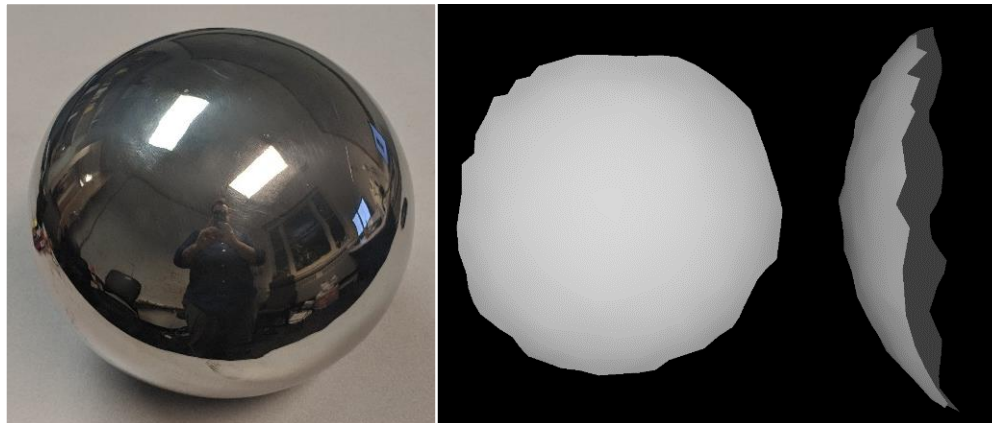
Active-light NLOS imaging

Time-resolved illumination



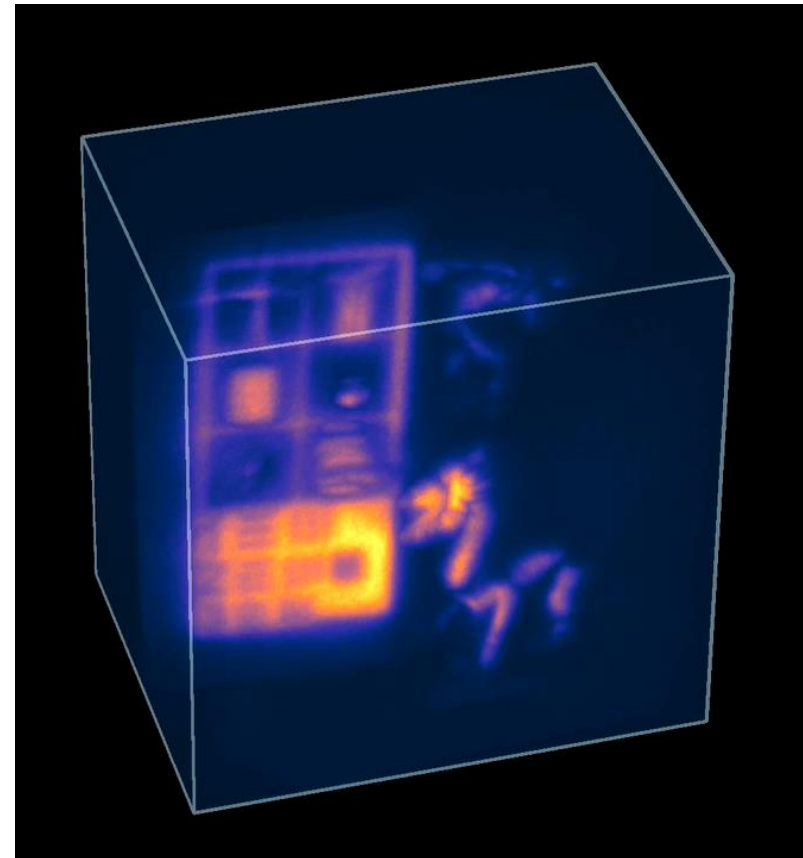
Active-light NLOS imaging

[Xin et al. 2019] Fermat paths



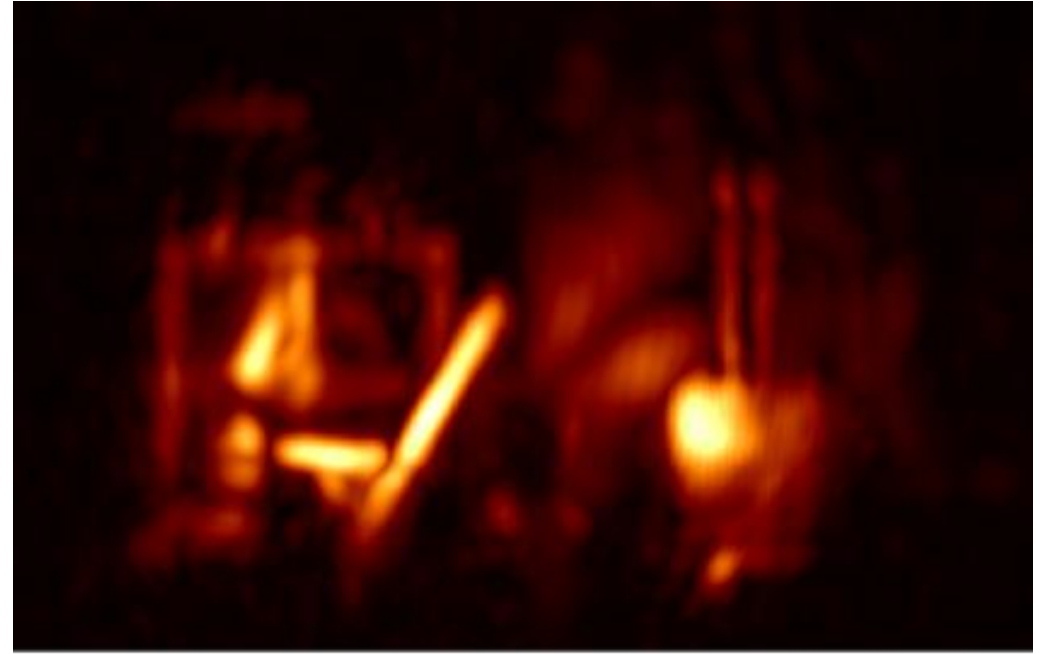
Active-light NLOS imaging

[Lindell et al. 2019] F-k migration



Active-light NLOS imaging

[Liu et al. 2019] Phasor fields



Active-light NLOS imaging

Current state: Mainly reconstruction of geometry

→ Need general understanding:

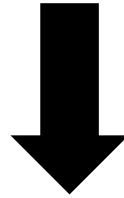
- Light transport components
- Isolation of specific light paths
- Material analysis

Our goal

General understanding of hidden scenes

Our goal

General understanding
of hidden scenes



Framework to compute light
transport in NLOS scenarios

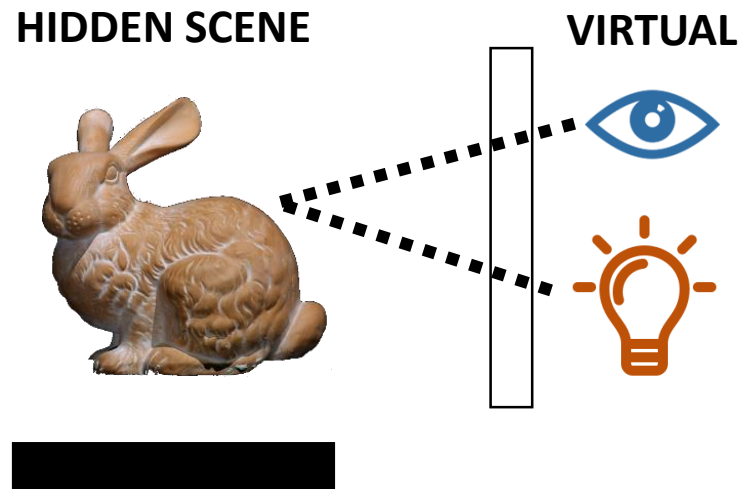
Our goal: General understanding of hidden scenes

How?

Our goal: General understanding of hidden scenes

How?

Phasor-field NLOS imaging



Our goal: General understanding of hidden scenes

How?

**Phasor-field
NLOS imaging**

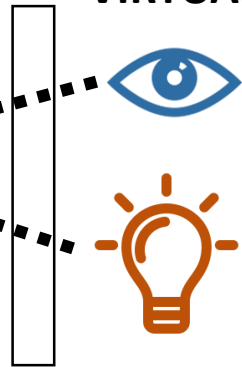
+

**LOS light transport
matrices**

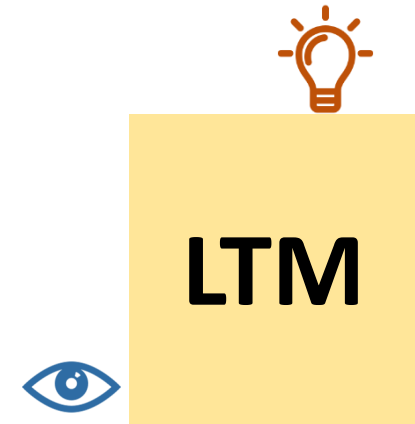
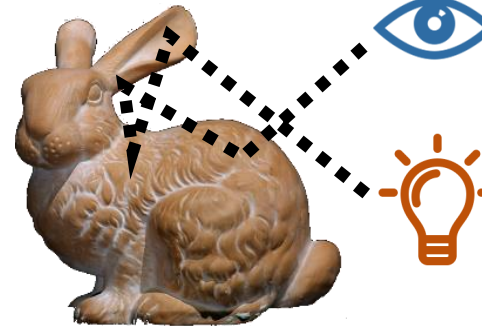
HIDDEN SCENE



VIRTUAL



VISIBLE SCENE



Our goal: General understanding of hidden scenes

How?

**Phasor-field
NLOS imaging**

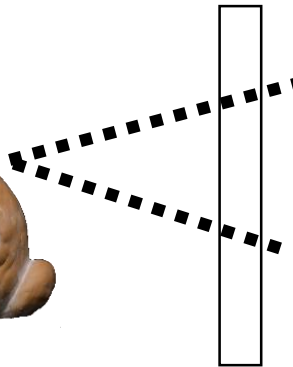
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**LOS light transport
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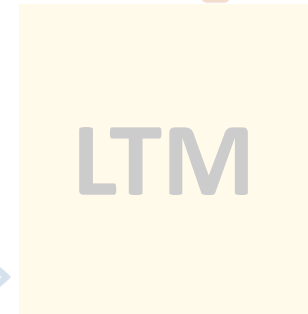
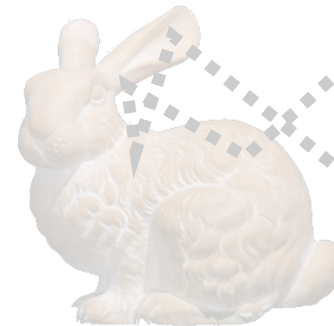
HIDDEN SCENE



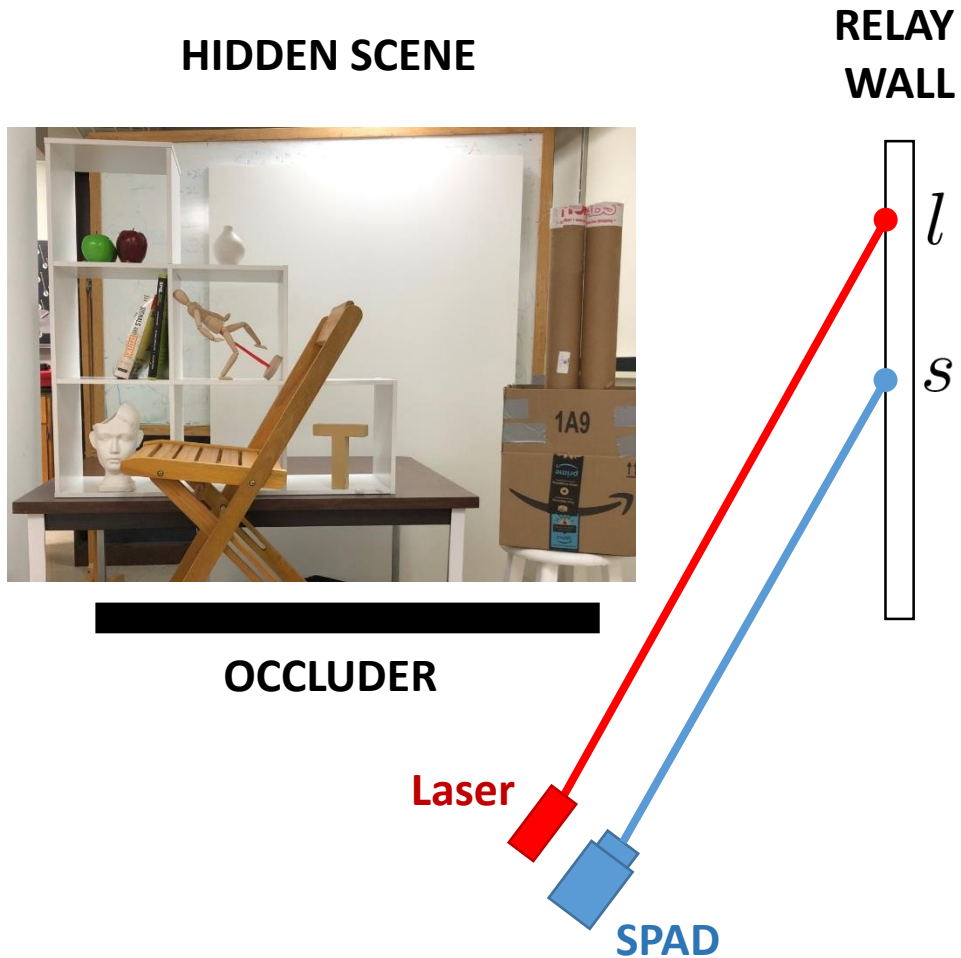
VIRTUAL



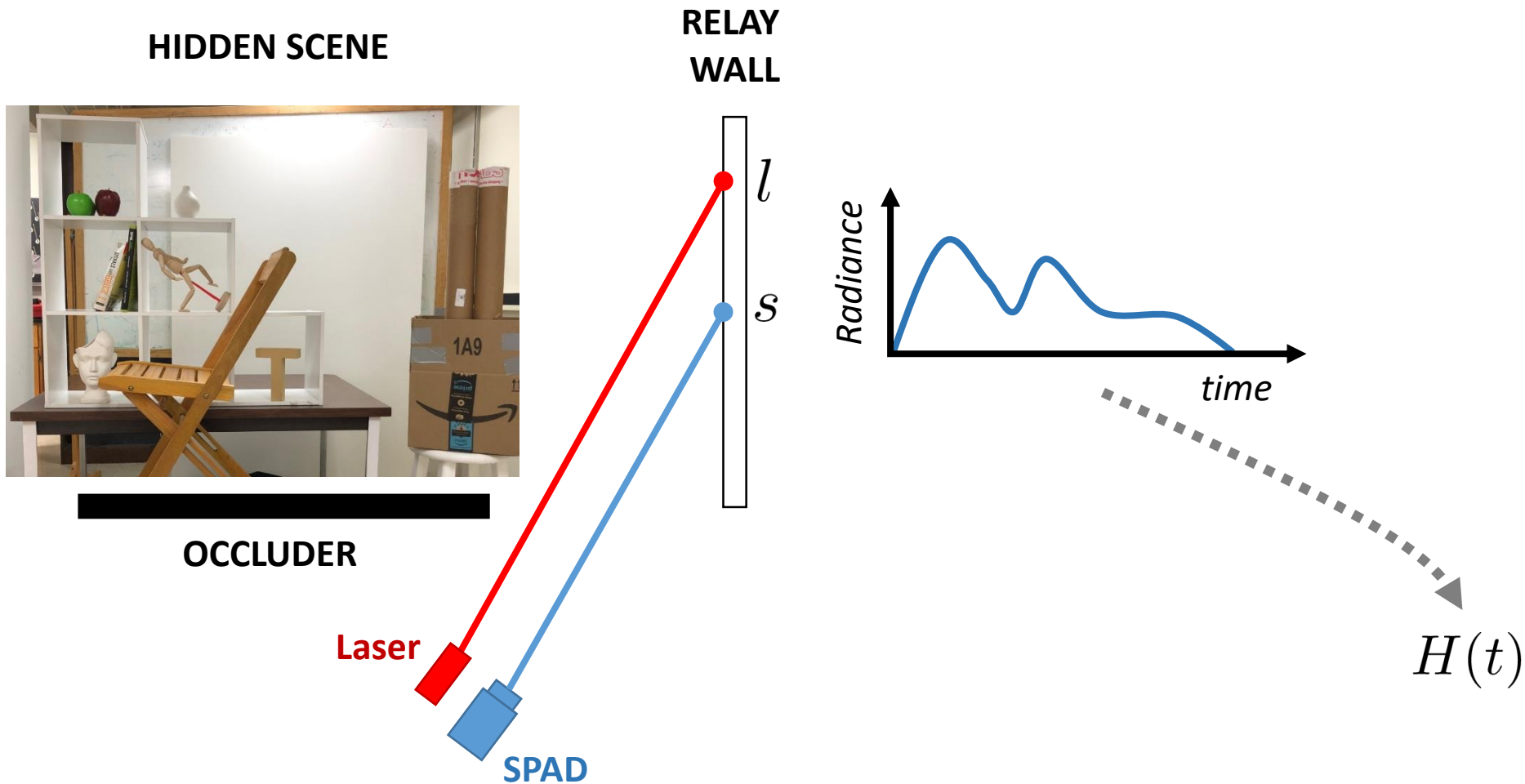
VISIBLE SCENE



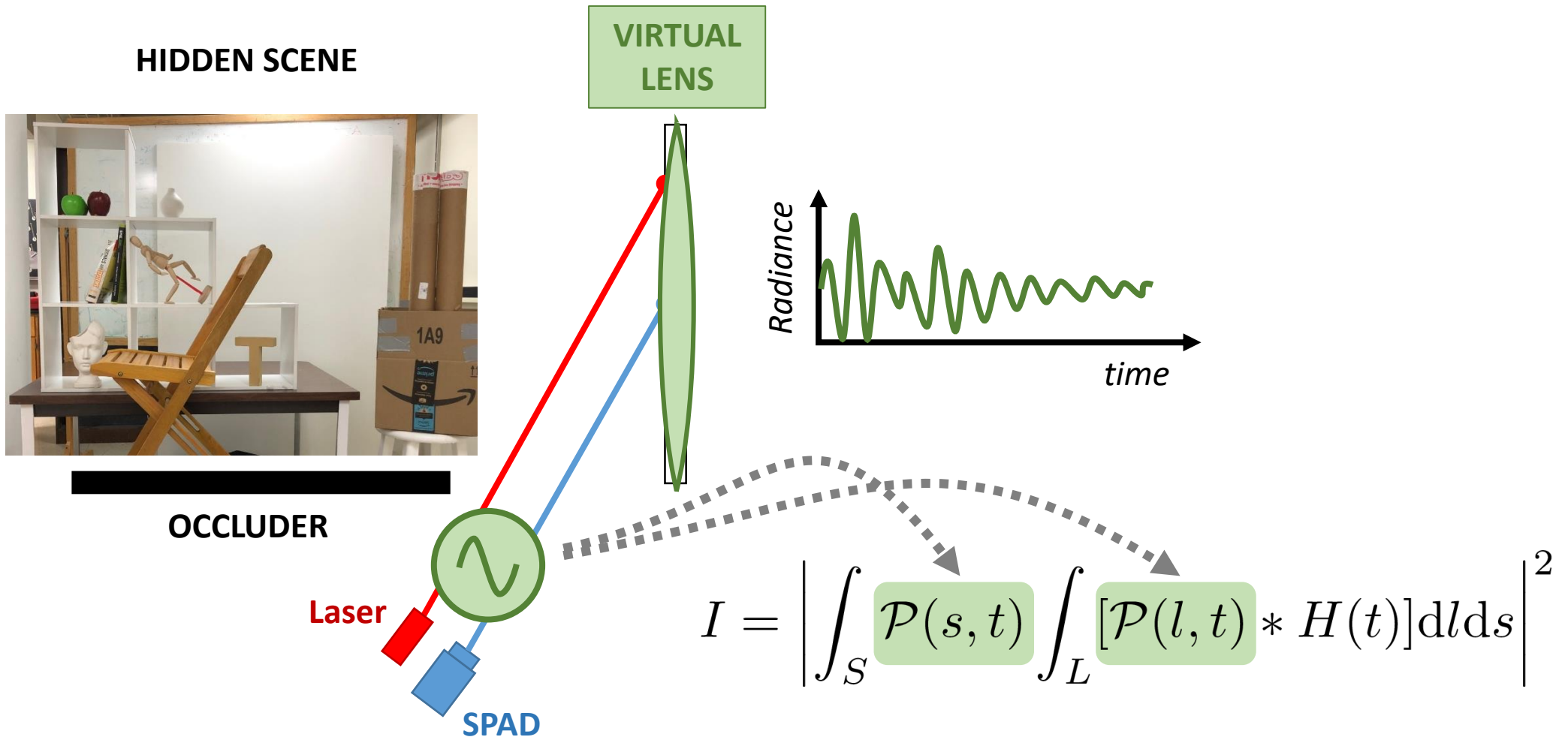
Phasor-field NLOS imaging [Liu et al. 2019, 2020]



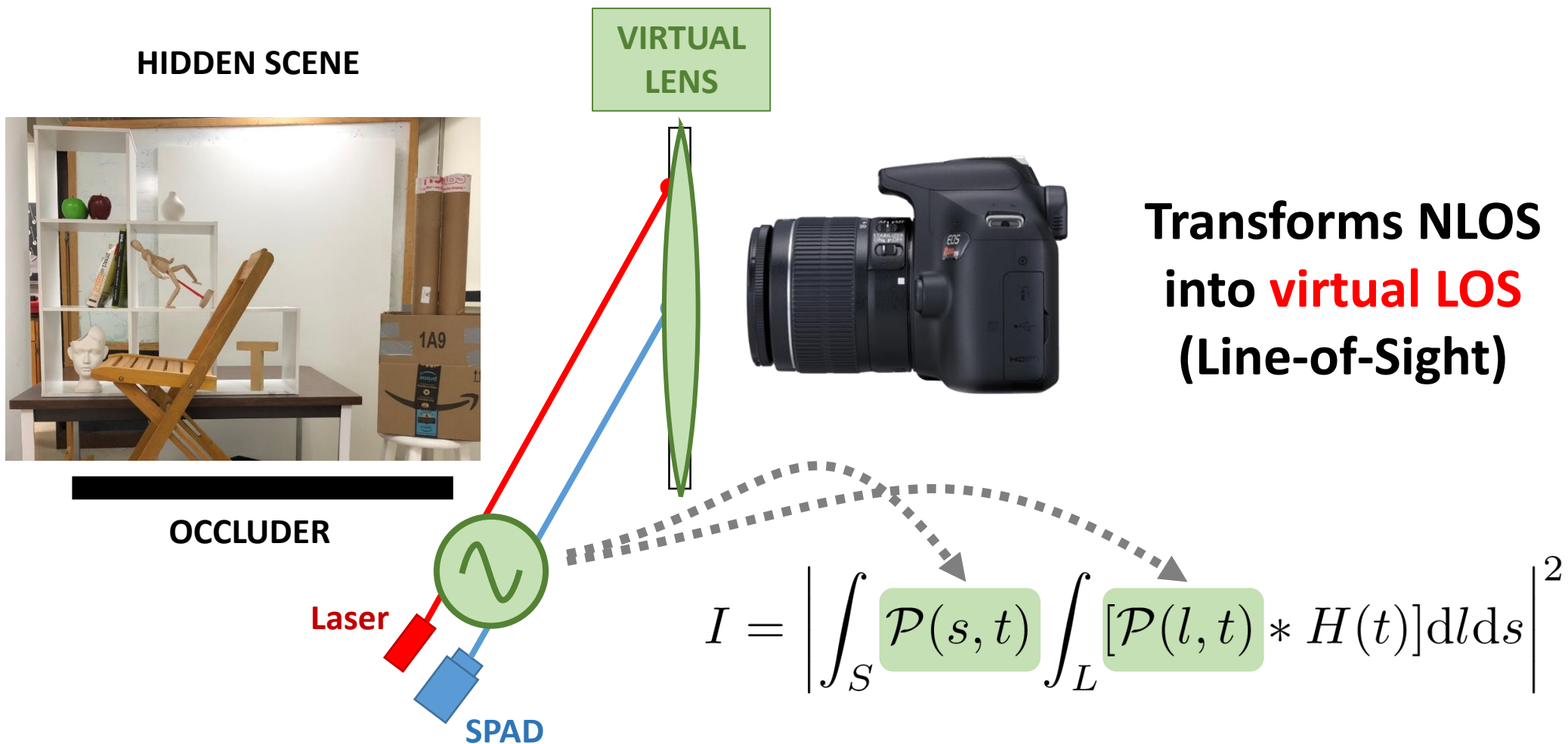
Phasor-field NLOS imaging [Liu et al. 2019, 2020]



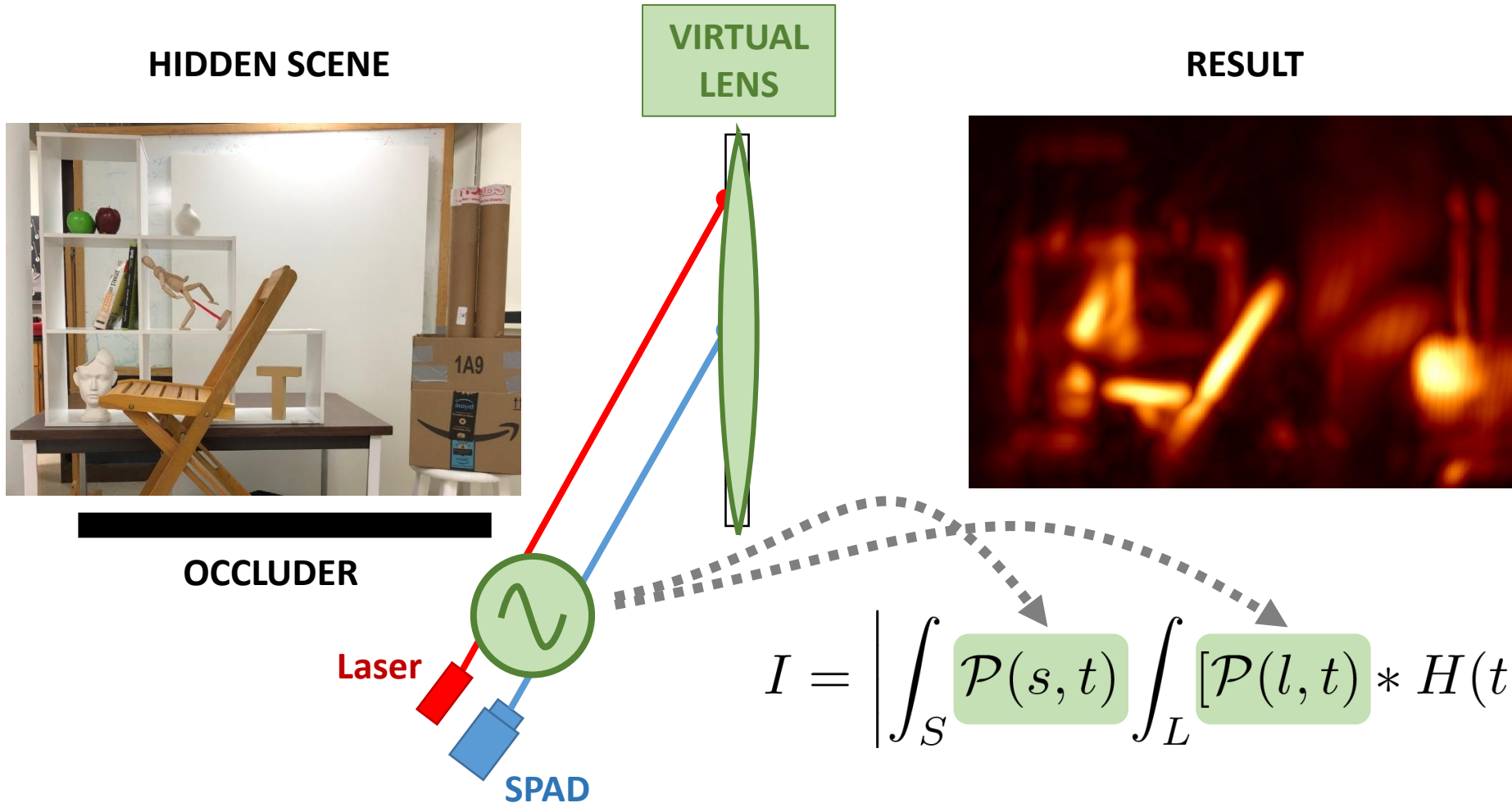
Phasor-field NLOS imaging [Liu et al. 2019, 2020]



Phasor-field NLOS imaging [Liu et al. 2019, 2020]



Phasor-field NLOS imaging [Liu et al. 2019, 2020]



Our goal: General understanding of hidden scenes

How?

Phasor-field
NLOS imaging

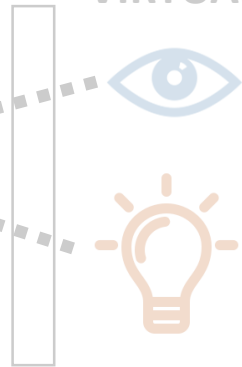


LOS light transport
matrices

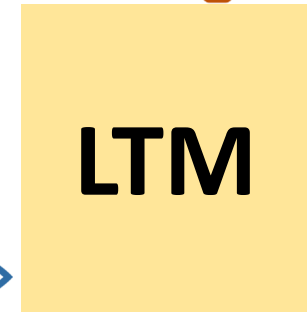
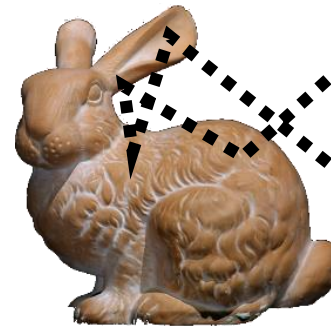
HIDDEN SCENE



VIRTUAL

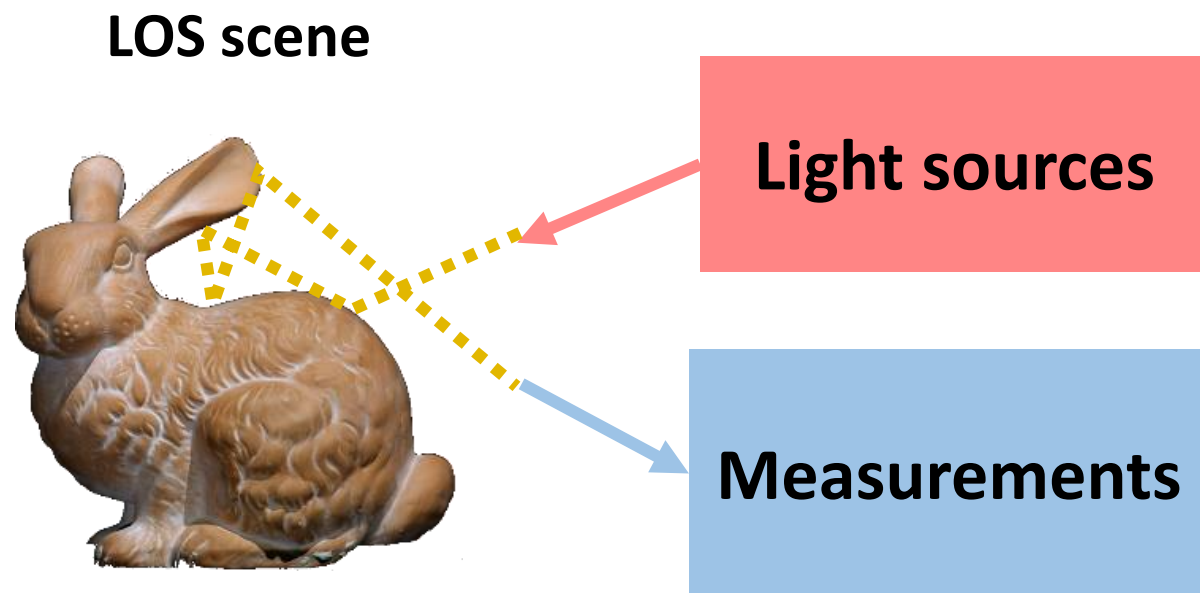


VISIBLE SCENE



Light transport equation

LTM is fundamental in scene understanding



$$\mathbf{i} = \mathbf{T} \cdot \mathbf{p}$$

The equation is represented visually with a blue vertical bar for \mathbf{i} , a yellow square for \mathbf{T} , and a red vertical bar for \mathbf{p} .

Light transport matrix probing

[Nayar et al. 2006] Fast direct vs. global illumination separation



Direct



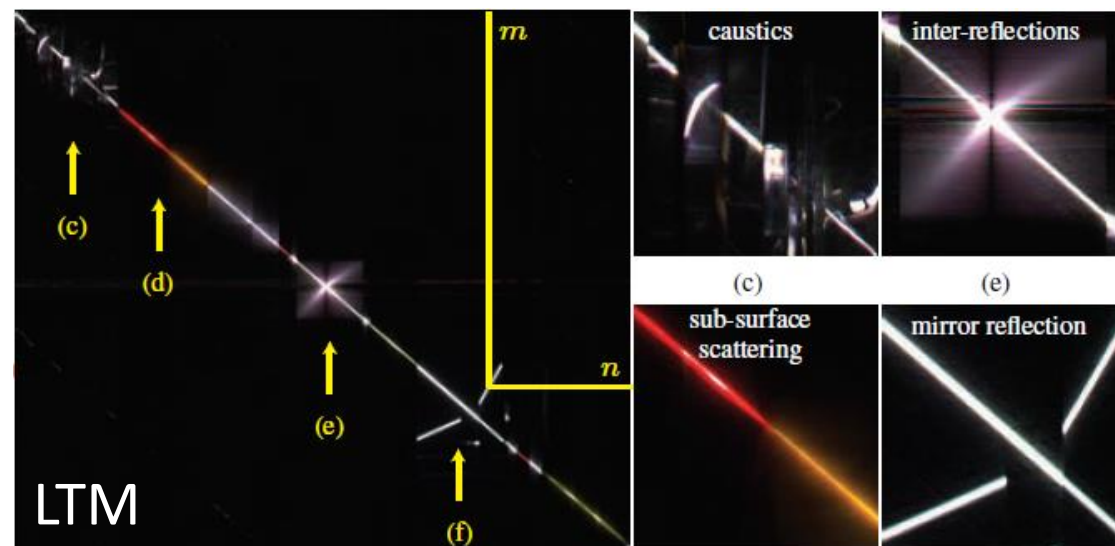
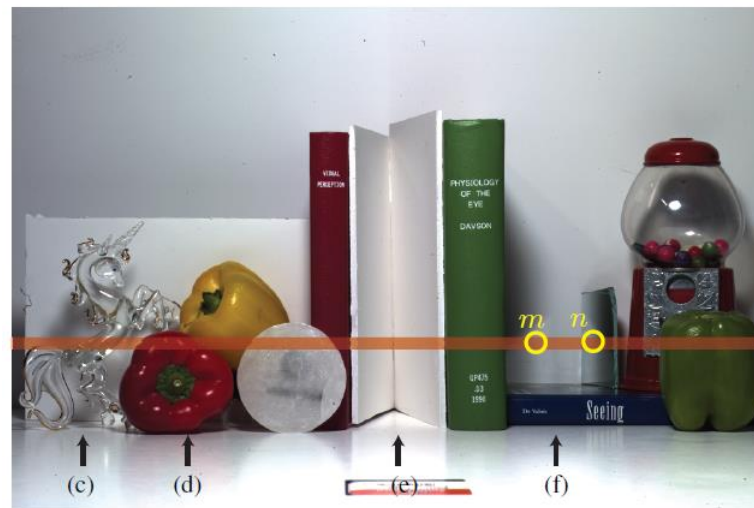
Global

Light transport matrix probing

[O'Toole et al. 2012]

LTM probing:

- Short vs long range separation
- De-scattering
- Masking specific paths
- Sub-surface scattering, caustics, interreflections



LOS light transport matrix probing

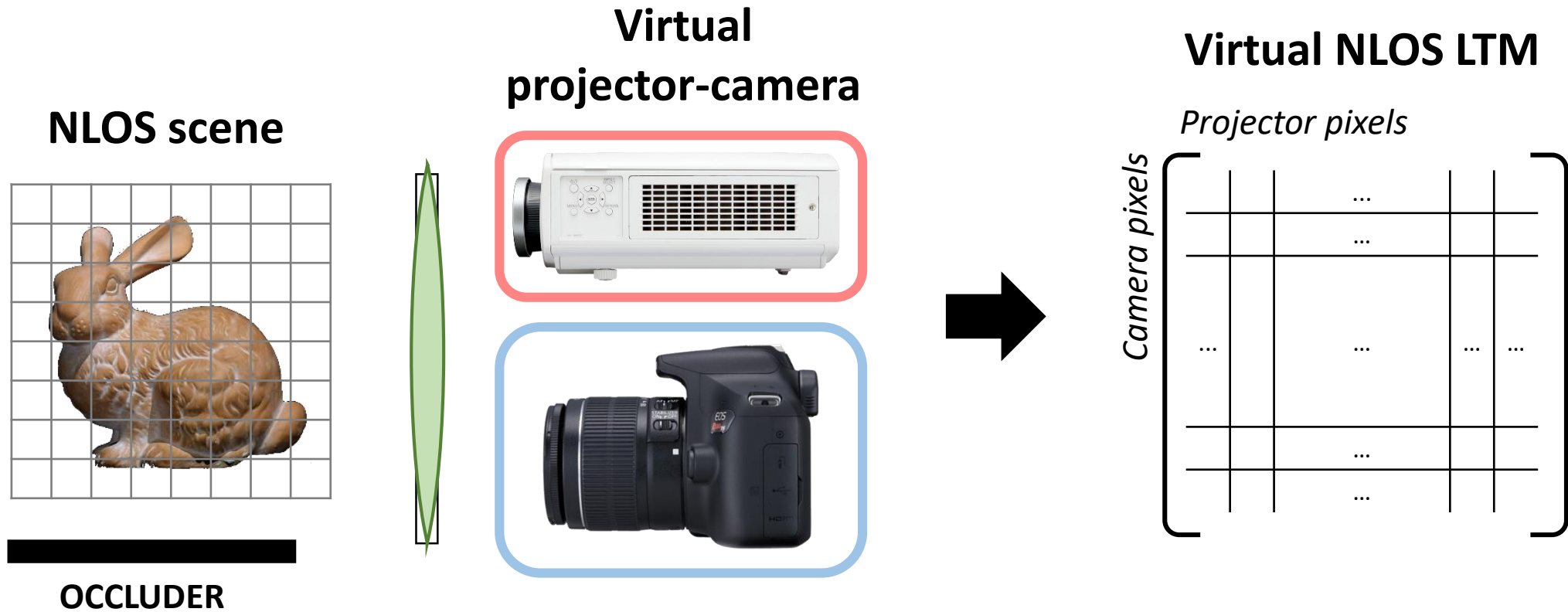


Virtual LTMs of hidden scenes

Phasor-field NLOS imaging

+

Light transport matrices

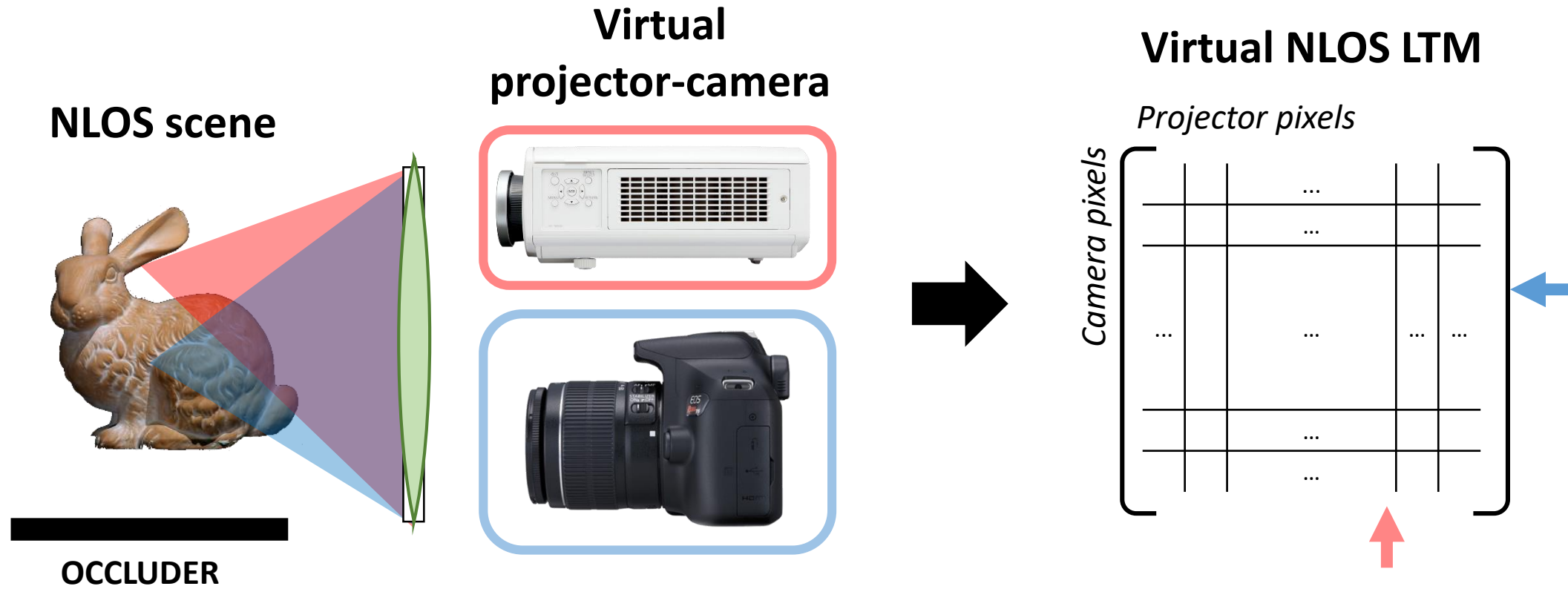


Virtual LTMs of hidden scenes

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Light transport matrices

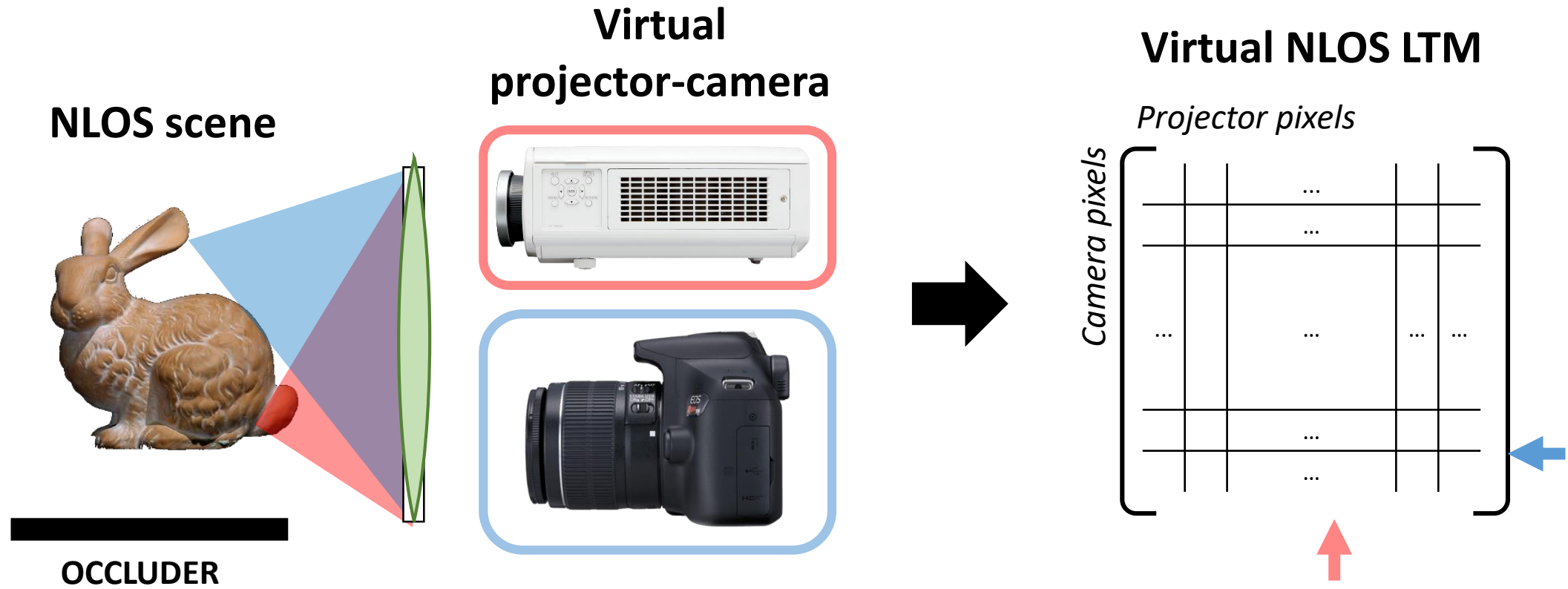


Virtual LTMs of hidden scenes

Phasor-field NLOS imaging



Light transport matrices



Virtual LTMs of hidden scenes

Phasor-field NLOS imaging

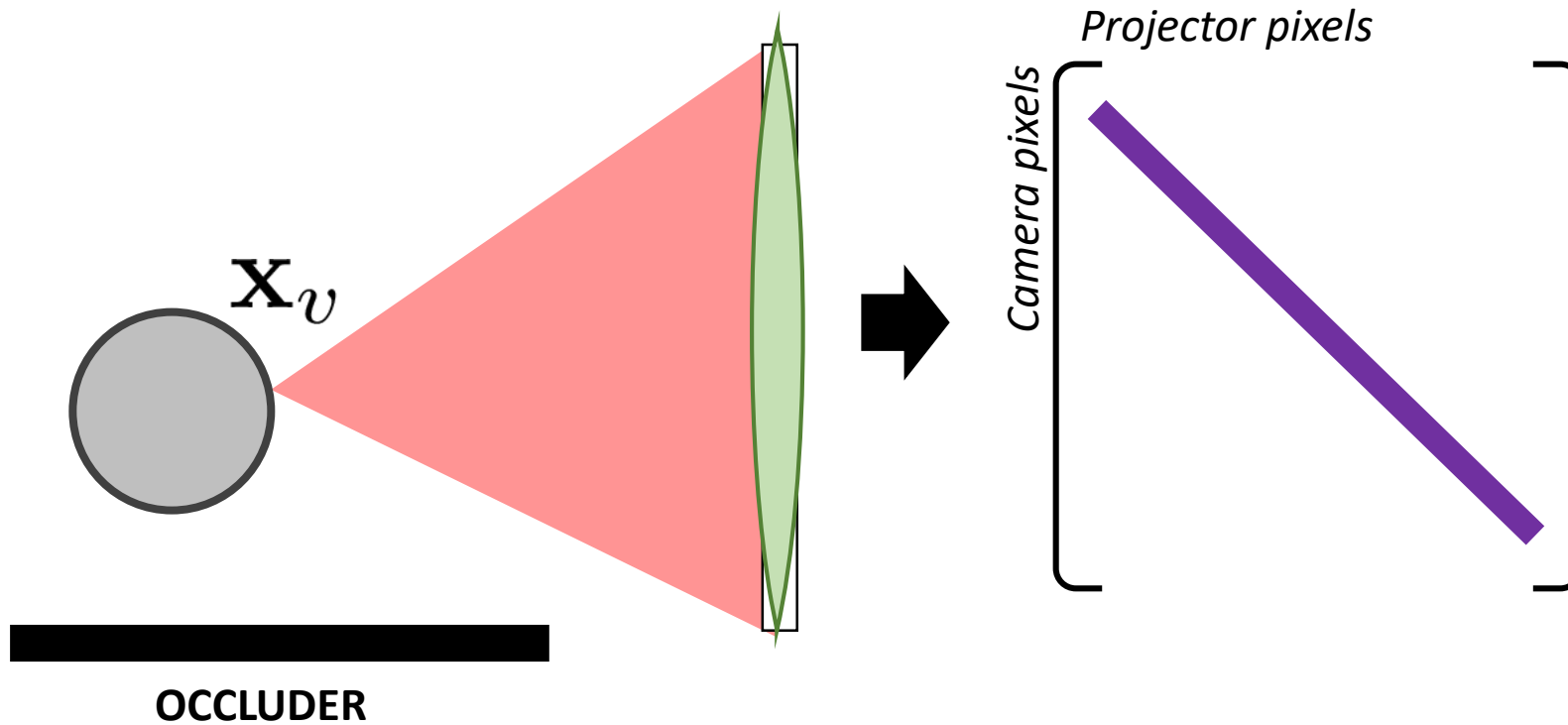
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Light transport matrices



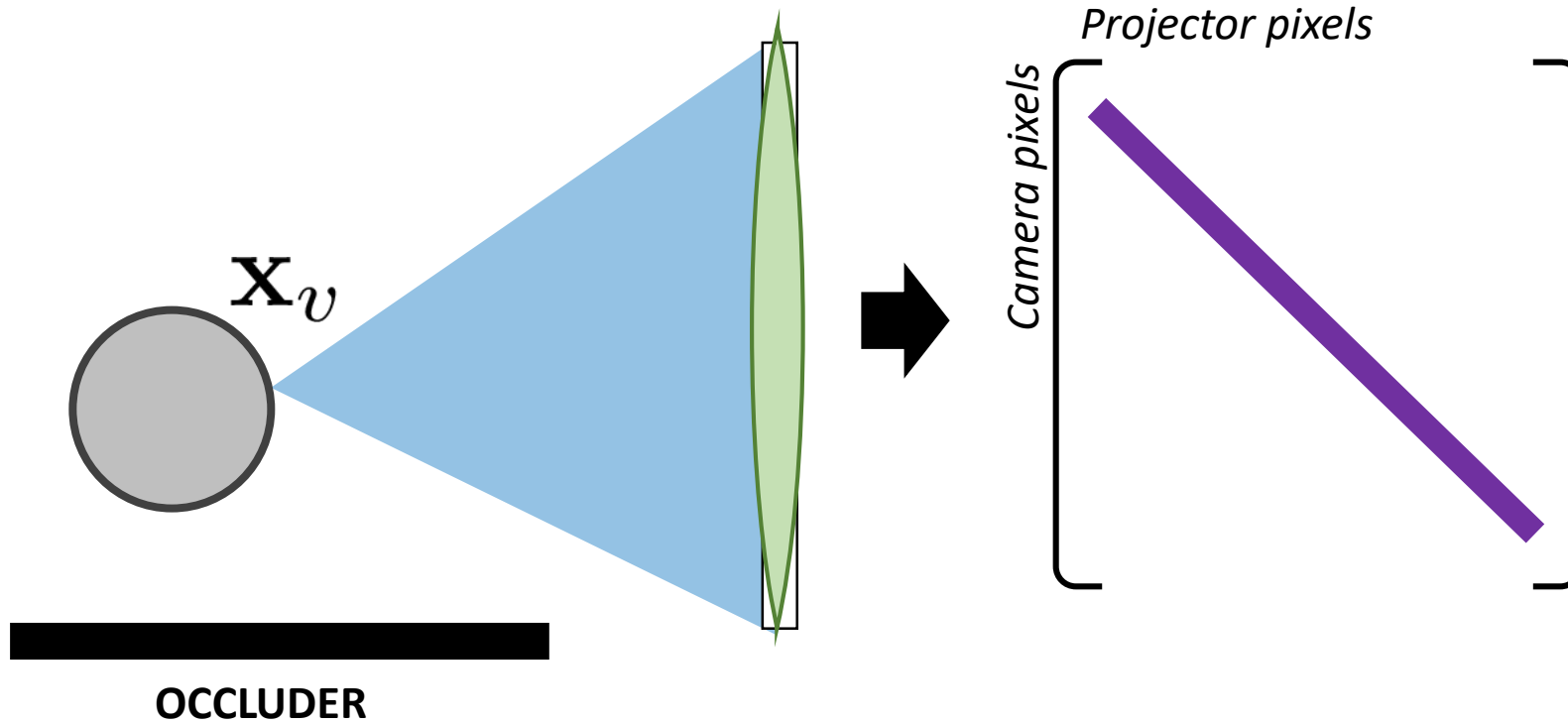
Virtual LTM computation

Diagonal: Confocal **projector** and **camera** pixels



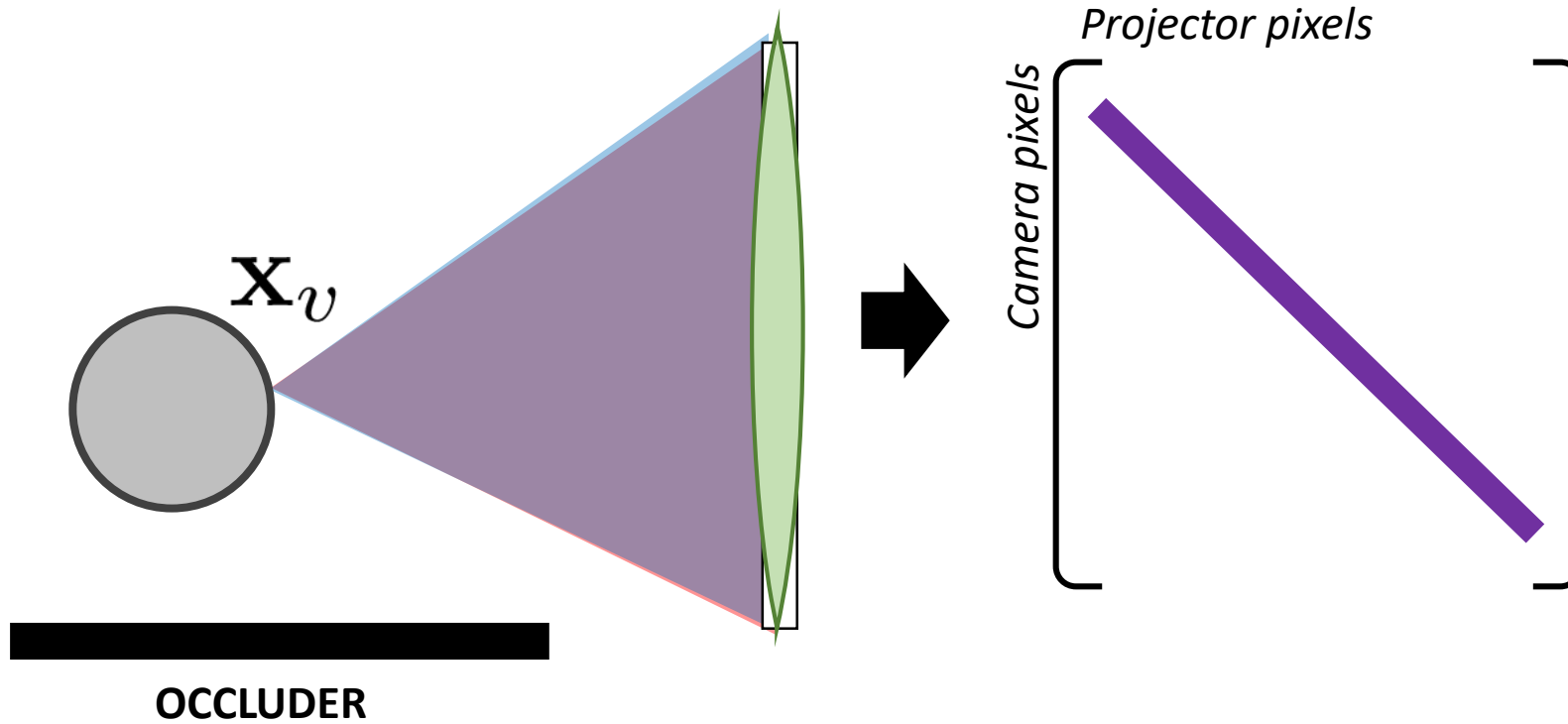
Virtual LTM computation

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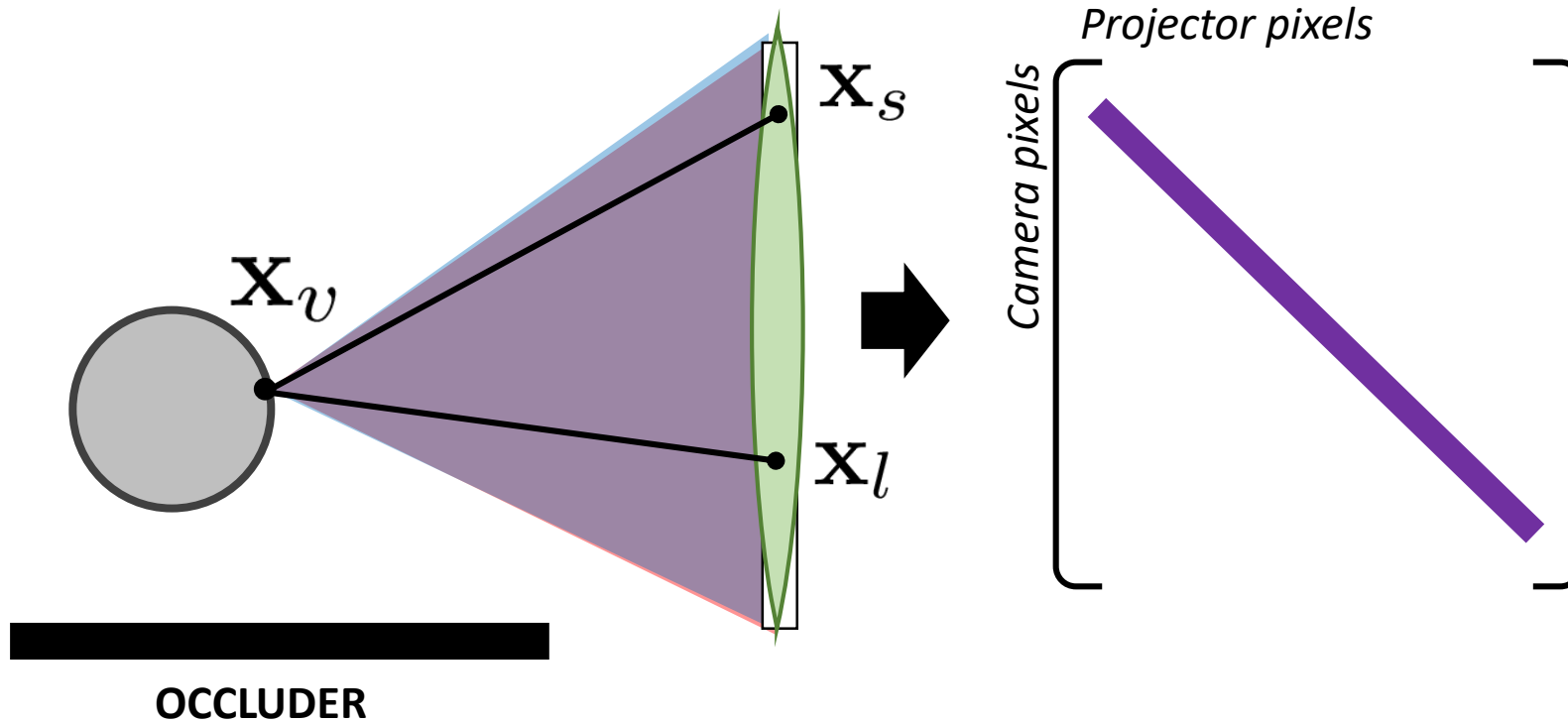
Virtual LTM computation

Diagonal: Confocal **projector** and **camera** pixels



Virtual LTM computation

Diagonal: Confocal **projector** and **camera** pixels



Shift phasor at

$$\langle \mathbf{x}_l, \mathbf{x}_s \rangle$$

Thin lens operators

LASER

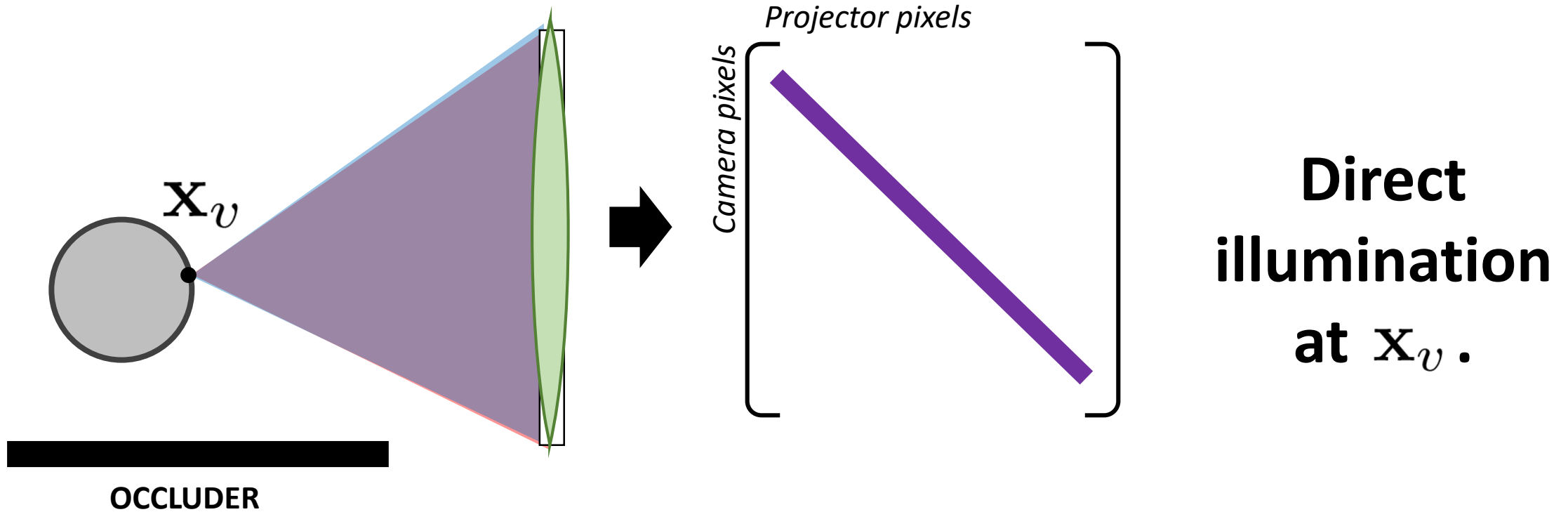
$$\frac{\mathcal{L}_\omega(\mathbf{x}_l, \mathbf{x}_v)}{|\mathbf{x}_l - \mathbf{x}_v|}$$

SPAD

$$\frac{\mathcal{L}_\omega(\mathbf{x}_s, \mathbf{x}_v)}{|\mathbf{x}_v - \mathbf{x}_s|}$$

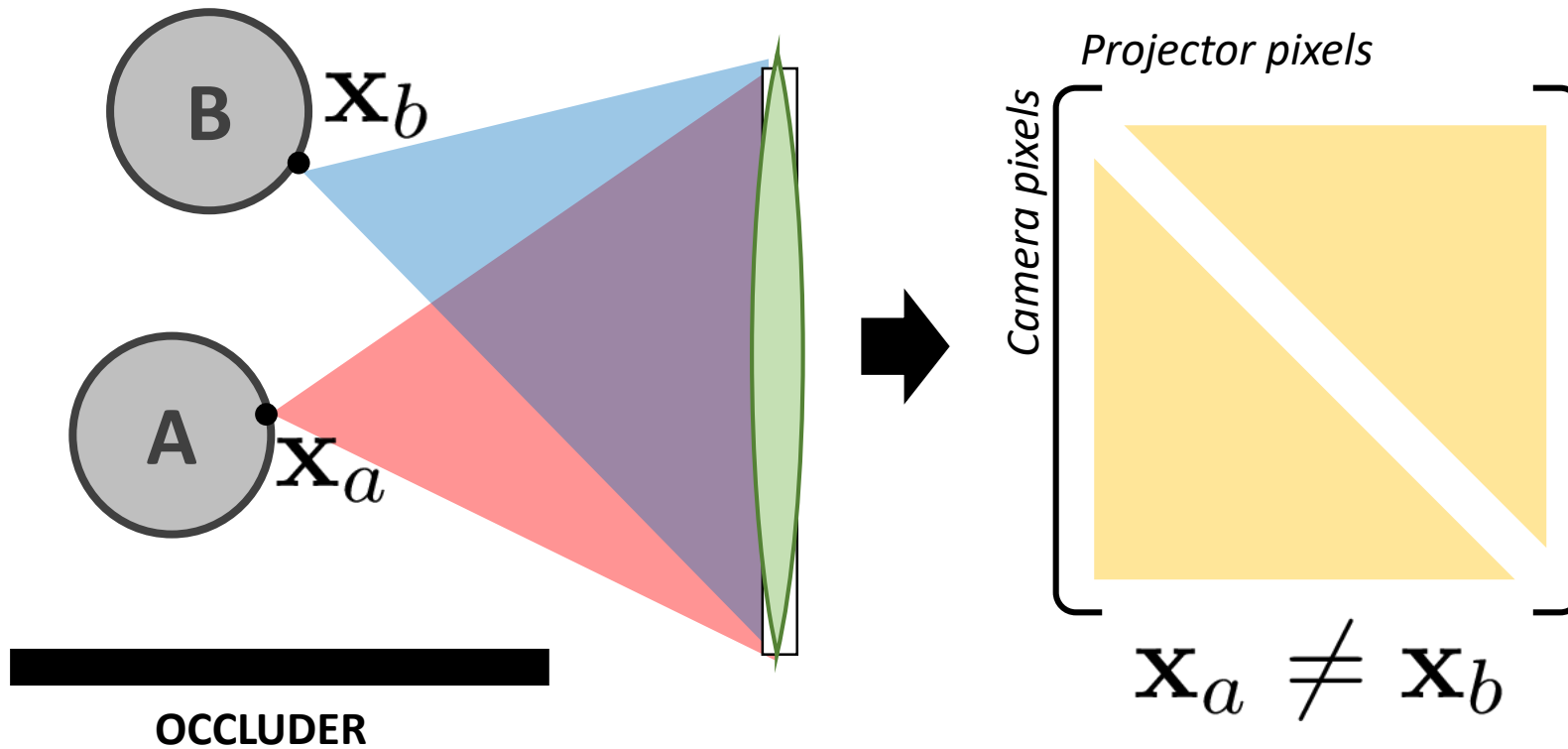
Virtual LTM computation

Diagonal: Confocal **projector** and **camera** pixels



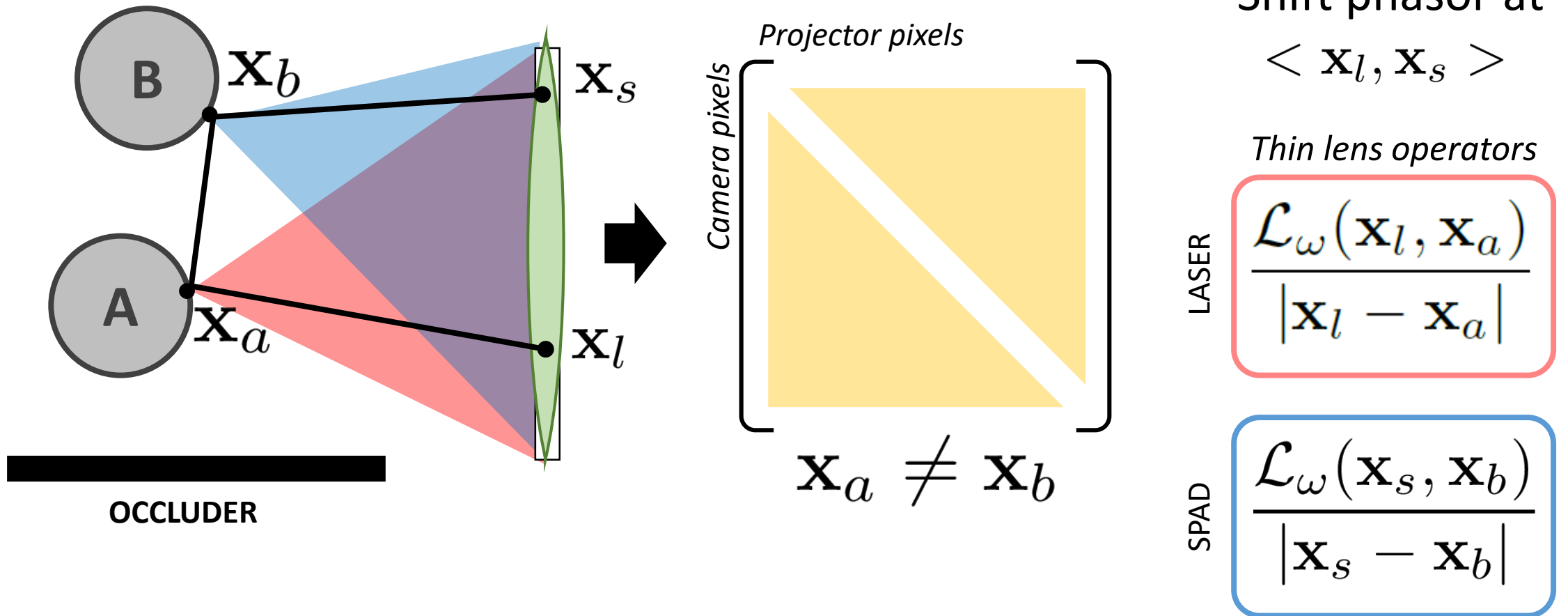
Virtual LTM computation

Off-diagonal: Different **projector** and **camera** pixels



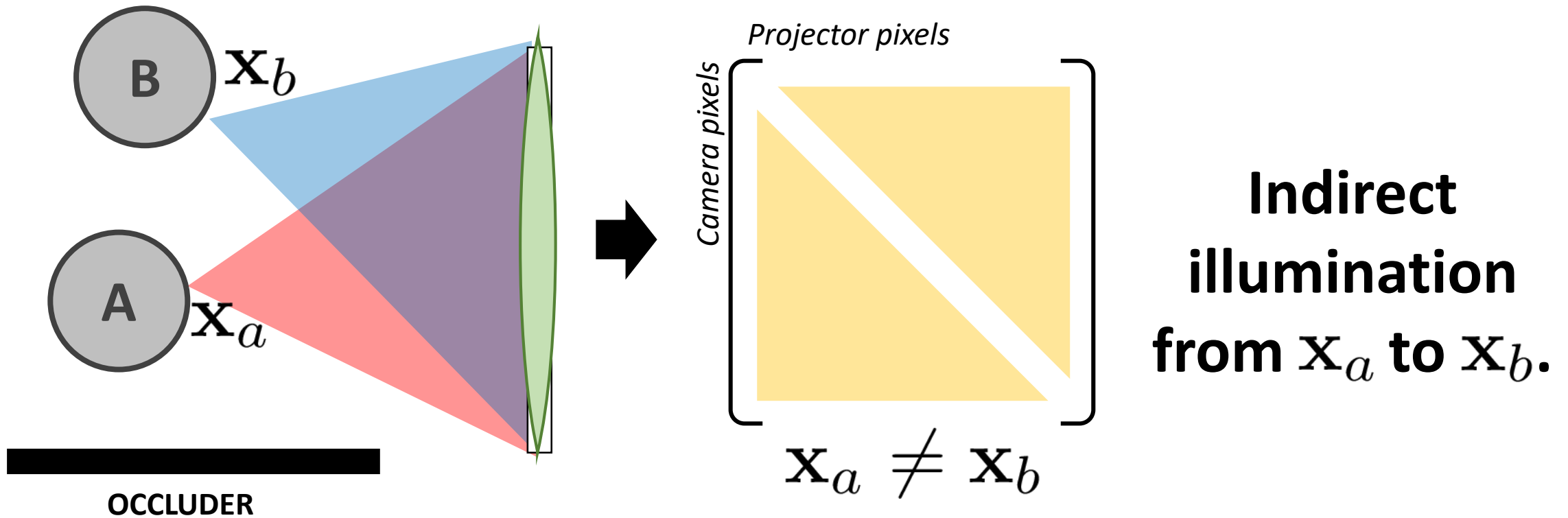
Virtual LTM computation

Off-diagonal: Different **projector** and **camera** pixels



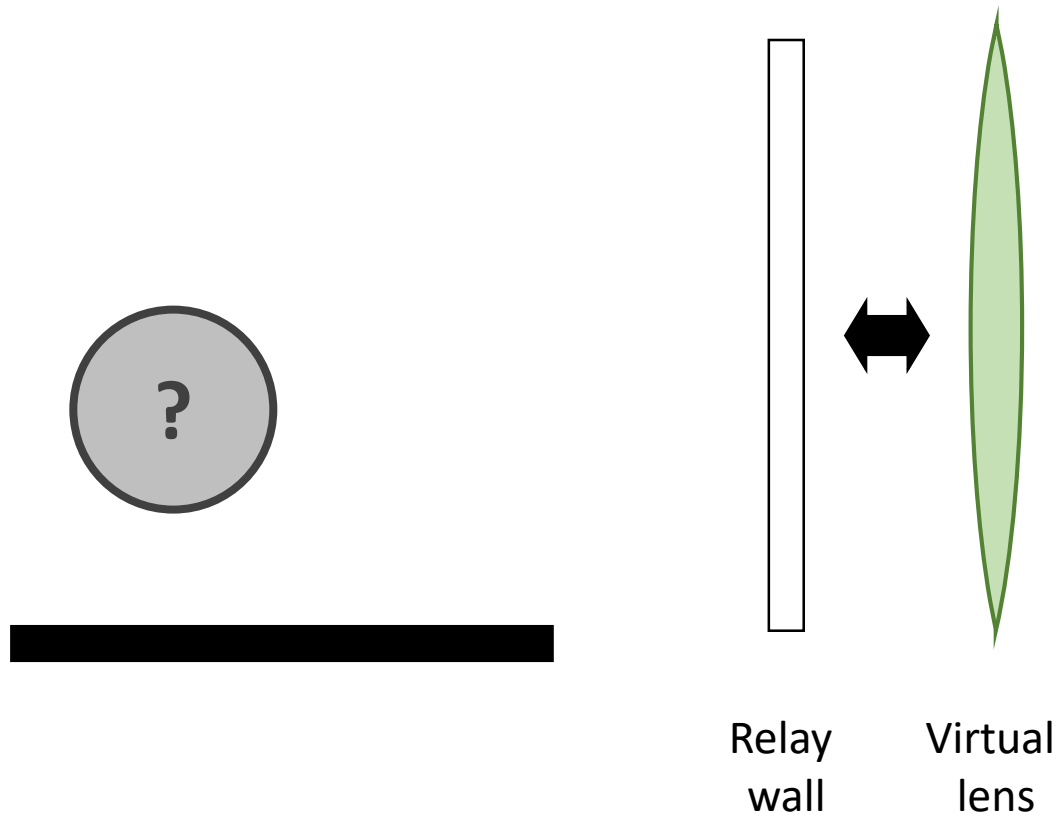
Virtual LTM computation

Off-diagonal: Different **projector** and **camera** pixels



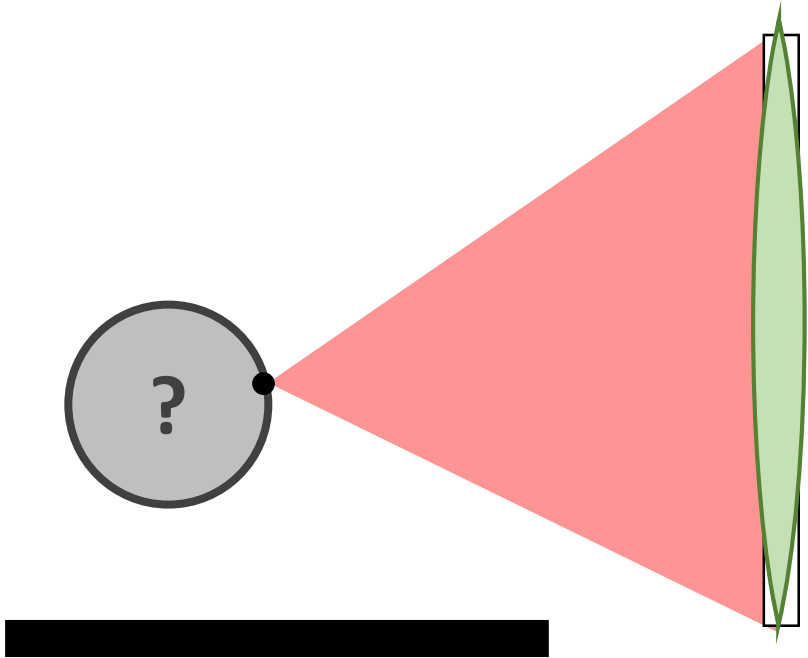
Virtual LTM: NLOS wide apertures

Size of relay wall = Size of lens aperture



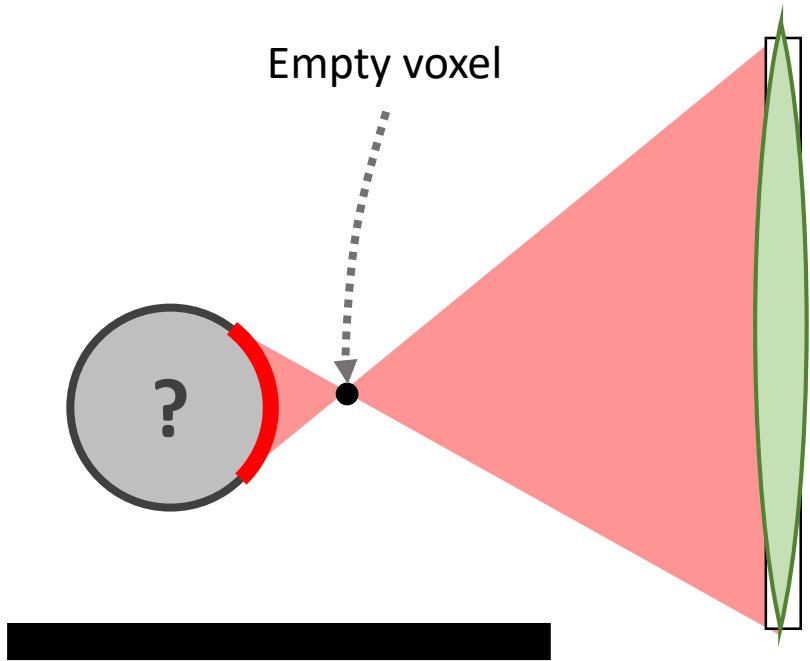
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Virtual LTM: NLOS wide apertures

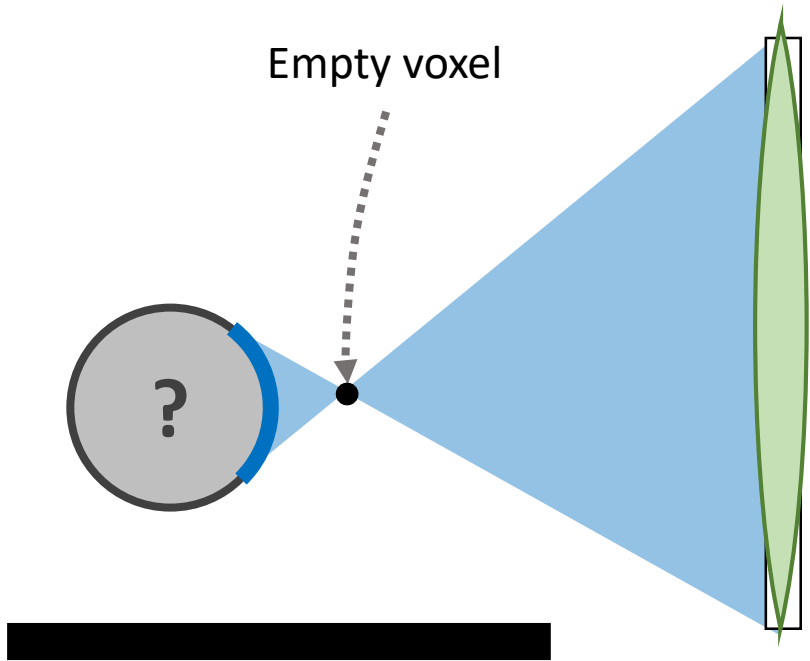
Size of relay wall = Size of lens aperture



Out of focus light:
- **Projector**

Virtual LTM: NLOS wide apertures

Size of relay wall = Size of lens aperture

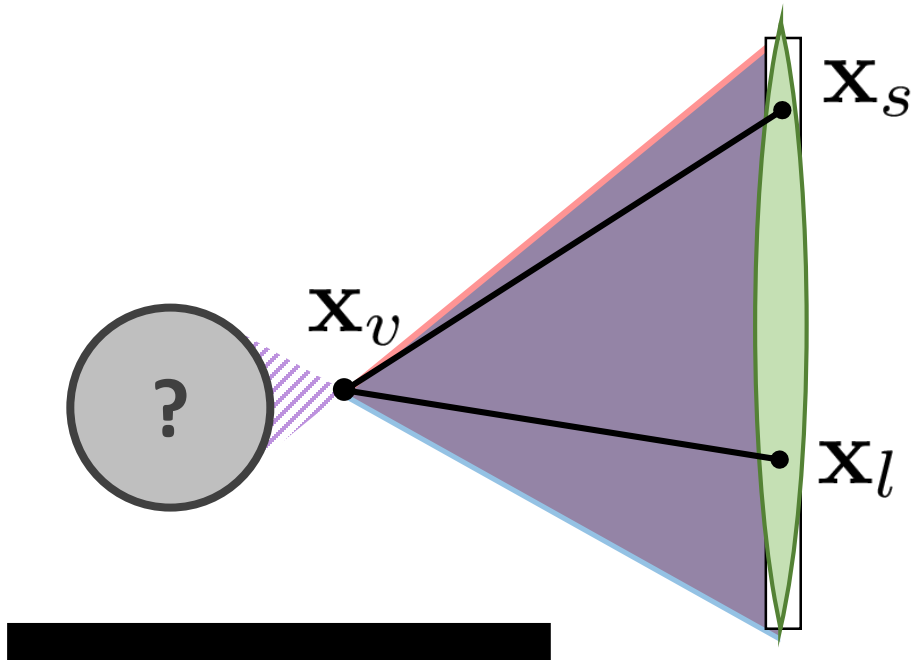


Out of focus light:

- **Projector**
- **Camera**

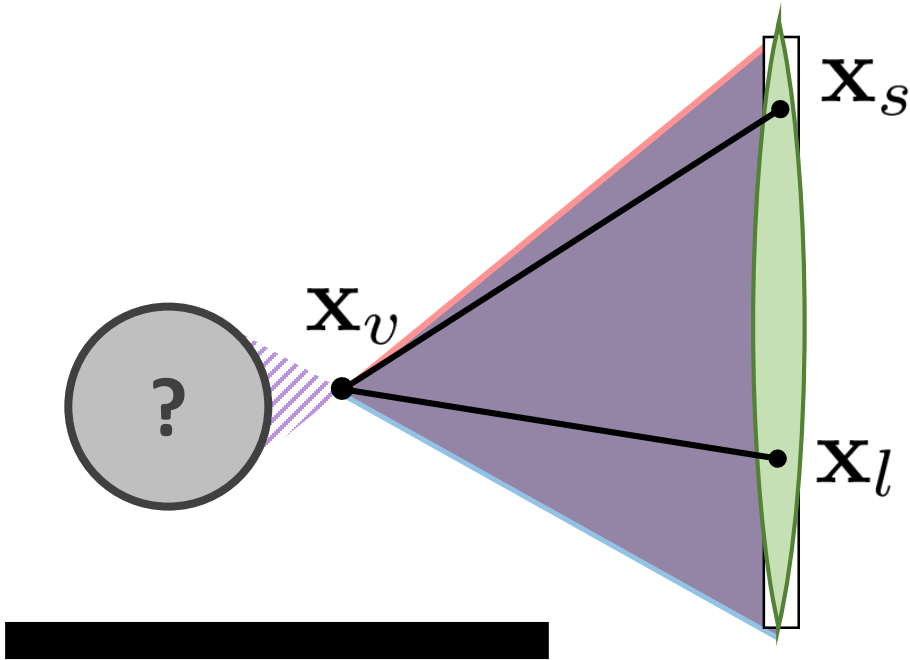
Virtual LTM: NLOS wide apertures

- Diagonal elements



Virtual LTM: NLOS wide apertures

- Diagonal elements



Gating single-bounce paths

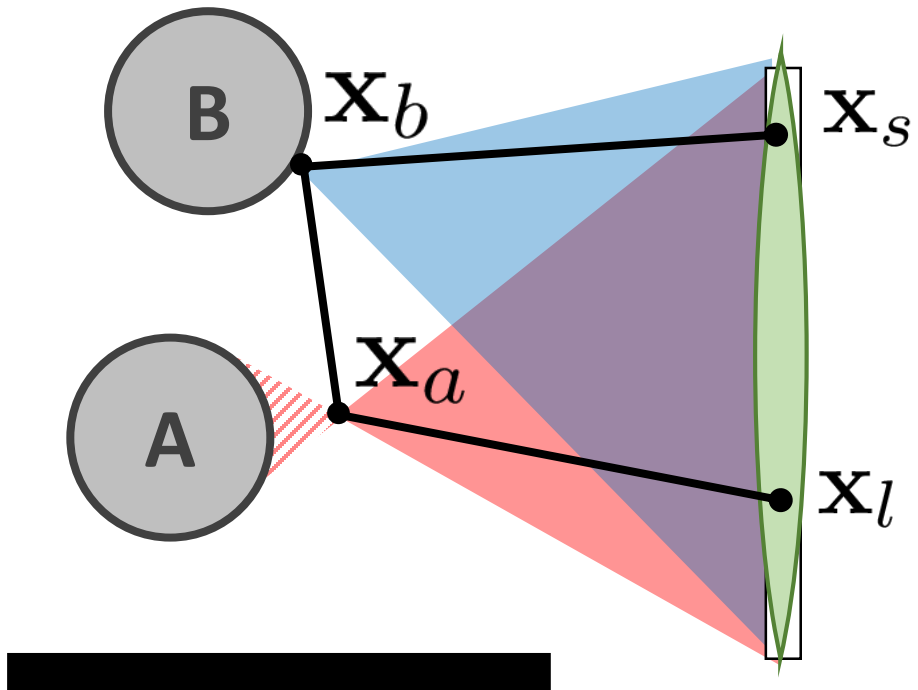
$$\mathbf{x}_l \rightarrow \mathbf{x}_v \rightarrow \mathbf{x}_s$$

at

$$t_d = \frac{|\mathbf{x}_l - \mathbf{x}_v| + |\mathbf{x}_s - \mathbf{x}_v|}{c}$$

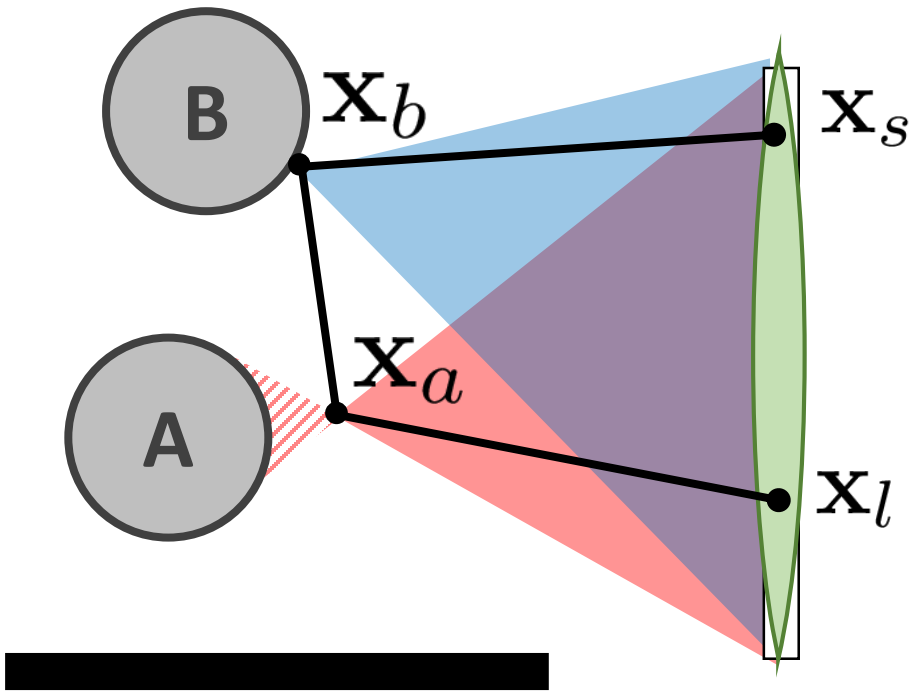
Virtual LTM: NLOS wide apertures

- Off-diagonal elements



Virtual LTM: NLOS wide apertures

- Off-diagonal elements

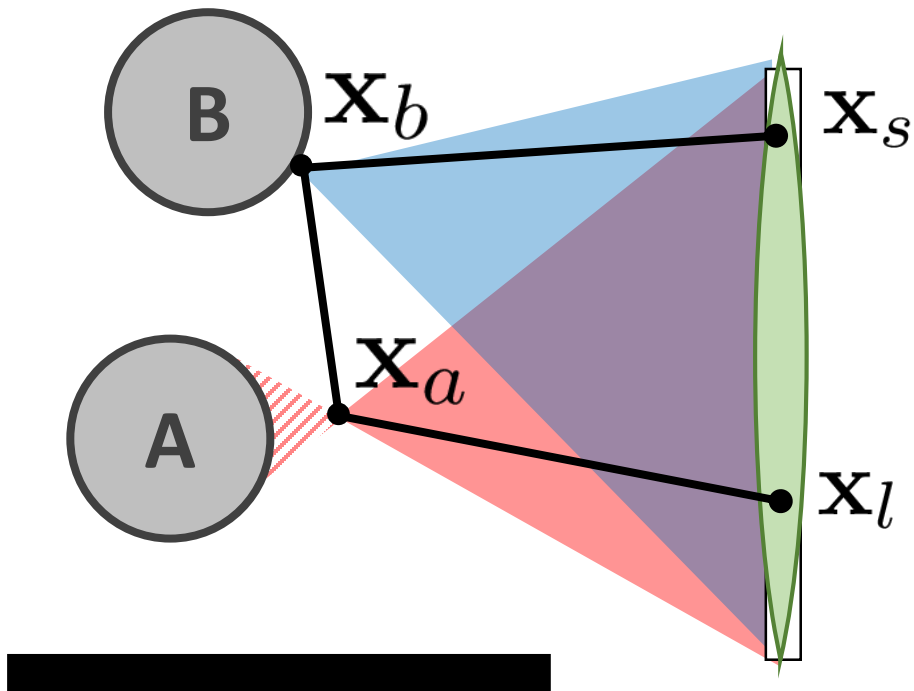


Gating two-bounce paths?

$$\mathbf{x}_l \rightarrow \mathbf{x}_a \rightarrow \mathbf{x}_b \rightarrow \mathbf{x}_s$$

Virtual LTM: NLOS wide apertures

- Off-diagonal elements



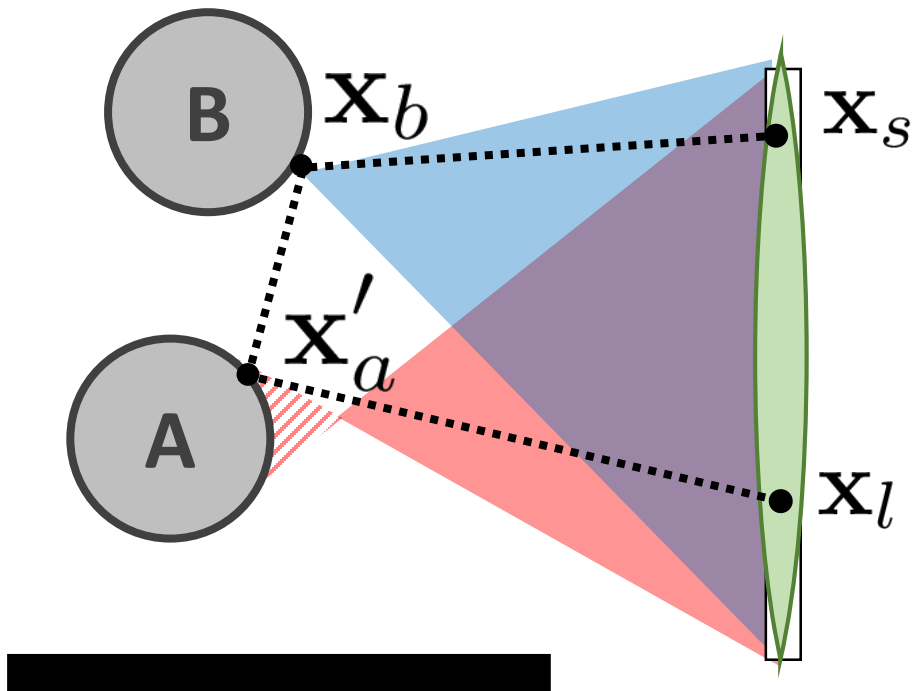
Gating two-bounce paths?

$$\mathbf{x}_l \rightarrow \mathbf{x}_a \rightarrow \mathbf{x}_b \rightarrow \mathbf{x}_s$$

But... out-of-focus paths of same length

Virtual LTM: NLOS wide apertures

- Off-diagonal elements



Gating two-bounce paths?

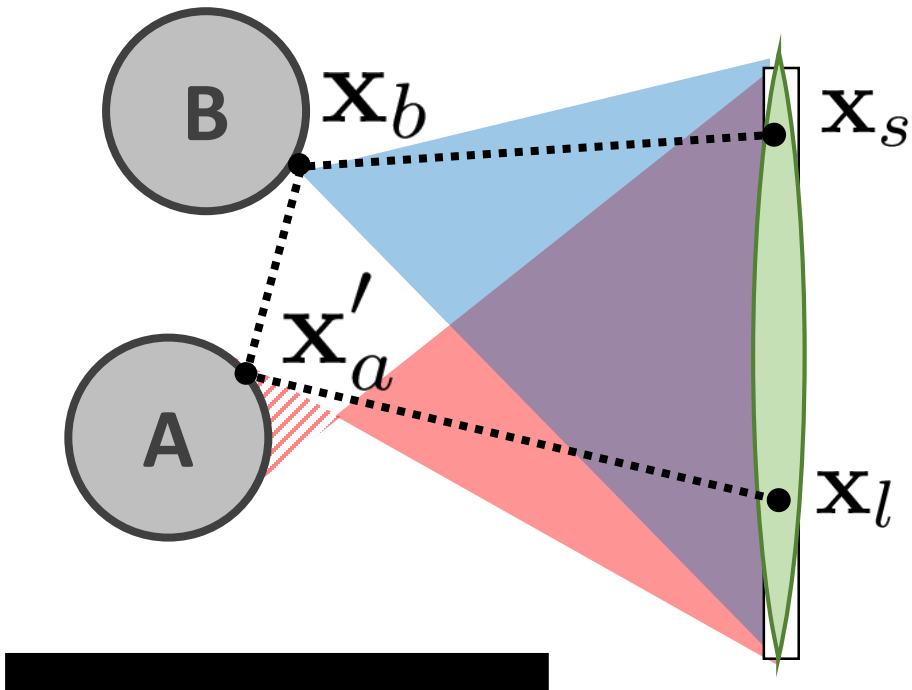
$$\mathbf{x}_l \rightarrow \mathbf{x}_a \rightarrow \mathbf{x}_b \rightarrow \mathbf{x}_s$$

But... out-of-focus paths of same length

$$\mathbf{x}_l \rightarrow \mathbf{x}'_a \rightarrow \mathbf{x}_b \rightarrow \mathbf{x}_s$$

Virtual LTM: NLOS wide apertures

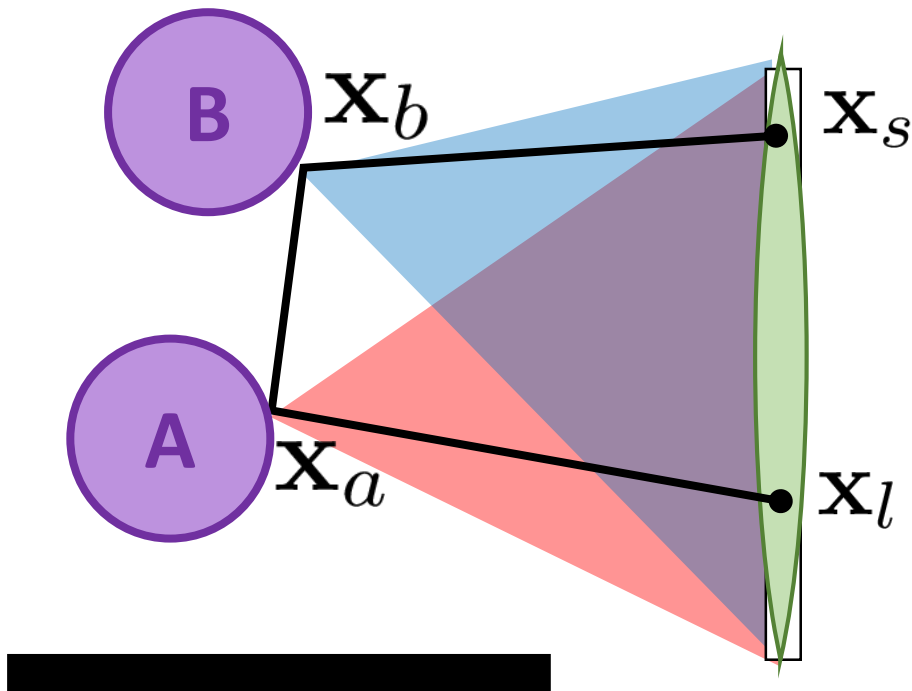
- Off-diagonal elements

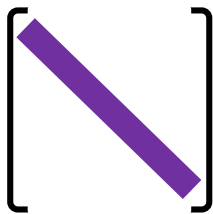


Diagonal $\left[\begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \end{array} \right] \approx \text{Geometry}$

Virtual LTM: NLOS wide apertures

- Off-diagonal elements



Diagonal  \approx Geometry

- Focus only at non-empty voxels

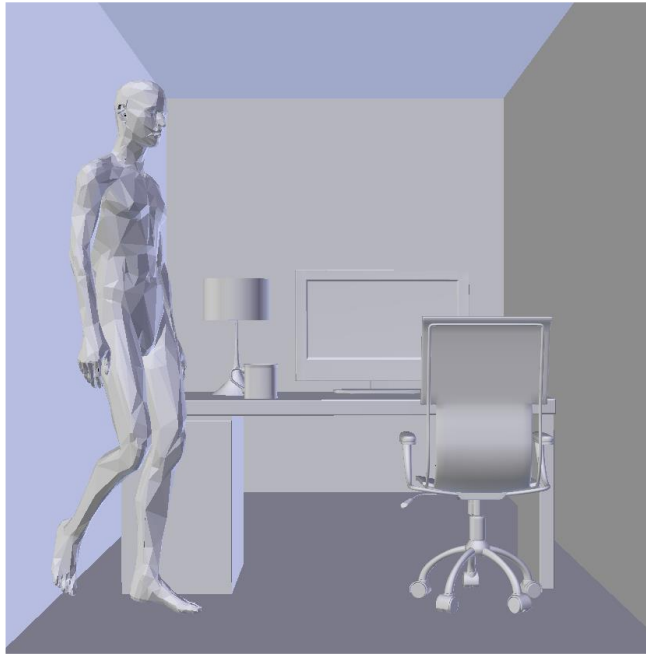
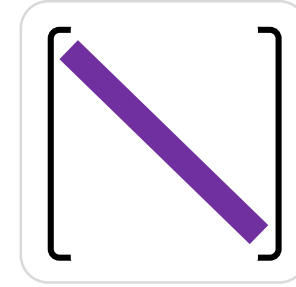
- Gate two-bounce paths:

$$t_i = \frac{|\mathbf{x}_l - \mathbf{x}_a| + |\mathbf{x}_a - \mathbf{x}_b| + |\mathbf{x}_s - \mathbf{x}_b|}{c}$$

Results: Direct illumination

- Diagonal computation and gating

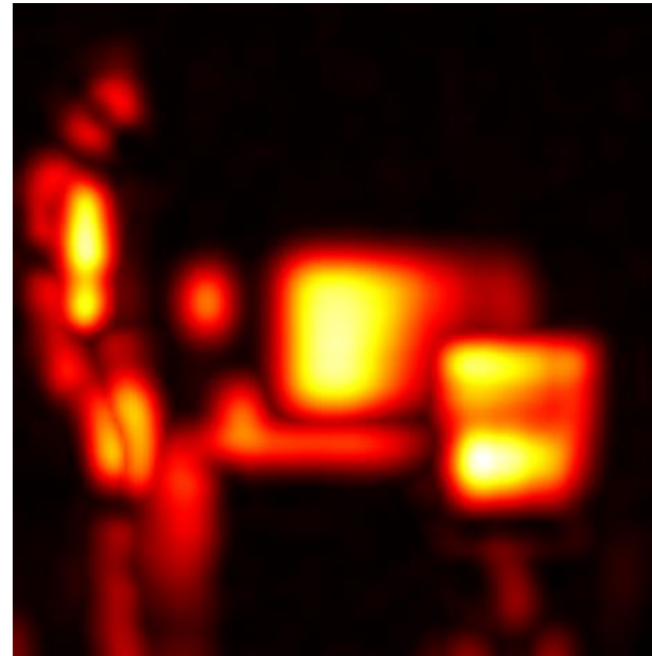
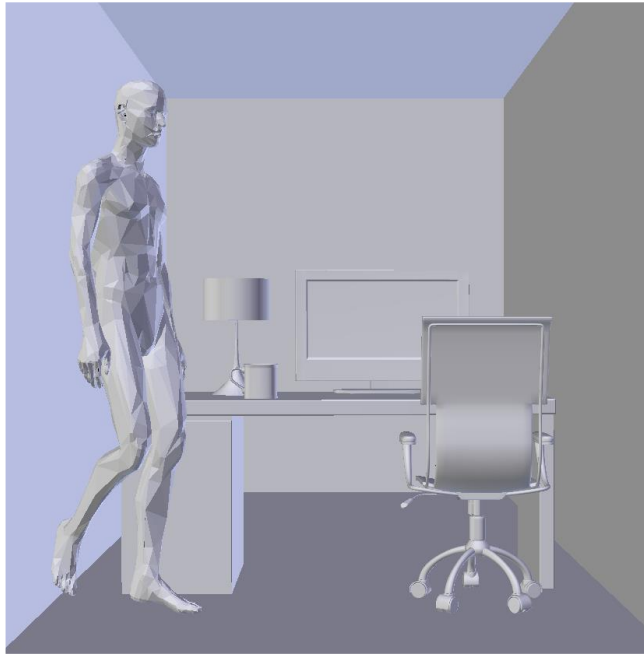
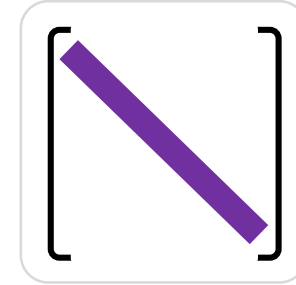
LTM diagonal



Results: Direct illumination

- Diagonal computation and gating

LTM diagonal

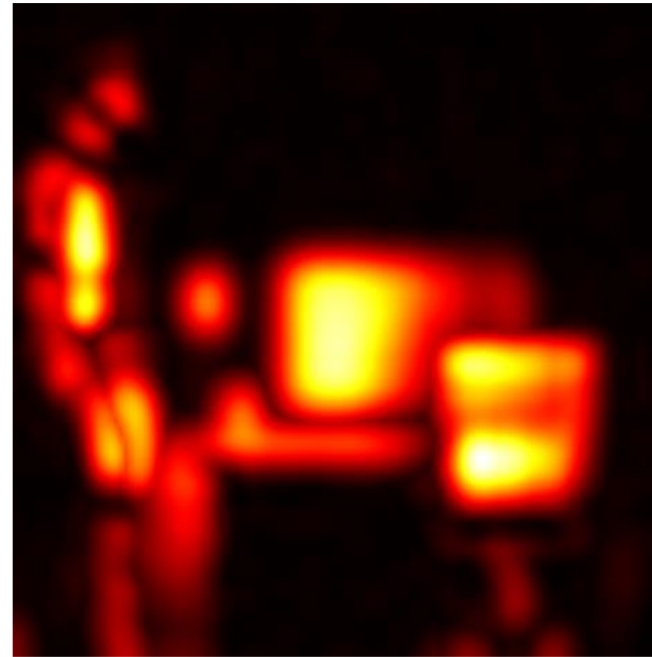
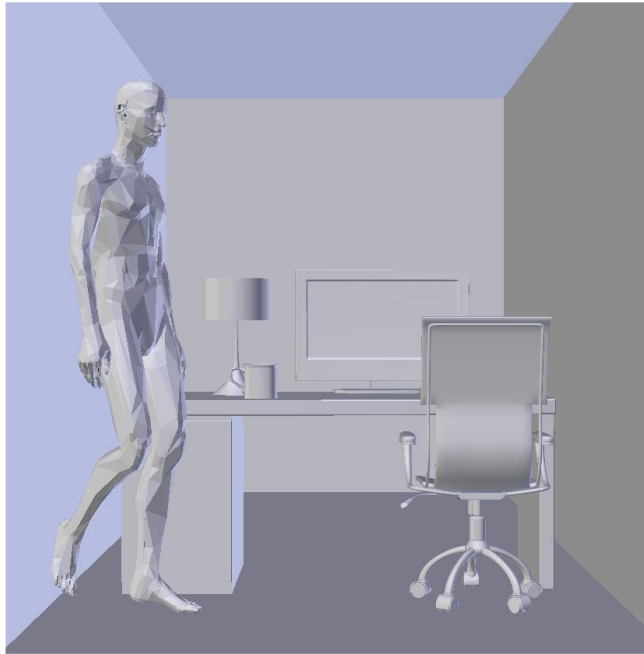
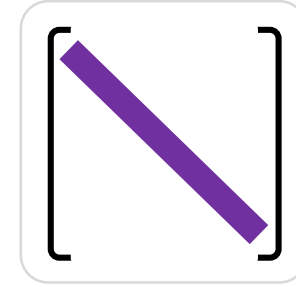


Single-bounce gating

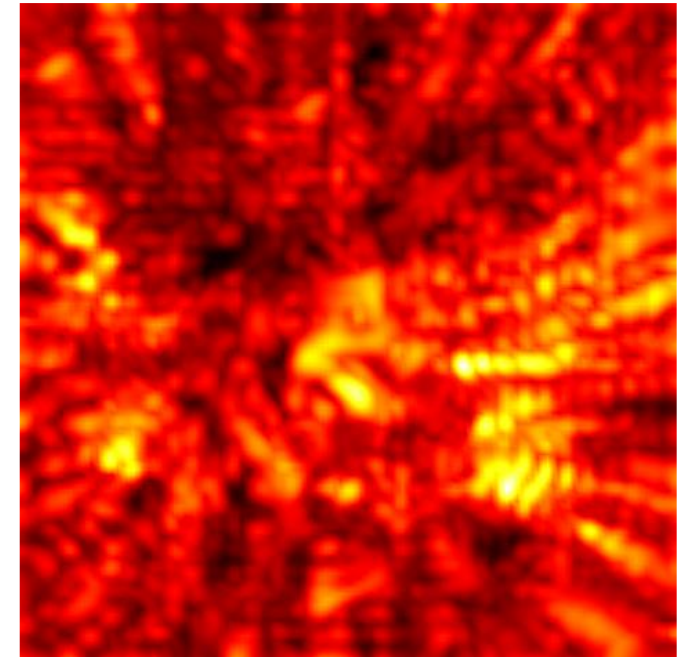
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LTM diagonal



Single-bounce gating

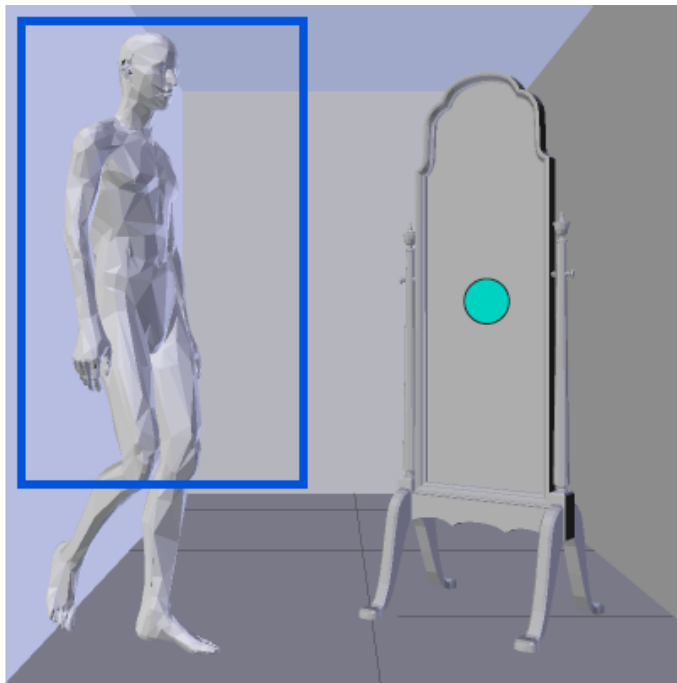
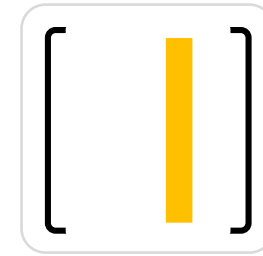


No gating

Results: Indirect illumination

- Off-diagonal under material changes

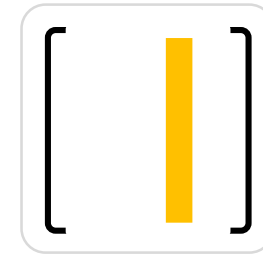
LTM off-diagonal at ●



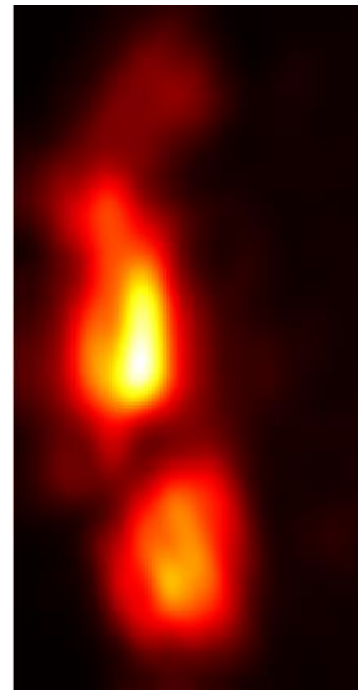
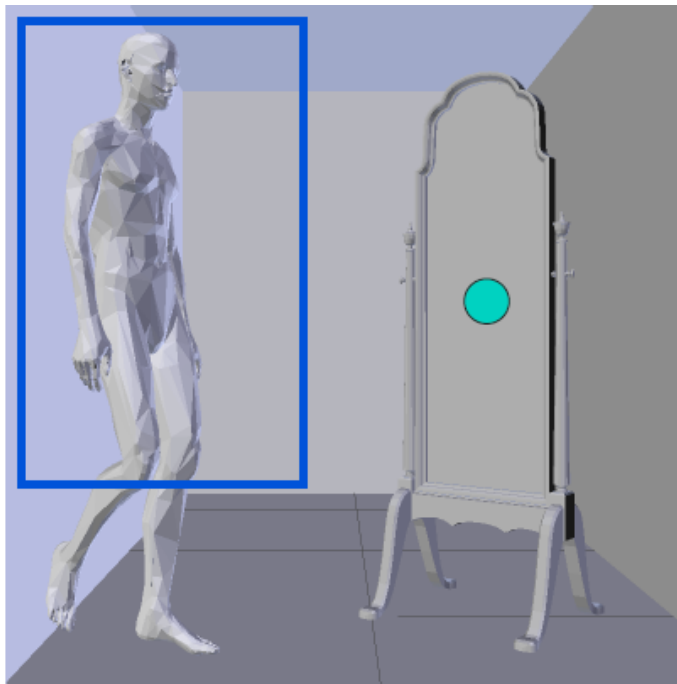
Results: Indirect illumination

- Off-diagonal under material changes

LTM off-diagonal at 



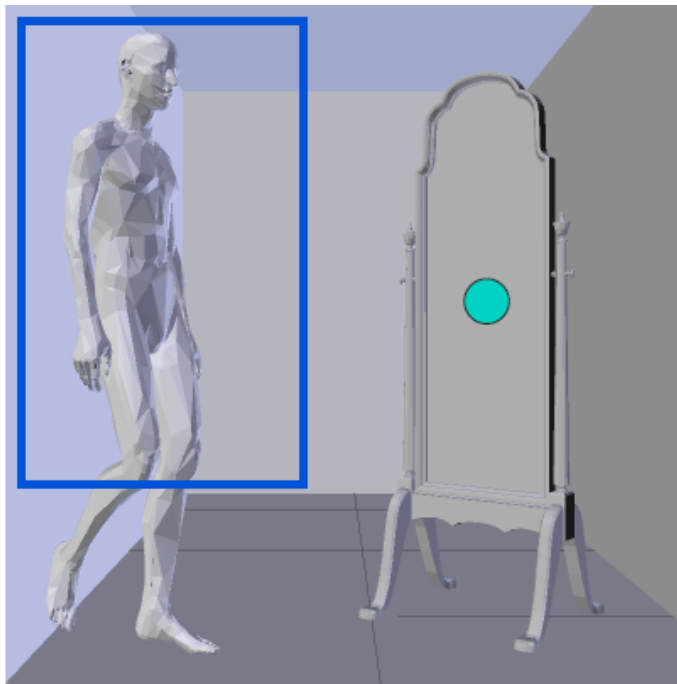
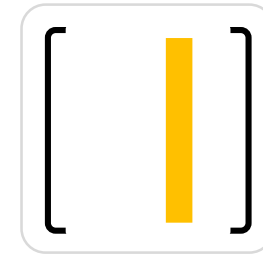
Low reflector specularity



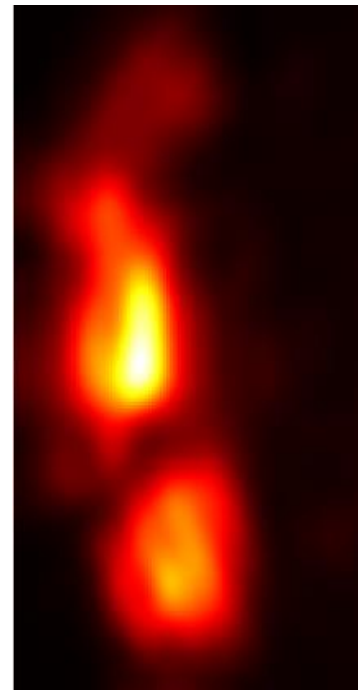
Results: Indirect illumination

- Off-diagonal under material changes

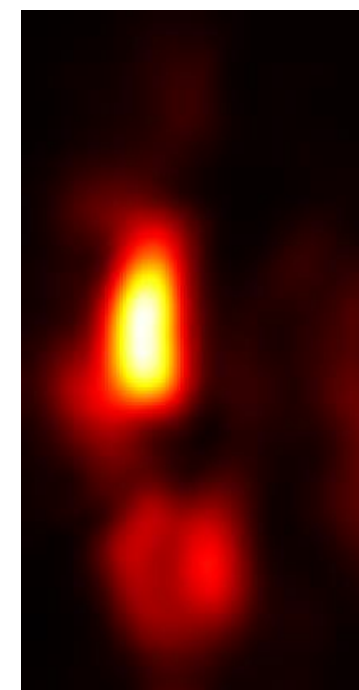
LTM off-diagonal at 



Low reflector specularity

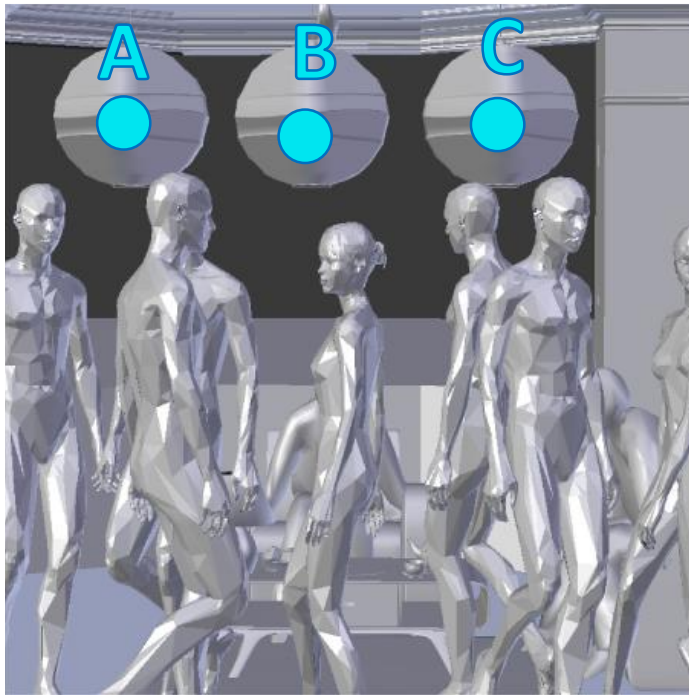


High reflector specularity

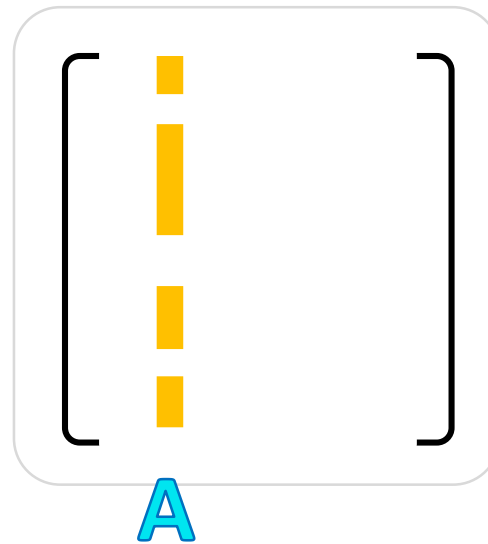


Results: LTM probing

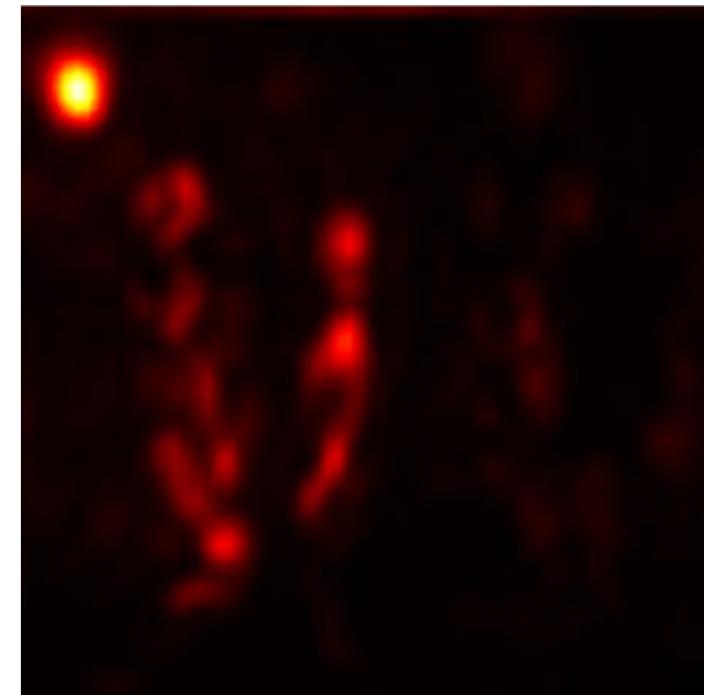
- Off-diagonal, indirect light



LTM off-diagonal

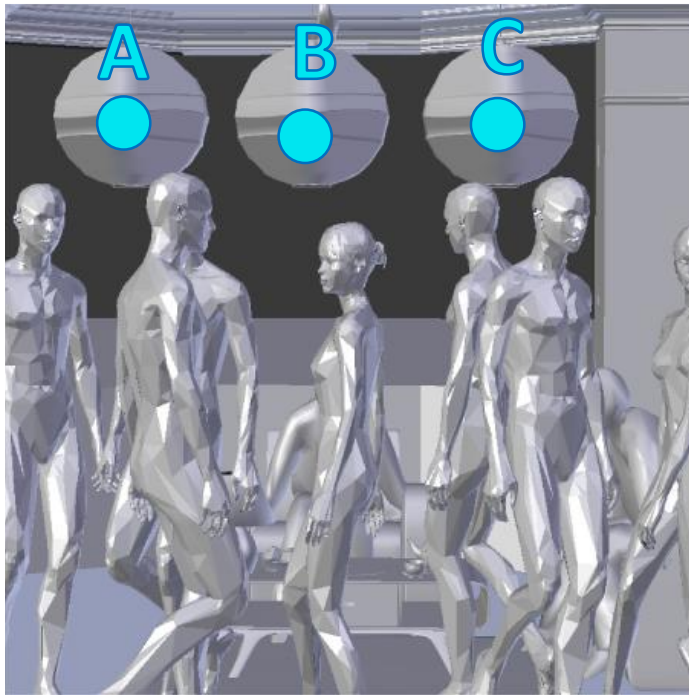


A

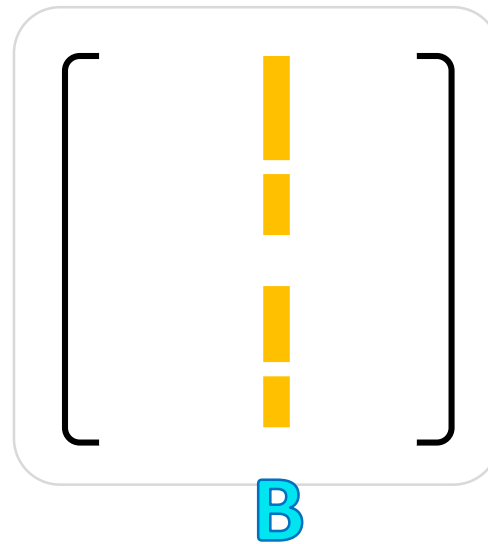


Results: LTM probing

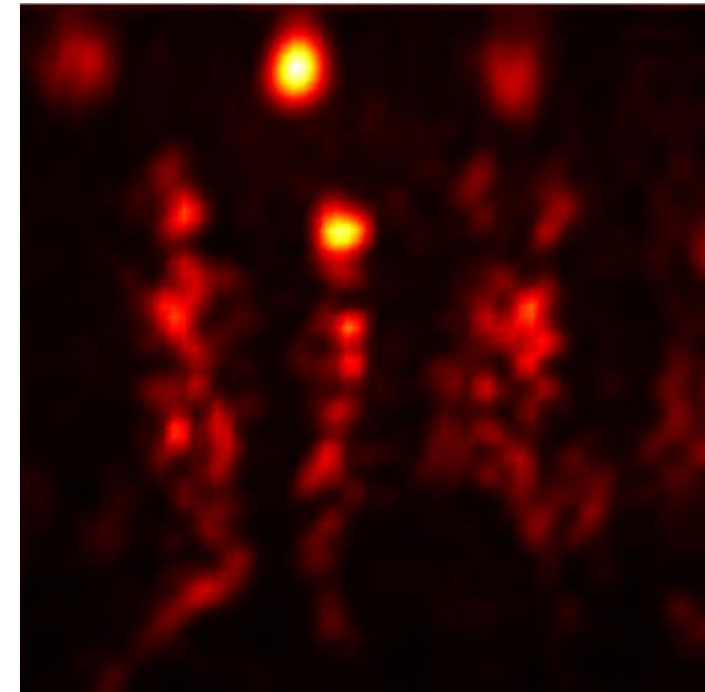
- Off-diagonal, indirect light



LTM off-diagonal

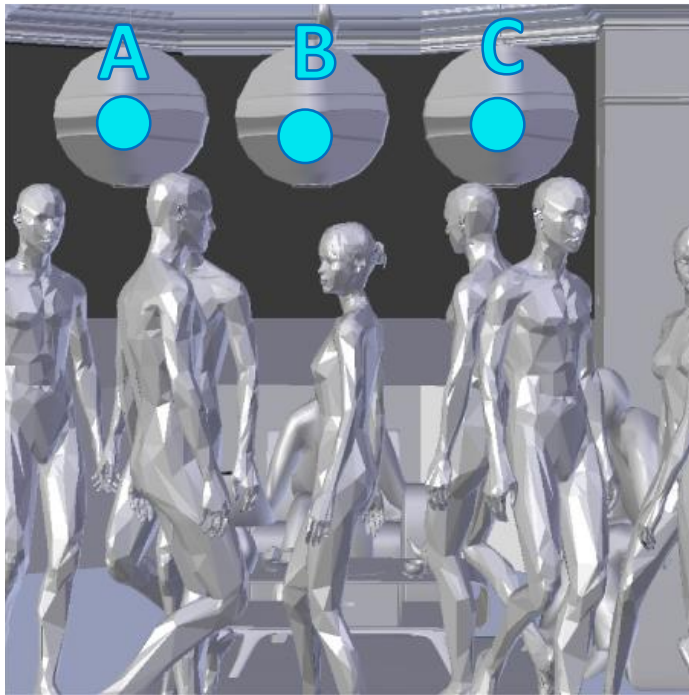


B

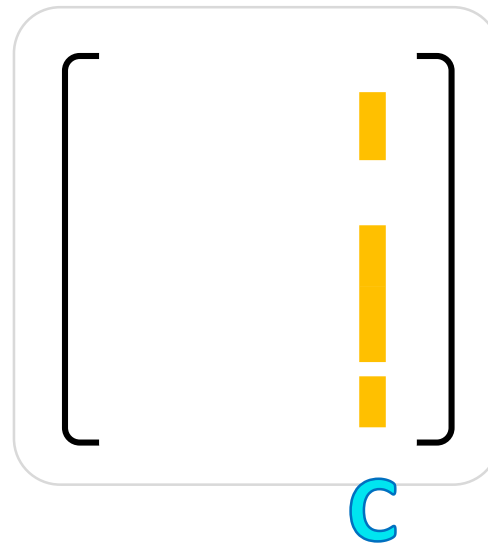


Results: LTM probing

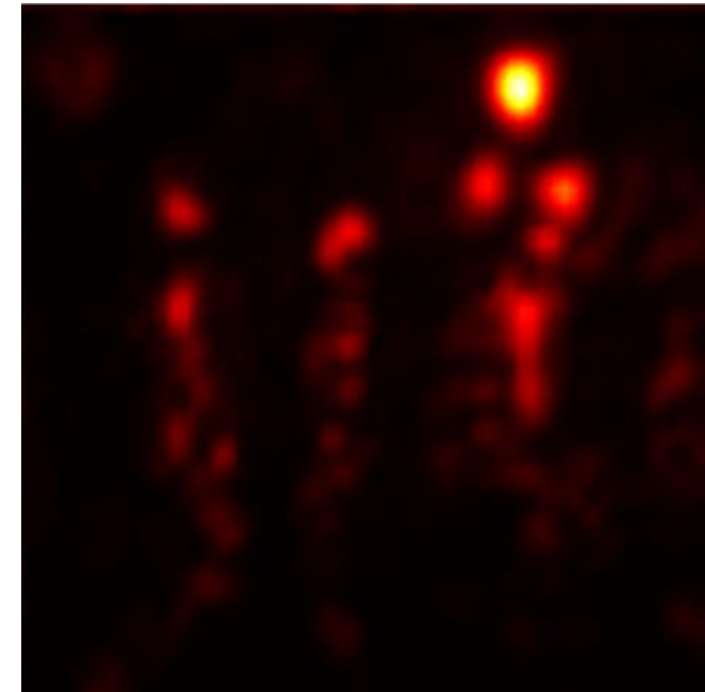
- Off-diagonal, indirect light



LTM off-diagonal

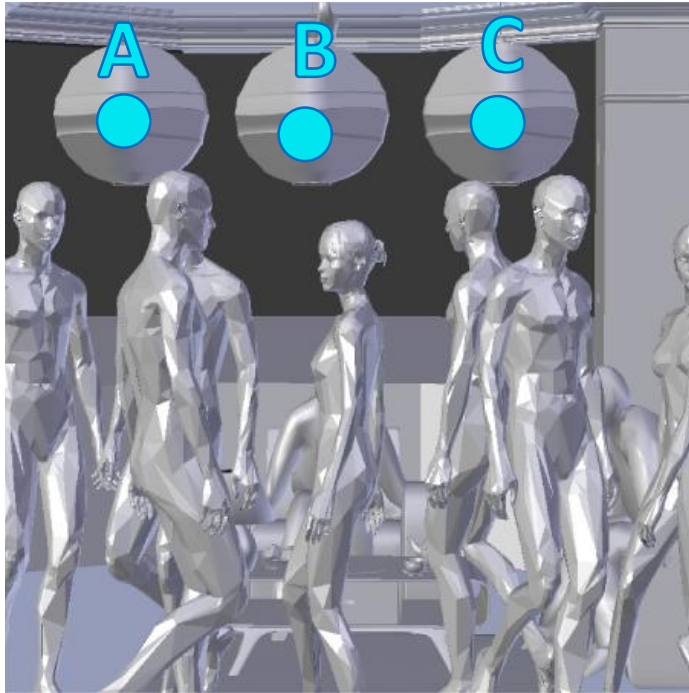


C

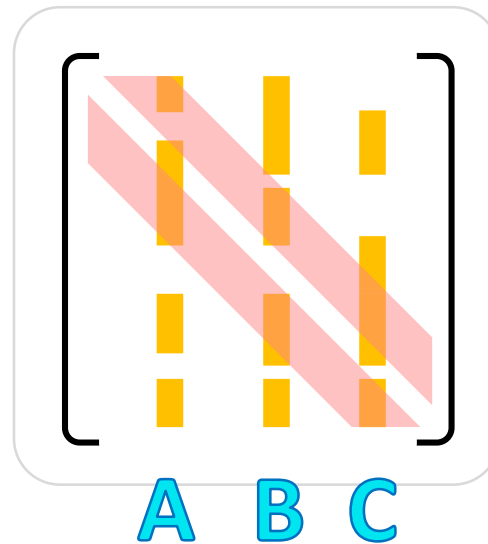


Results: LTM probing

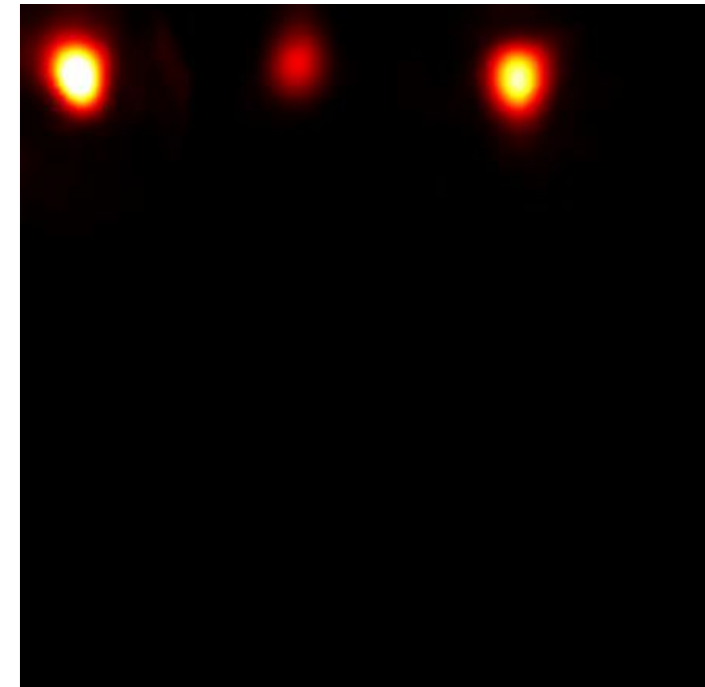
- Off-diagonal, near-range



LTM off-diagonal



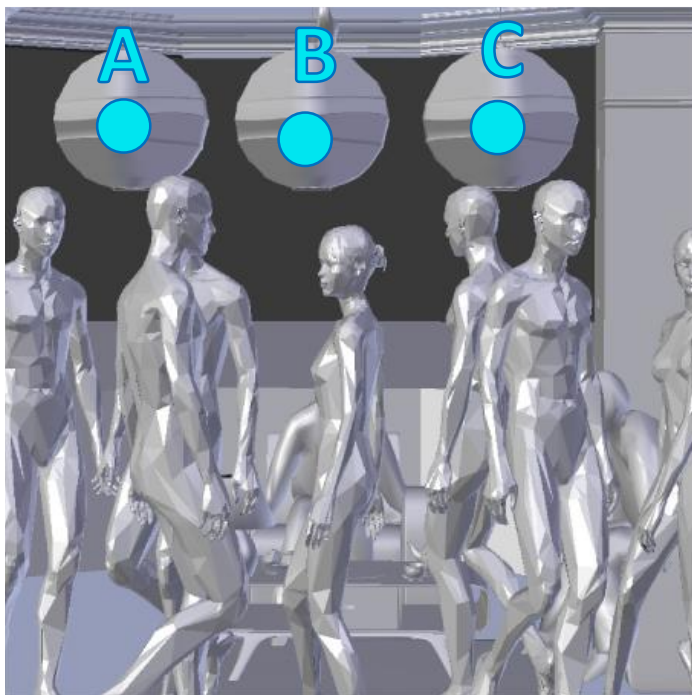
A, B, C



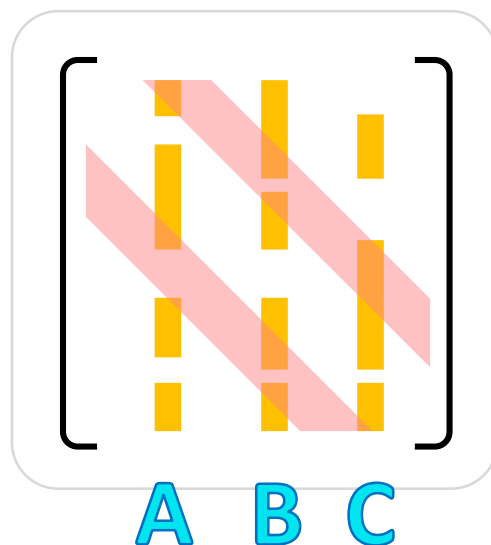
0.1m to 0.4m

Results: LTM probing

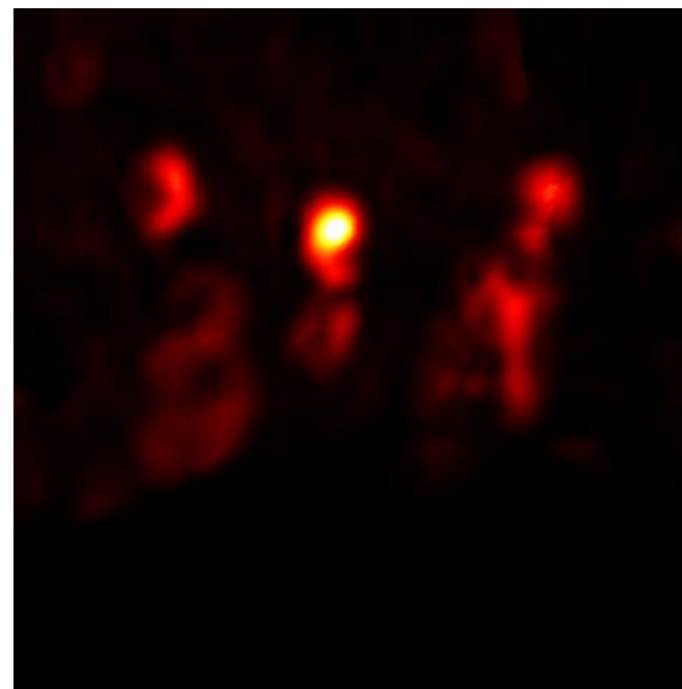
- Off-diagonal, mid-range



LTM off-diagonal



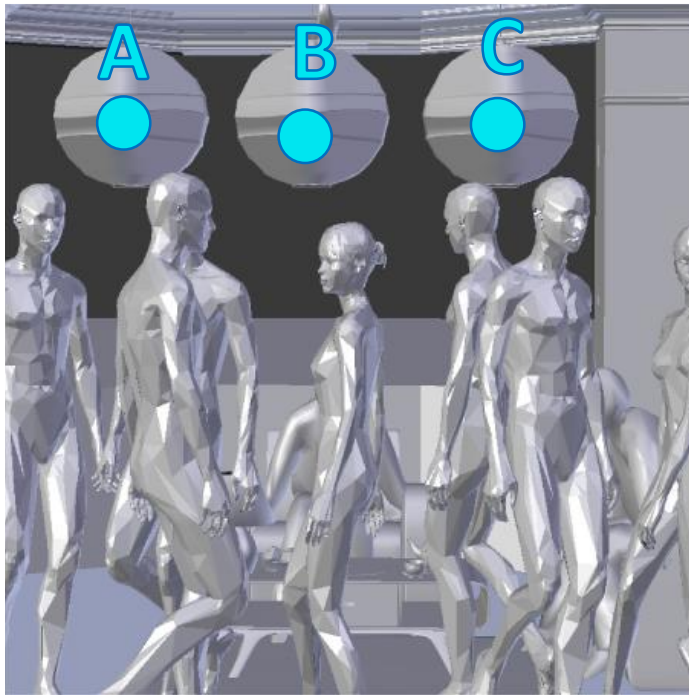
A, B, C



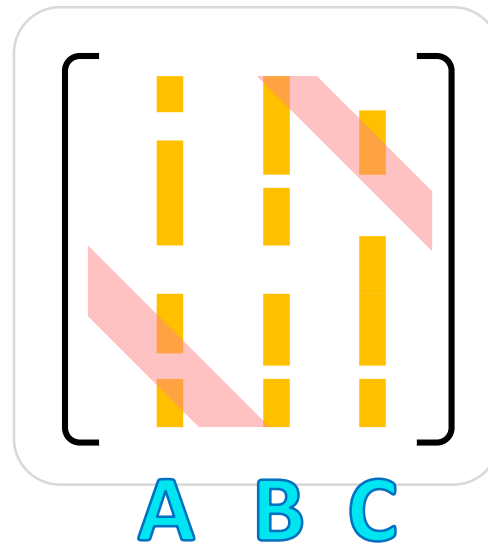
1.1m to 1.4m

Results: LTM probing

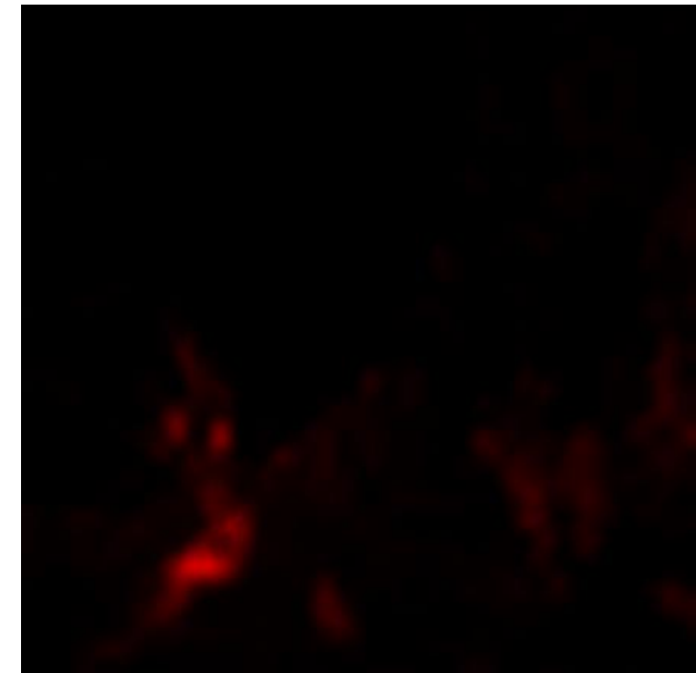
- Off-diagonal, far-range



LTM off-diagonal



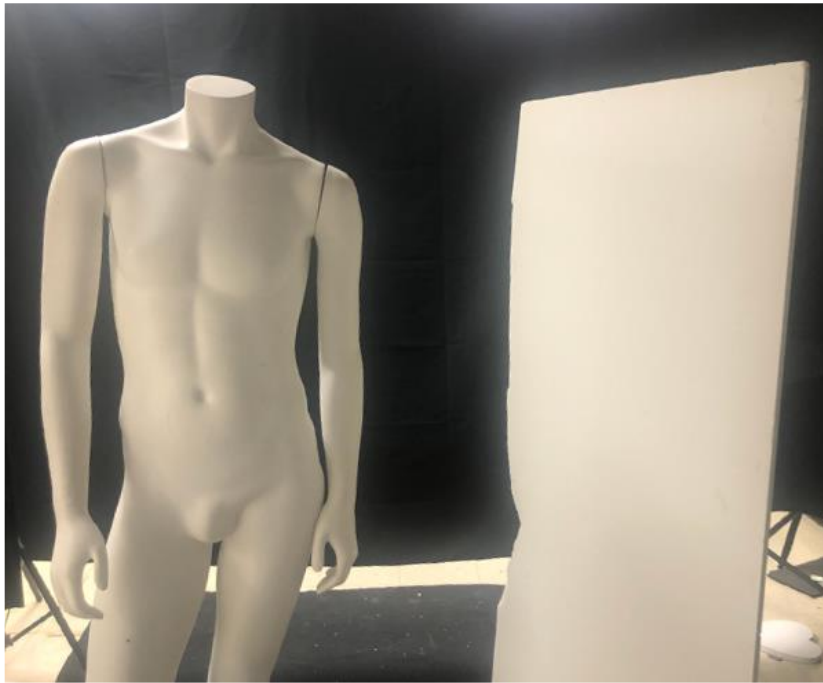
A, B, C



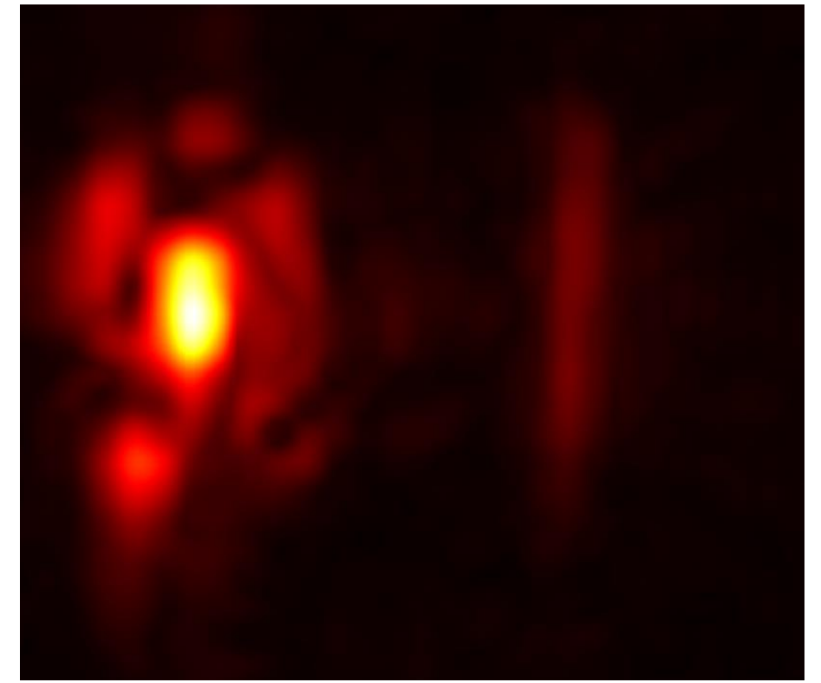
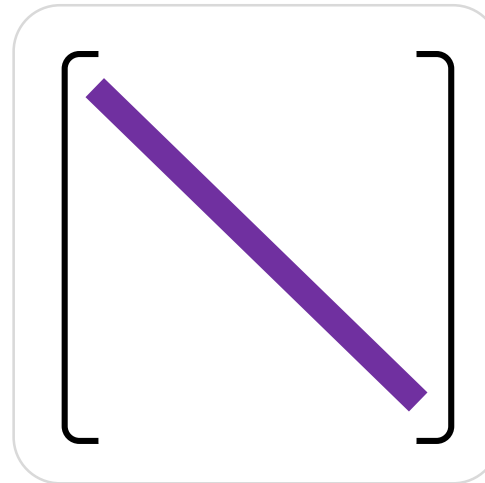
2.0m to 2.3m

Results: Real scenarios

- Horizontal 1D SPAD → Focus light on vertical line

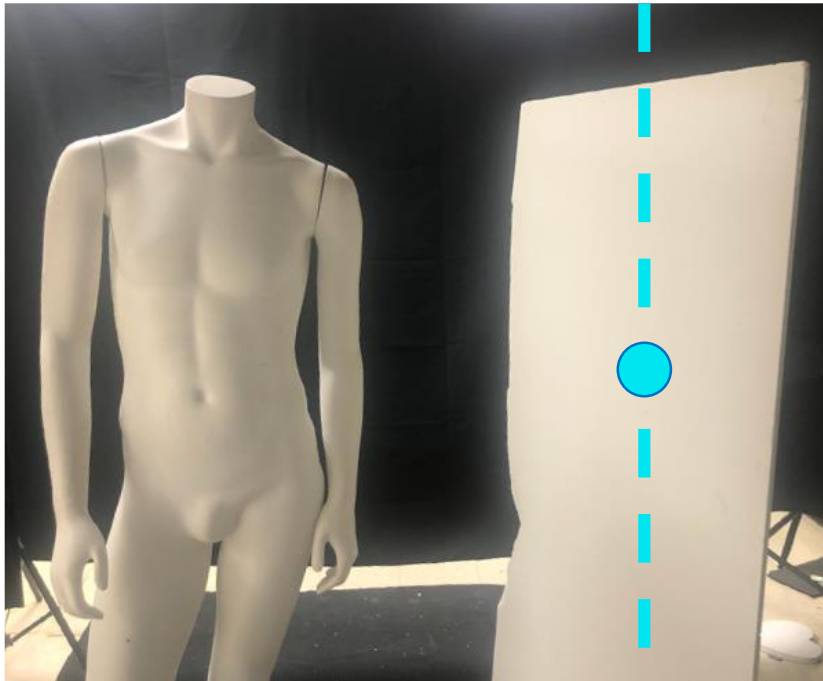


LTM diagonal

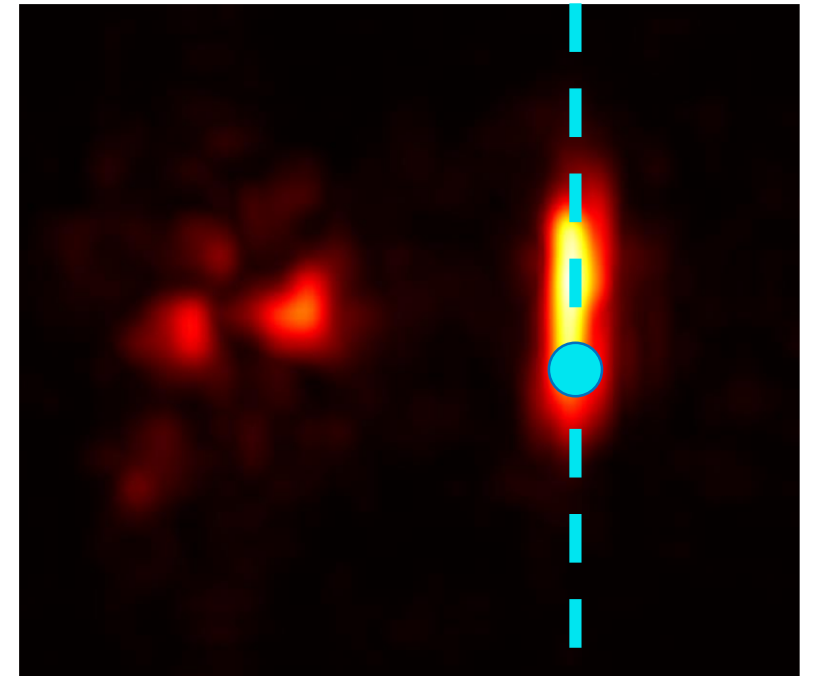
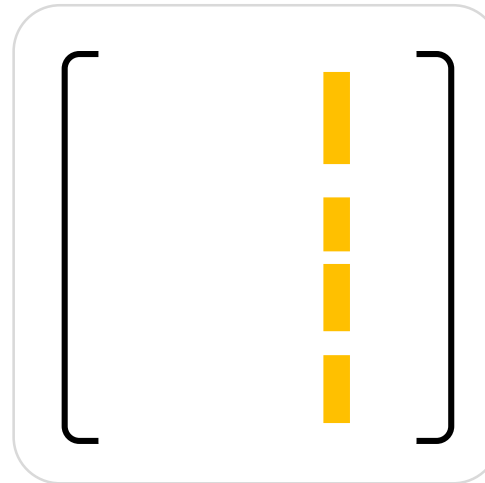


Results: Real scenarios

- Horizontal 1D SPAD → Focus light on vertical line



LTM off-diagonal



Summary

- Coupled LTM with NLOS forward propagation
- Specific imaging functions for virtual LTM
- Mitigate large-aperture issues
- Probing the LTM: direct-indirect, specific path lengths

Future work

- Apply existing LOS techniques for deeper LTM analysis
- Improve separation higher-order bounces
- Applications: 2-corner setups, de-scattering

Virtual light transport matrices for non-line-of-sight imaging

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