Time augmented Petri nets

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Outline

Introduction

- □ Interpreted Petri nets
- Stochastic Petri Nets and CTMC-based analysis
- Bibliography

Introduction

- Formalism: conceptual framework suited for a given purpose
- Life cycle: all phases, from preliminary design, detailed design, implementation, tuning...
- □ Different goals in each phase \rightarrow → different formalisms
- Family of formalisms: PARADIGM

Introduction

Why time augmenting the formalism?

□Autonomous Petri nets

Non-determinism with respect to
 Which enabled transition will fire?
 When will it fire?

□duration of activities and □routing

Not valid for performance evaluation (quantitative analysis: throughput, response time, average marking)



 t_{z}

Introduction

Formalism suitable for system life cycle. Two characteristics:



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Abstract formalism \leftrightarrow Reality

Generic meaning: Place = state variable □ Marking = value of variable Transition = transformation of state Firing = event that produces transformation Particular meanings (annotations): □ Place (and marking) □ State of subsystem S_i \Box Condition C_i is true \Box Resource $\vec{R_k}$ is available Stock of parts in a store... Transition (and firing) Subsystem S, evolves End of activity Aj A customer arrives A fail occurs...

Interpretation

(relation with the environment)

Constraints over the evolution

(imposed by the environment)

Reduction of non-determinism

Synchronization with signals (from the environment)

Time constraints

Typical interpretations:

□ Marking diagrams (and Grafcet)

Timed interpretations (time augmented Petri nets)

Timed interpretations

Specification of activities and servers

- □ sensibilization \rightarrow start of activity □ firing \rightarrow end of activity]
- ≻ delay
- transition \rightarrow service station (# servers)



Specification of resolution of conflicts

race policy (race between timed enabled transitions)
 preselection (random or deterministic choice)



α β 🕇

Immediate transitions

■ Modelling of synchronizations or routing ■ Zero delay ⇒ higher priority in case of conflict $p_{1} \bigoplus \mu$



Reduction of the non-determinism
 Define duration of activities

 (elapsed time from enabling to firing of a transitions)
 Constant → Timed Petri nets (TPN, Ramchandani, 1974)
 Interval → Time Petri nets (TPN, Merlin and Faber, 1976)
 Random (exponentially distrib.) → Stochastic Petri nets (SPN, Symons, 1978; Natkin, 1980; Molloy, 1981)
 Random or immediate → Generalized Stochastic Petri nets (GSPN, Ajmone Marsan, Balbo, Conte, 1984)

Define server semantics (single/multiple/infinite)

Define routing at conflicts
 Race between stochastically timed transitions
 Preselection (probabilistic or deterministic choice)

Interpretation and logic properties
 An interpretation restricts possible behaviour
 Some reachable markings are not reachable anymore
 Analysis of qualitative properties of the autonomous model can be non conclusive



□ In general, a marking does not define a state □ In a SPN:

□ The same reachable makings than autonomous model (support of r.v. = $[0,\infty)$ and race policy gives positive probabilities to all possible outcomes of conflicts)

live?

□ A marking does define a state (memoryless property)

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Stochastic Petri Nets and CTMC-based analysis

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- Time interpretation of Petri nets:
 - Duration of activities: exponentially distributed random variables
 - Single server semantics at each transition
 - □Conflicts resolution: race policy

The reachability graph of the SPN is isomorphic to a Continuous Time Markov Chain



Continuous Time Markov Chain

The CTMC associated with a (bounded) SPN is obtained:

- □ The state space $S = \{s_i\}$ of the CTMC is equal to the reachability set $RS(m_0)$ of the underlying PN $(m_i \leftrightarrow s_i)$
- □ The transition rate from state s_i (corresponding to marking m_i) to state s_j (m_j) is obtained as the sum of the service rates of transitions enabled in m_i whose firing leads to marking m_j .

If transitions have single-server semantics and marking independent rates, the components of Q are:

$$q_{ij} = \begin{cases} \sum w_k, & \text{si } i \neq j \\ T_k \in e_j(m_i) & \\ -q_i, & \text{si } i = j \end{cases}$$

where $q_i = \sum_{T_k \in e(m_i)} W_k$

$$e_j(m_i) = \{T_h \mid T_h \in e(m_i) \land m_i \xrightarrow{T_h} m_j\}$$

T

Let $\pi(m_i,\tau)$ be the probability for the SPN to be at the state m_i at instant τ .

The Kolmogorov differential equation for the associated CTMC is: $\frac{d\pi(m_i,\tau)}{d\tau} = \sum_{\substack{T_k \in T}} q_{kj}\pi(m_k,\tau)$ in matrix form: $\frac{d\pi(\tau)}{d\tau} = \pi(\tau)Q$

and its solution can be expressed as: $\pi(\tau) = \pi(0)e^{Q\tau}$

where $\pi(0)$ is the initial probability distribution

(usually $\pi_i(0) = 1$ if $m_i = m_0$ and $\pi_i(0) = 0$ otherwise)

The steady-state "solution" of an SPN is based on the study of the probability distribution of the set of reachable markings

$$\pi = (\pi_1, \dots, \pi_{|RS|})$$

The limit behaviour of that distribution

$$\pi = \lim_{\tau \to \infty} \pi(\tau)$$

is computed by solving the following system of linear equations

$$\begin{bmatrix} \pi Q = \mathbf{0} \\ \pi \mathbf{1}^{\mathrm{T}} = 1 \end{bmatrix}$$

where 0 and 1 $^{\rm T}$ are vectors of the size of π with all the components equal to 0 and 1 respectively

- $\hfill The steady-state distribution <math display="inline">\pi$ is used for the computation of performance indices of interest
- Performance indices can be expressed from reward functions defined over the markings of the SPN, the average reward is computed as average value of the reward of the steady-state distribution

$$R = \sum_{m_i \in RS(m_0)} r(m_i) \pi_i$$

where r(m) represents a given reward function

To compute the probability of a given condition $\Gamma(m)$ in the SPN

First, we define the reward function:

 $r(m) = \begin{cases} 1, & \text{if } \Gamma(m) = true \\ 0, & \text{otherwise} \end{cases}$

Then, the desired probability is computed as:

$$P\{\Gamma\} = \sum_{\substack{m_i \in RS(m_0) \\ m_i \in A}} r(m_i)\pi_i = \sum_{\substack{m_i \in A \\ m_i \in A}} \pi_i$$
where

$$A = \{m_i \in RS(m_0) \mid \Gamma(m_i) = true\}$$

Example: mean number of tokens at place p_j The reward function is

$$r(m) = n$$
 if and only if $m(p_i) = n$

Then the average marking of place:

$$\mu(p_j) = \sum_{m_i \in RS(m_0)} r(m_i)\pi_i = \sum_{n > 0} P\{A(j,n) \\ n > 0$$

where $A(j,n) = \{m_i \in RS(m_0) : m_i(p_j) = n\}$ and the sum is constrained to $n \le k$ if place is k-bounded

Other example: throughput of transition T_j (average number of firings per time unit)
 A transition can fire only if it is enabled, thus the reward function is

$$r(m) = \begin{cases} w_j, & \text{si } T_j \in e(m) \\ 0, & \text{en otro caso} \end{cases}$$

 \Box Then the throughput of T_i is

$$\chi_j = \sum_{\substack{m_i \in RS(m_0)}} r(m_i)\pi_i = \sum_{\substack{m_i \in A_j}} w_j\pi_i$$

where $A_j = \{m_i \in RS(m_0) : T_j \in e(m_i)\}$

Shared memory multiprocessor



Both processors behave in a similar way: A cyclic sequence of: local activity, then an access request to the shared memory, and then accessing the shared memory

All transitions have exponentially distributed durations, except for t2 and t5, access request to the shared memory (immediate)
→ GSPN

рS

Т3

D8

T6

D2

Reachability graph



It is not isomorphic to a Continuous Time Markov Chain (infinite rates are not allowed in CTMCs)

Tangible reachability graph



It is isomorphic to a Continuous Time Markov Chain

Infinitesimal generator matrix of the CTMC



The stationary distribution can be computed (steady state probability of each state)

$$(m{\pi}_1,m{\pi}_2,m{\pi}_3,m{\pi}_4,m{\pi}_5)\cdot egin{bmatrix} -(\lambda_1+\lambda_4) & \lambda_1 & \lambda_4 & 0 & 0\ \lambda_3 & -(\lambda_3+\lambda_4) & 0 & \lambda_4 & 0\ \lambda_6 & 0 & -(\lambda_1+\lambda_6) & 0 & \lambda_1\ 0 & 0 & \lambda_3 & -\lambda_3 & 0\ 0 & \lambda_6 & 0 & 0 & -\lambda_6 \end{bmatrix} = m{0}$$

 $\pi_1 + \pi_2 + \pi_3 + \pi_4 + \pi_5 = 1$

And from here, compute, for instance, utilization rate of shared memory

 \Box In this case, it is equal to 1 minus the steady-state probability of the unique state with p_2 (shared memory is free) marked

$$[-\mu[p_2] = 1 - \pi_1$$

Other example, *processing power*

Average number of processors effectively (locally) working

We define the reward function

 $r_P(m) = m[p_3] + m[p_6]$

Then:

$$P = \sum_{\substack{m_i \in RS(m_0)}} r_P(m_i) \pi_i = 2\pi_1 + \pi_2 + \pi_3$$

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