# Multi-agent systems applied in manufacturing

Marius Şutu, ph.d. student, "Gh. Asachi" Technical University of Iaşi Department of Automatic Control and Applied Informatics Bd. D. Mangeron 53A, Iaşi, Romania Email: msutu@ac.tuiasi.ro

#### **CONTENTS**

**GISED** Seminary

**Multi-agent systems in industry** Holonic manufacturing systems **The starting point: PROSA Extending PROSA** □Holons and services Resource holon implementation **Communication** middleware Preliminary conclusions **Future work** 

Multi-agent systems applied in manufacturing

An approach in the intelligent factory direction could consist in interconnecting two major research fields:
 Computer integrated manufacturing (CIM)
 Multi-agent systems (MAS)

A multi-agent system implementation involves two different intelligent behavior sources:

The agent internal reasoning mechanism
Interaction between the designed agents



Multi-agent systems applied in manufacturing

Using industrial robots in CIM environments leads to flexible manufacturing systems

Flexibility creates the context for task splitting and sharing:

Machine flexibility – easier adaptation to new product types

Routing flexibility – the possibility of using different machines for the same operation

Multi-agent systems applied in manufacturing

Manufacturing a wide range of products leads to the following operations: □Part processing Image: Manipulation **Palletization Each product requires an initially** specified sequence involving one or more of the above operations

**GISED Seminary** 

Multi-agent systems applied in manufacturing

December 10, 2009

5



Figure 1. A flexible manufacturing system

**GISED Seminary** 

Multi-agent systems applied in manufacturing



Figure 2. ABB IRB 2400 Robot

GISED Seminary

Multi-agent systems applied in manufacturing



Figure 3. ABB IRB 1400 Robot

Multi-agent systems applied in manufacturing

December 10, 2009

8

**GISED Seminary** 

FMS are linked with MAS considering:

Each robot being coupled with a software agent

Product operation sequences are dynamically determined by the agents – distributed planning mechanism

Robot interaction in the manufacturing process relies on agent coordination and negotiation

**GISED Seminary** 

Multi-agent systems applied in manufacturing

Multi-agent systems: **Dynamic systems** □ Shared environment Planning mechanism Centralised Distributed Coordination protocols **Cooperative Competitive Communication** layer **Peer-to-**peer **Broadcast** 

**GISED Seminary** 

Multi-agent systems applied in manufacturing

#### **Contract NET**





12

#### **HOLONIC SYSTEMS**

**GISED** Seminary

Model – biological systems
 Organizational structures
 Whole – Part paradigm
 Recursivity

Factory
Collection of specialized sub-systems
Autonomous character
Cooperativity

Multi-agent systems applied in manufacturing

#### **HOLONIC SYSTEMS**

□New concept: Holon ≠ Agent
□Agent - part of a holon

 Holon - composite entity:
 Software Agent
 Communication Middleware Interface
 Structural component
 Physical device
 Holarchy, by concatenation

Multi-agent systems applied in manufacturing

**GISED** Seminary

#### **HOLONIC SYSTEMS**

**Recursive structure Double holon role: Whole Semi-heterarchical** organization **UThe aggregation** phenomena



**GISED** Seminary

Multi-agent systems applied in manufacturing

#### **THE STARTING POINT: PROSA**



#### **THE STARTING POINT: PROSA**

**Holon types Product** Permanent **Specific** functionality Physical devices Specialized software

Multi-agent systems applied in manufacturing

GISED Seminary

#### **THE STARTING POINT: PROSA**

Coordination protocol **Plan propagation Ifrom Order agent to Resource agents Event propagation UFrom Resource agents to Order** agent

Multi-agent systems applied in manufacturing

#### **EXTENDING PROSA**

Coordination protocol **Contract** Net **Open auction** mechanism **Recursive context Temporary** bids support **Global** goal **Auto-organization** 

Multi-agent systems applied in manufacturing

**GISED Seminary** 

#### **HOLONS AND SERVICES**



#### **HOLONS AND SERVICES**

#### 

Loose coupling
Robust communication mechanism

#### **Dynamic service composition**

A service call made by an upper level agent might require several service calls on a lower level
 Auto-organization



Multi-agent systems applied in manufacturing



#### **RESOURCE HOLON IMPLEMENTATION**

Functional components
 Execution device
 Driver application
 Communication middleware
 Software Agent



#### **RESOURCE HOLON IMPLEMENTATION**

**Driver** application **Connected to a physical device Exporting its functionality High specificity Communication** middleware **CORBA** compatible **Unifying communication** channels for distributed and heterogeneous systems

**GISED** Seminary

Multi-agent systems applied in manufacturing

#### **COMMUNICATION MIDDLEWARE**

**CORBA - Common Object Request Broker Architecture Communication** layer **Language specific interfaces** Standardized by the Object management group (omg.org) Mechanism for remote procedure call Servant applications **Object references** Remote method invocations **Client applications Support** layer for SOA

Multi-agent systems applied in manufacturing

#### **COMMUNICATION MIDDLEWARE**

**CORBA** Services □Name service – a CORBA dns □Trader service – open auction system **Event** service **Event channels Event producers/consumers Object Request Broker (ORB)** Platform independent - Mico **Platform dependent Java RMI IIOP.NET** 

Multi-agent systems applied in manufacturing

#### **PRELIMINARY CONCLUSIONS**

The holonic system advantages
 Increased adaptability
 Goal driven auto-organization
 Minimum fault impact

Holon implementation advantages
 Modular architecture
 Plug & Play functionality
 Quick integration of legacy devices



Multi-agent systems applied in manufacturing

### **PRELIMINARY CONCLUSIONS**

Middleware benefits
 Distributed event handling
 Knowledge separation
 Communication transparency

SOA benefits
 Decoupled agent system
 Increased robustness



Multi-agent systems applied in manufacturing

#### **FUTURE WORK**

Communication middleware support for higher level holons
 Dynamic service composition with CORBA
 Implementing the auto-

organization mechanism

# □Validating the resulting holonic system architecture

GISED Seminary

Multi-agent systems applied in manufacturing

December 10, 2009

29

#### **FUTURE WORK**

□Investigating the usage of Petri-Nets in validating holonic/agent based systems

 Global action spaces
 Narrowing action chains corresponding to goal solving plans
 Defining workflows
 Analyzing performances and obtaining a benchmark mechanism

Multi-agent systems applied in manufacturing

**GISED** Seminary

## Thank you for your attention!